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QUARTERLY REPORT

TRENDS AND TECHNIQUES FOR
SPACE BASE ELECTRONICS

Prepared by:

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SPACE BASE ELECTRONICS

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for

NASA Contract NAS8-26749

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1. DOUBLE-LEVEL METALLIZATION TECHNIQUES

Most of the work during the first quarter was directed toward the development of a sputtering system for preparing aluminum and aluminum-alloy films. A photograph of the completed system is shown in Figure 1.1. Briefly, the system consists of the following.

The basic vacuum system is a Varian-NRC 6 inch oil diffusion and mechanical roughing pump equipped for automatic and manual operation. The diffusion pump is equipped for LN₂ cooling of the cold trap. The sputter gun and power supply were obtained from Sloan Technology. The sputtering chamber was designed and built at Mississippi State. It consists of a Corning 12X18 glass cylinder and an aluminum top plate machined to accomodate up to three sputter guns. A cold cathode discharge gauge was constructed and installed in the baseplate of the chamber to measure the pressure during the sputtering operation. A throttle valve with several threaded holes for accomodating plugs is operated by one of two mechanical feedthroughs in the baseplate. A lift mechanism with a reversible motor was designed and constructed for raising the top plate and sputter guns.

Inside the chamber is equipped with a rotating table which accomodates up to eight wafers of 1½" in diameter. The table is driven by a vacuum sealed shaded pole motor through a magnetic coupling at 7 rpm. The entire motor-table assembly is rotated by a chain-sprocket-mechanical feedthrough arrangement through three sputter-gun and two mask positions. The mask is attached to the rotating assembly and provides one hole through which the sputter-gun deposits metal on the wafers. A crystal film thickness sensor is located beneath the sputter-gun and receives a deposit through a hole at an unused wafer position on the table.

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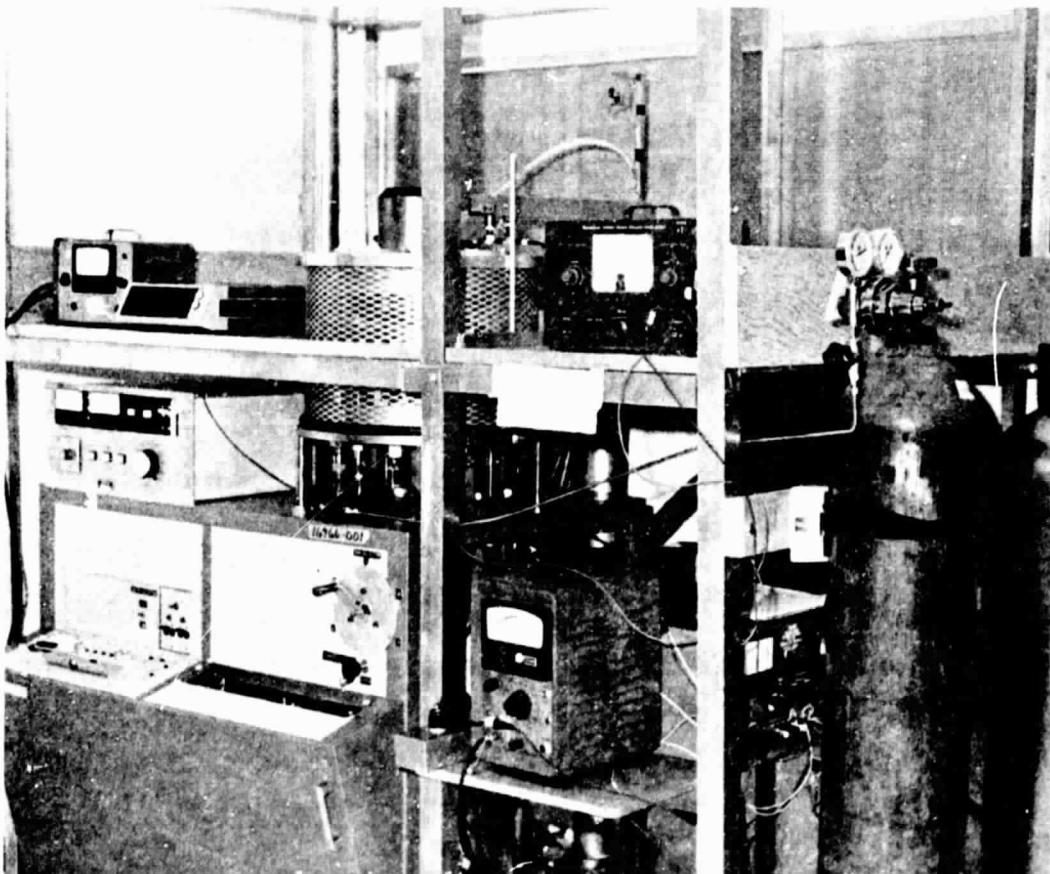


Figure 1.1 Photograph of metallization system using sputter-gun source.

The sputtering chamber opens into a class 100 clean bench in order to maintain a high level of cleanliness. The system is located in the metallizing and bonding room of the microelectronics laboratories in Simrall Engineering Building, and this room was designed with air conditioning and filtering units to maintain a class 30,000 environment. The entire system has been constructed and checked out and is ready for depositing sputtered films.

The installation of a six-tube Thermco Ranger diffusion furnace was completed with the addition of a venting system for exhausting the scavenger boxes. All that remains to be done is to line the tube and connect the nitrogen ambient source in order to anneal the aluminum films.

2. TWO-DIMENSIONAL MODELS FOR MOS TRANSISTORS

The work done during the first quarter was directed toward preliminary investigations of numerical schemes and computational algorithms for solving the semiconductor equations for a two-dimensional field.

A recent report has described the application of the finite-element method to the analysis of a JFET.¹ The finite-element method has been used for some time in solving problems in mechanics and elasticity; however, it has only recently been applied to semiconductor problems. This method has the power to treat some problems, such as eigen-value problems, for which the finite-difference method is awkward if at all applicable. It can also be applied to the solution of field distributions governed by partial differential equations, and one of the most attractive features as compared to the finite-element method is purported to be the ease of treating non-rectangular geometries and irregular boundaries. For example, the geometry of the VMOS structure could be accommodated. It was decided to further investigate this technique.

In order to better understand the applicability of the method, it was applied to a one-dimensional linear diffusion problem. This simple problem is one for which familiar results are available for comparison and at the same time taxes the finite-element method. In its most valid form, the finite element method is applicable to variational problems in which a true minimum of an energy-related function exists. Such a minimum does not apply for the semiconductor problem in which current flow occurs by diffusive and conductive mechanisms. It has been proposed that a "weak form", the so-called Galerkin method, be applied to such problems.² The typical semiconductor problem is a non-linear boundary value and initial condition problem of which the linear diffusion problem is a very special case. In the example chosen, the diffusion variable, u , obeys:

$$u(x,t)|_{x=0} = u_s = 1 \quad (a) \quad (2.1)$$

$$u_x(x,t)|_{x=a} = 0 \quad (b)$$

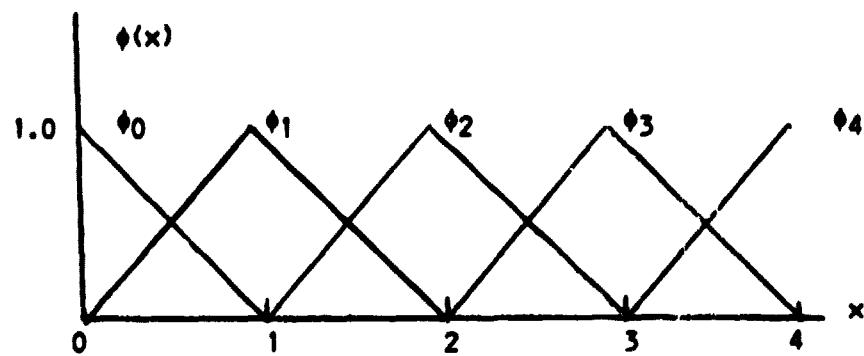
$$u(x,t)|_{t=0} = 1, x=0 \quad (c)$$

$$u_t - u_{xx} = f(x,t) = 0 \quad 0 \leq x \leq a \quad (2.2)$$

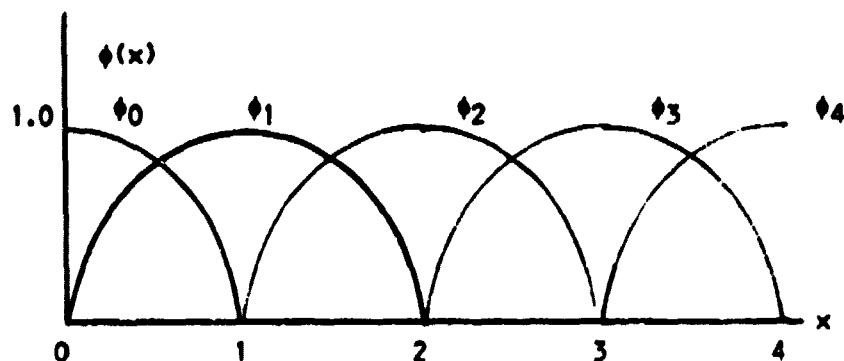
The Galerkin formulation of this problem is:

$$\int_0^a (u_t v - u_{xx} v_x - fv) dx = 0, \quad (2.3)$$

where $v(x,t)$ represents a "trial function" which is used to approximate $u(x,t)$. The finite element methods uses a set of "hill functions" as illustrated in Figure 2.1 to construct the $v(x,t)$ approximation. Two of the popular hill functions are the Hermite bicubic and the bilinear functions which are illustrated in the figure and were used in the example. The final form of the approximate solution is;



(a) Bilinear hill functions



(b) Bicubic (Hermite) hill functions

Figure 2.1 Illustration of hill functions used in finite element method.

$$v(x,t) = \sum_{i=1}^N q_i(t) \phi_i(x). \quad (2.4)$$

On the node points the solution is approximated by the set $\{q_i(t)\}$ for the type of hill functions which overlap as illustrated in Figure 2.1. Solution for the set $\{q_i(t)\}$ is then analogous to solving for the set $\{u_i(t)\}$ on the node points using the finite difference technique. The equations for the set $\{q_i(t)\}$ are obtained by substituting (2.4) into (2.3).

$$\sum_{i=1}^N \int_0^a \left(\frac{\partial q_i}{\partial t} \phi_i \phi_j + q_i \frac{\partial \phi_i \phi_j}{\partial x \partial x} + f \phi_j \right) dx = 0 \\ j = 1, 2, 3, \dots, N \quad (2.5)$$

From (2.5) a set of time differential equations is obtained which is solved using an implicit numerical method.

The solution of the problem posed by the example is closely approximated by the erfc function in the range $0 \leq x \leq 3$ if $a = 6$, and this solution was used to compare the accuracy of the finite element and finite difference methods. Figures 2.2-2.4 show the maximum error as a function of the reciprocal of the number of grid points and the size of the time step, i.e. $\lambda^2 = \Delta t / \Delta x^2$.

The error obtained in the solution by the bilinear finite element method is very nearly the same as that obtained with the finite difference method. This was not surprising because the system of equations for $\{q_i(t)\}$ and $\{u_i(t)\}$ were quite similar. What was surprising was that the Hermite bicubic finite element produced such poor results, although this surprise was based upon the intuition that since this element was more difficult to use it should provide some reward for the difficulty.

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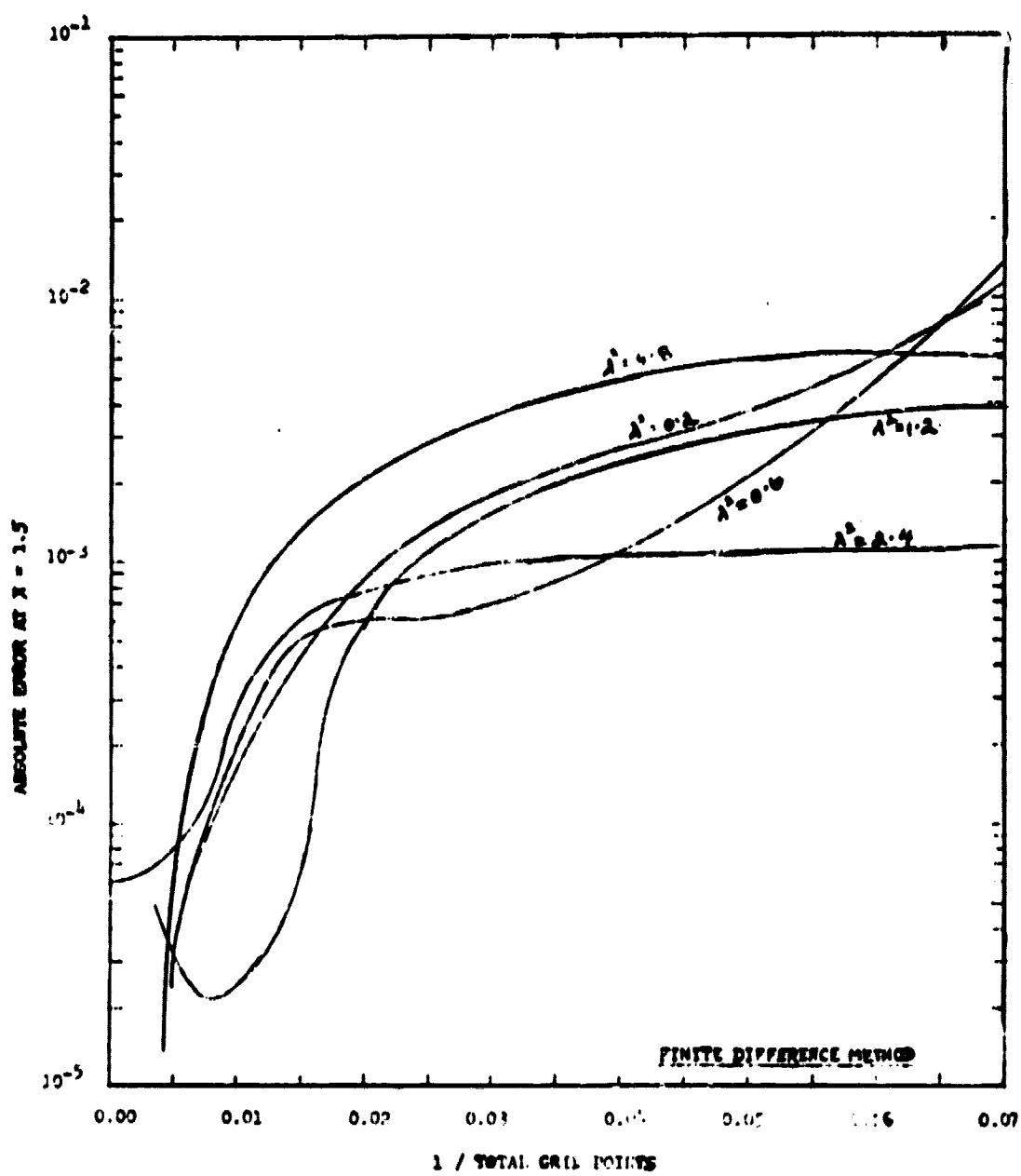


Figure 2.2 Error for finite-difference vs. reciprocal of total number of grid points,

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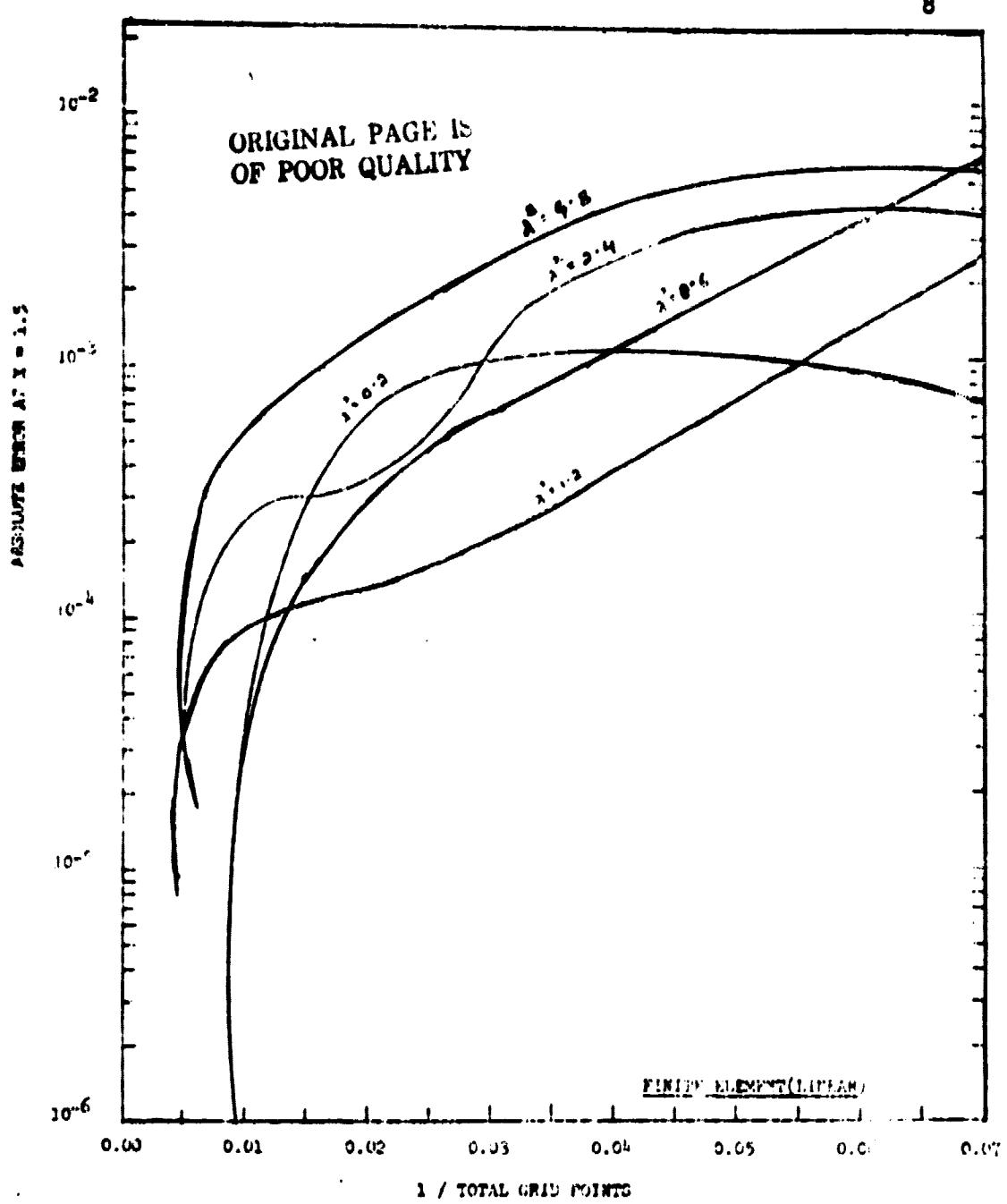


Figure 2.3 Error for finite-bilinear element vs. reciprocal of total number of grid points.

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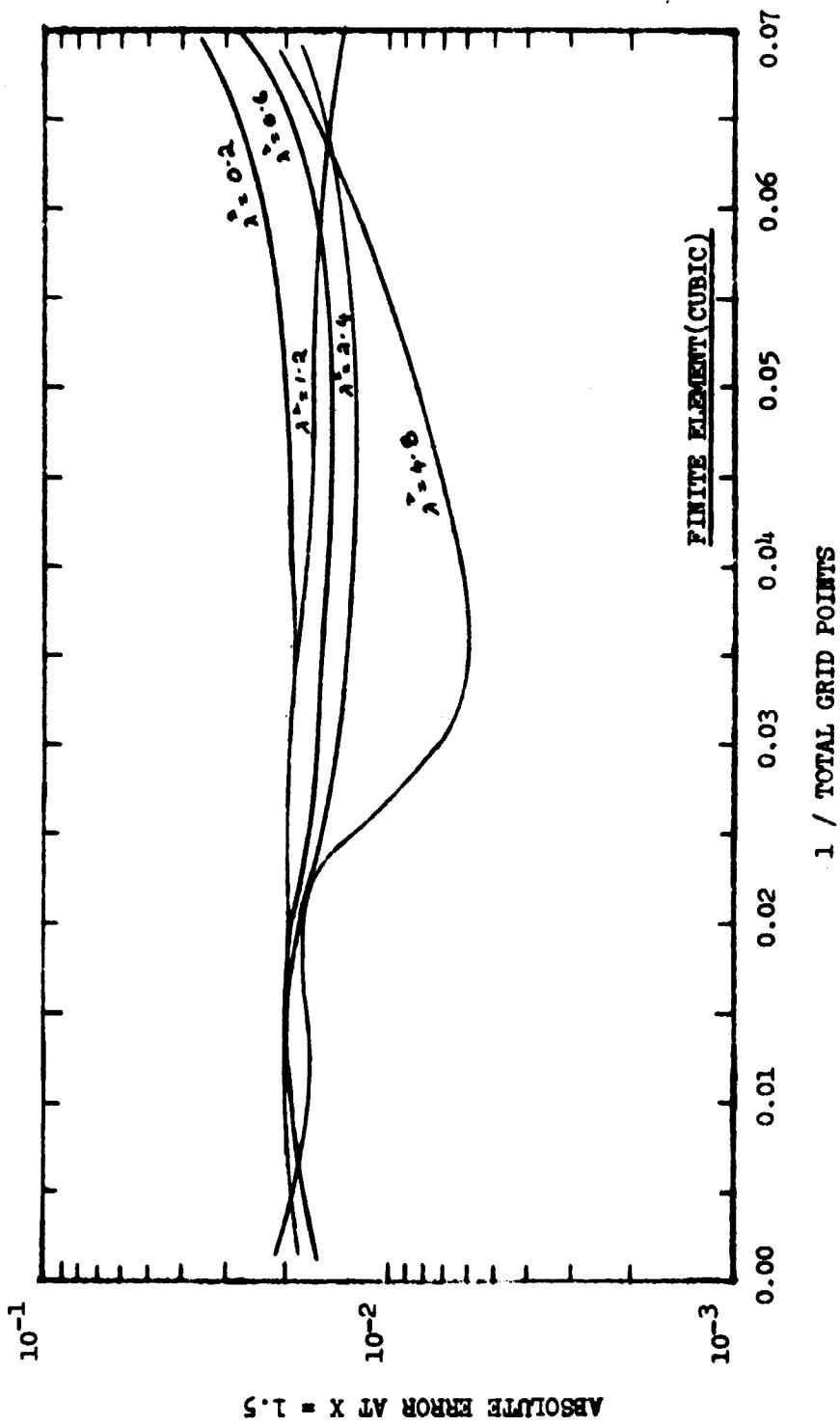


Figure 2.4 Error for finite-bicubic-element vs. reciprocal of total number of grid points.

This experience resulted in some skepticism that the finite element method would be effective for semiconductor problems. A more recent paper has reinforced this attitude.³ This paper indicates that the proper formulations of the semiconductor problem for the finite element approach remain to be demonstrated, and, in agreement with our observations, point out that the application of Galerkin's method is subject to skepticism. Therefore, it was concluded that the further work should be based upon the finite-difference method which we have used before although the finite-element method is intriguing and may be further developed in the future.

The second phase of this program is underway to develop a computational program with which to generate data from a model. During the past quarter, the major emphasis was upon deriving a simple two-dimensional algorithm which could be economically used in a simulation program during its development. It is plausible that this algorithm can be later modified to become adequate for modeling of other effects which are significant in certain situations, e.g., short channel effects, avalanche breakdown, etc.

During the past quarter an algorithm has been developed based upon the usual assumption that the mobile carriers are included in an infinitesimally thick layer of charge at the Si-SiO₂ interface. The current flow is then described by a one-dimensional equation:

$$i = \frac{kT}{q} \mu_N \left(\frac{\partial \mu_L S}{\partial X} + \frac{q \mu_L E_S S}{kT} \right), \quad 0 \leq x \leq a \quad (2.6)$$

where i and S are channel current and charge per unit channel width, E_S is the tangential interface field and μ_N and μ_L are the mobility factors accounting respectively for gate modulation and hot electron effects. This equation is solved iteratively with Poisson's equation which includes two-

dimensional effects:

$$\nabla^2 \psi = -\rho/\epsilon. \quad (2.7)$$

Equation (2.7) will be solved for one segment of a periodic structure with respect to x and equation (2.6) will be integrated to produce auxiliary equations for the boundary conditions at the Si-SiO₂ interface. It will be assumed initially that $S = 0$ at $x = a$, the point at which the normal component of the interface field changes sign. The solution algorithm then proceeds in an iterative fashion to solve (2.6) and (2.7) simultaneously for the potential distribution from which the current, i , is ultimately calculated as a function of the gate, drain and body voltage.

The model at this point admittedly has some short-comings, mainly due to the neglection of generation-recombination mechanisms. Therefore, it will not treat impact avalanche and bulk generated leakage currents. It is believed at this time that such effects can be treated by adding another iterative loop to the algorithm. The major emphasis at this point will be the development of a program for input and output data management and including subroutines which generate data internally within the program and solve systems of equations which will be encountered in implementing the algorithm.

3. REDISTRIBUTION DIFFUSIONS FOR ION-IMPLANTED PREDEPOSITS OF BORON AND PHOSPHORUS IN SOS FILMS.

The objective of this work was to produce curves describing the variation with diffusion time and temperature of the junction depth, sheet resistance and integrated impurity dose. This data has been generated for boron and phosphorus redistributed in nitrogen, dry oxygen and steam ambients for $\langle 111 \rangle$ oriented SOS films. The following section presents discussions of the implantation and redistribution model, further program develop, the computational procedure and of the computed results.

3.1 The Redistribution Model:

There are three aspects of the redistribution model which are considered:

(a) the implanted profile, (b) the oxidation model, and (c) the diffusivity model.

(a) The implanted profile.

The implanted profile is described by the gaussian function,

$$C(y) = C_{\max} \exp \left\{ -\frac{1}{2} \left(\frac{y - R_p}{\Delta R_p} \right)^2 \right\}, \quad (3.1)$$

where C is the concentration, y is the distance from the entrant silicon surface, R_p is the range and ΔR_p is the straggle for the implant. The peak concentration, C_{\max} , is related to the implant dose, Q_{imp} by:

$$C_{\max} = Q_{\text{imp}} / \sqrt{2\pi} \Delta R_p. \quad (3.2)$$

Redistribution data has been generated for the following conditions:⁴

Q_{imp} : $5 \times 10^{12}, 10^{13}, 5 \times 10^{13}, 10^{14} \text{ cm}^{-2}$

R_p : $0.2735 \mu\text{m}$ 80 keV boron implant.
 $0.1727 "$ 150 keV phosphorus.

ΔR_p : $0.0665 \mu\text{m}$ 80 keV boron implant.
 $0.0440 "$ 150 keV phosphorus.

The doses are light to moderate resulting in concentrations no heavier than $6 \times 10^{18} \text{ cm}^{-3}$, and the range-straggle values are typical of those employed at MSFC. It is assumed that all of the ions become activated shortly after redistribution begins and thereby diffuse by a substitutional mechanism involving vacancies.

(b) Oxidation model:

The oxidation model is assumed to be the same as for bulk silicon and the data of Deal et. al.⁵ has been used to calculate the oxidation rate according to:

$$\frac{dx_o}{dt} = B / (2x_o + B/C), \quad (3.3)$$

where B and C follow Boltzmann-like temperature dependences. Figures (3.1) and (3.2) illustrate the oxide thickness dependence upon time and temperature for both dry O_2 and steam ambients.

During the oxidation, the silicon film thickness is reduced according to:

$$W = W_o - \alpha x_o, \quad (3.4)$$

where W_o is the initial film thickness, taken to be 1 μm , and $\alpha = 0.45$ is the ratio of the densities of SiO_2 to silicon. Redistribution data is given for $W_o = 1 \mu\text{m}$ and an initial oxide thickness of $x_o = 300 \text{ \AA}$.

(c) Diffusivity model:

The diffusivity model for boron was discussed in an earlier report⁶ and it includes a linear dependence of the diffusivity upon the vacancy concentration as well as the field-enhancement effect. The diffusivity model for phosphorus includes only the field-enhancement effect which is sufficient to describe the non-linear behavior of phosphorus diffusions at concentrations lower than 10^{19} cm^{-3} as shown by Barry⁷ and Fair and Tsai⁸. The diffusivity-

temperature dependence is after Fair⁹ and Fair and Tsai⁸ adaptation of data by Ghostagore¹⁰. For either boron or phosphorous the effective diffusivity is given by:

$$D_{\text{eff}} = D(u) \times (1 + u / \sqrt{u^2 + 1}) , \quad (3.4)$$

where,

$$u = C / 2 n_i , \quad (3.5)$$

and,

$$\begin{aligned} D(u) &= D_B^* u, \quad \text{for boron,} \\ &= D_P^* , \quad \text{for phosphorus.} \end{aligned} \quad (3.6)$$

and where n_i is the intrinsic carrier concentration at the diffusion temperature and D_B^* and D_P^* are the intrinsic diffusivities of boron and phosphorus:

$$D_B^* = 3.17 \exp (-3.59 \text{eV} / k_B T) \text{ cm}^2/\text{sec.} ,$$

$$D_P^* = 3.85 \exp (-3.66 \text{eV} / k_B T) \quad (3.7)$$

3.2 Further Program Development:

The program which was used to generate the data has been described in detail in an earlier report. It was noted that the program was developed in such a way that one could take advantage of a normalization procedure for predeposition diffusions and generate data applicable to different film thicknesses. However, it is not possible to gain such an advantage for redistribution diffusions involving ion-implants or growth of an oxide. Then the program was used to generate data, it was discovered that some other features of the program are extraneous unless further refined.

The program was developed to account for both thin and thick oxides such as would be encountered in some practical situations. However, such a simulation requires the incorporation of a warped grid system, a modification which would require considerably more effort. Therefore, the variable oxide feature

is of limited value at this time, since the program, at best, only approximates the conditions for growth of a very thin oxide during redistribution.

A modification was made which allows accurate treatment of redistribution under oxidizing conditions when only a single oxide thickness is involved. The original program treated the oxidation process with regard to the boundary conditions; however, unlike the case of bulk silicon, one must also account for the reduction of the silicon film thickness. This feature is now included in the program. During the simulation of a redistribution in an oxidizing ambient, the vertical grid spacing continuously shrinks while the horizontal grid spacing is constant. The modification does not show up on logic flow diagrams at the level of detail which has previously been given. For completeness, a new listing of the affected main and sub-programs is given in the appendix.

3.3 Computational Procedure:

The program described in an earlier report, and modified as described in the preceding, was used to generate the data. Two-dimensional data was obtained in the form of isoconcentration contours for typical situations. The bulk of the data which can be correlated with experimental measurements is generated using a quasi-one-dimensional model in a manner described in a previous report.⁶ A brief review of the procedure is given in the following.

For generation of sheet resistance, junction depth and integrated impurity dose data as a function of time and temperature, only a one-dimensional profile need be calculated. This is accomplished by making the horizontal grid only three units wide but keeping the field six film thicknesses wide. Periodic boundary conditions for the horizontal dimensions are employed in the program and result in a calculation which produces the vertical profile

equivalent to a none-dimensional model. Thus without sacrificing the generality of the program for treating two-dimensional cases, the amount of computing time is drastically reduced when the data that is desired does not require the full power of the program.

The vertical grid varies from thirty one to sixty one points as required for accuracy in details of the profile, and most of the data is not sensitive to the number of grid points used if the number is chosen in this range. For the purpose of illustrating the unusual nature of phosphorous profiles, the larger number of points was required.

3.4 Discussion of Results:

First, some of the unusual behavior of redistribution diffusions in SOS films will be discussed in this section. Next, the format for the calculated curves will be discussed, and, finally, the bulk of the generated data is given in the appendix without further comment.

Figures (3.1) and (3.2) illustrate the oxide thickness growth and silicon film thickness reduction as functions of time for <111> silicon films oxidized in steam and dry O_2 ambients. The evolution traced beginning with an initial oxide of 300 Å thickness on an SOS film of 1 µm initial thickness. The curves are shown for four temperatures. The data are necessary for interpreting some of the results for simulated redistributions.

Figures (3.3) and (3.4) show impurity profiles for boron and phosphorus implants being redistributed in a steam ambient at 1000 deg. C. The profiles are all plotted with a common origin as would be the case for experimentally derived profiles where the Si-SiO₂ interface would serve as the logical origin. However, the profiles are normalized with respect to the film thickness which

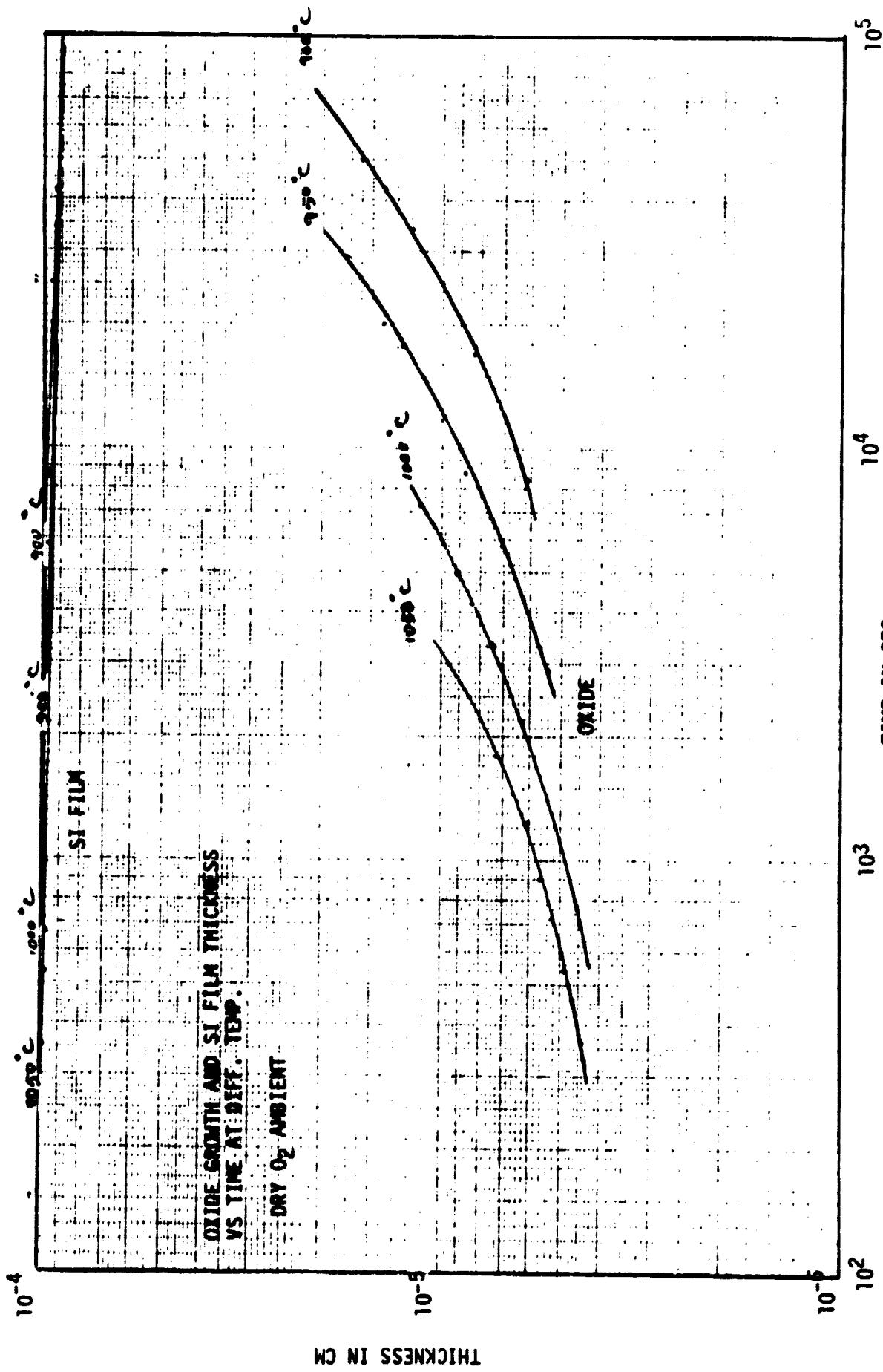


Figure 3.1

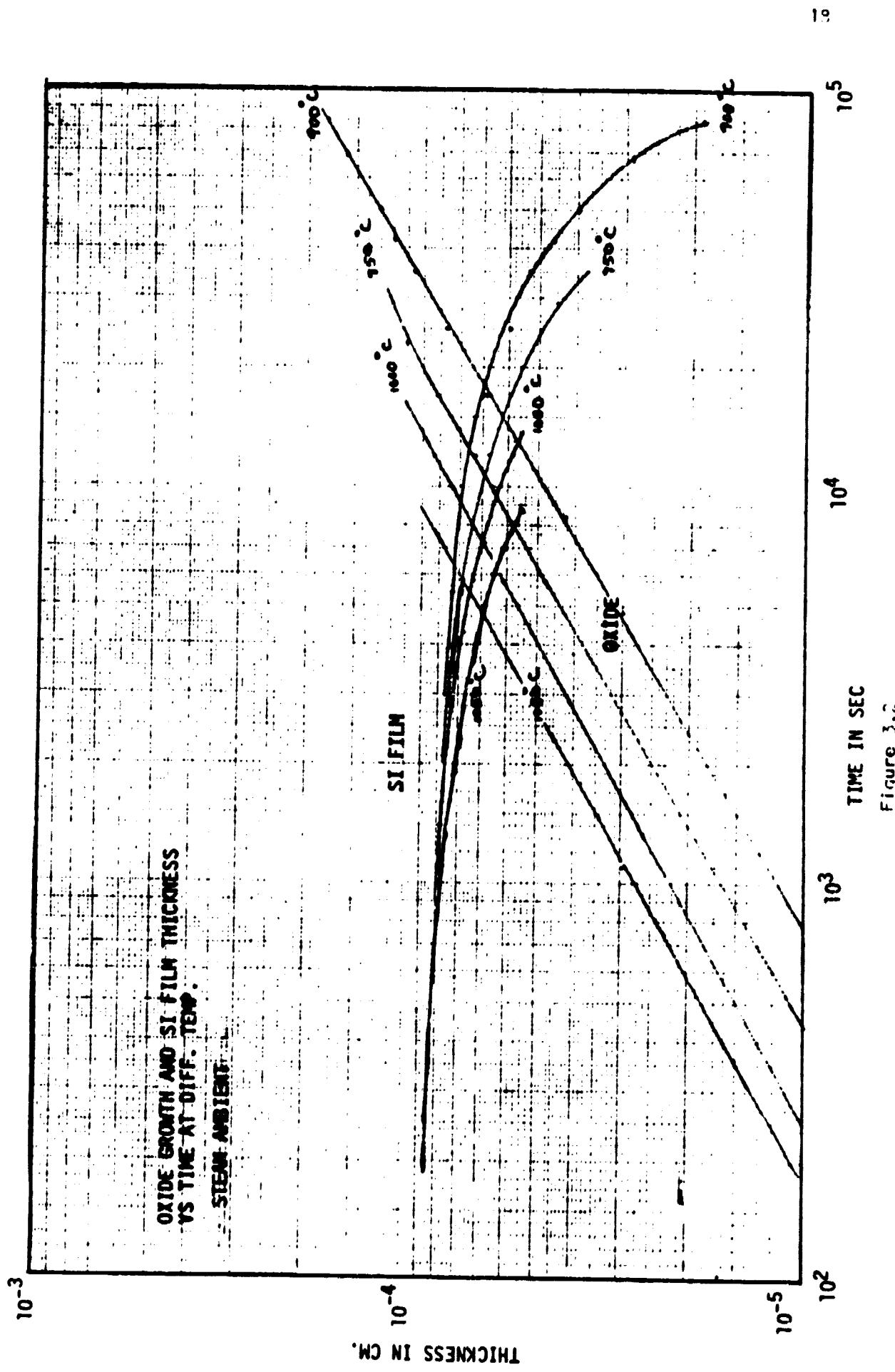
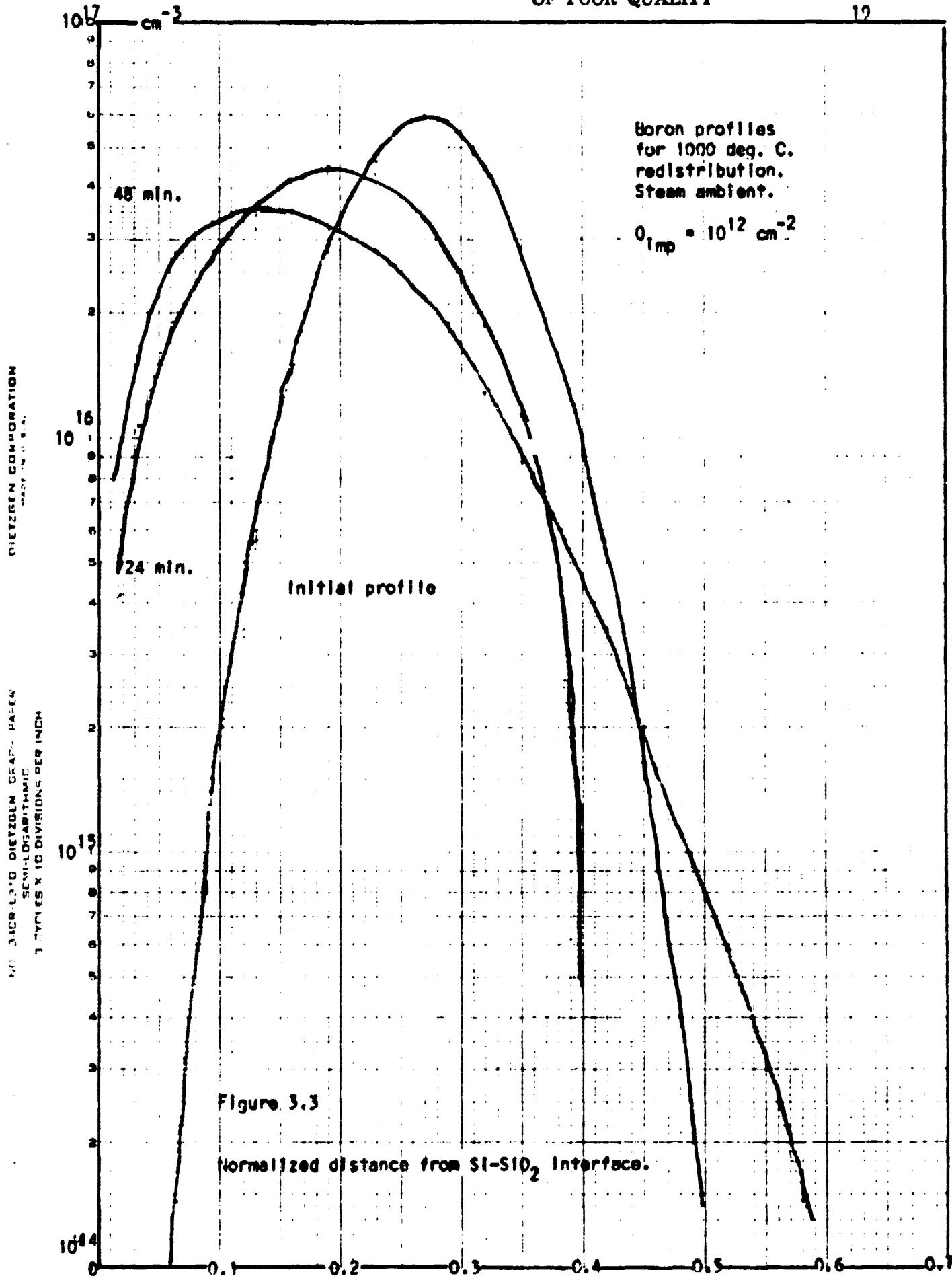
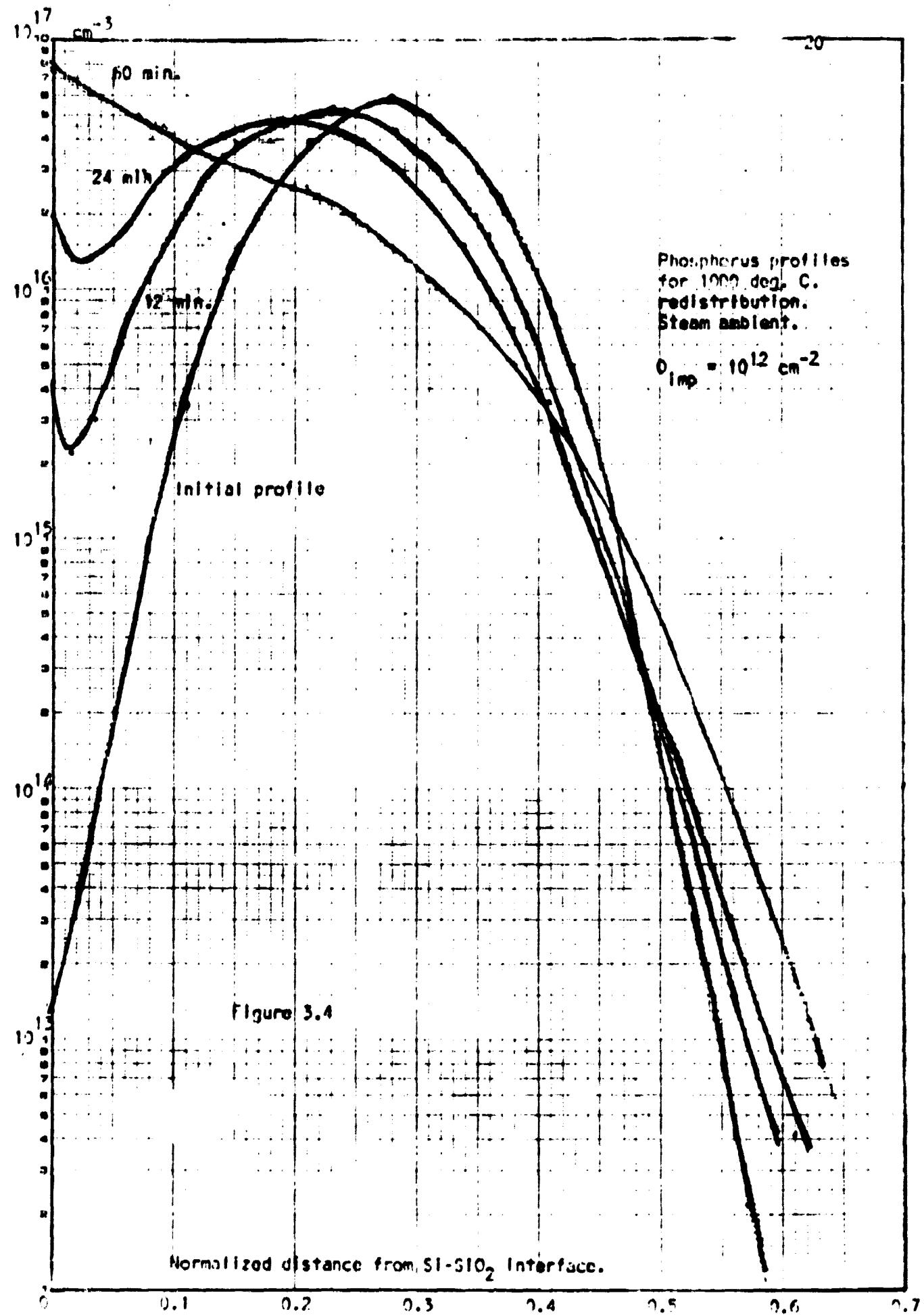


Figure 3.2



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is of course shrinking. The boron profiles are not unusual but show the well-known leaching effect due to segregation into the oxide. The phosphorus profiles show the effect of impurities being rejected from the oxide. There is a pile-up of impurities in front of the advancing Si-SiO₂ interface and then a dip which eventually disappears. It is easy for one to draw an erroneous conclusion from observing the profiles, because it appears that the integrated dose should increase for at least remain constant and the sheet resistance should decrease with time. This is not true. Although the segregation coefficient favors phosphorus in silicon vs. SiO₂, eventually all of the phosphorus will be in the SiO₂ when the SOS film is completely oxidized since the model assumes that there is no diffusion into the sapphire.

Figures (3.5-3.7) illustrate the behavior of the junction migration, sheet resistance variation, and integrated impurity dose variation over a long period of time. All of the curves are plotted with respect to normalized time, and true time is obtained by multiplying by the normalizing time value given on the plot. Junction depths are in microns, sheet resistance values are in ohms, and dose values are in cm⁻² units unless otherwise marked. The curves are given in the typical format for all of the data.

For an ion-implanted profile, there are in fact two junctions until one of the junctions emerges at the Si-SiO₂ interface. Therefore, the sheet resistance values are for the buried layer until the front junction disappears. This typically occurs in a short time compared with that for through-diffusion of the back junction. Figure (3.5) illustrates the through-diffusion of the back junction for the heavier doses. This always occurs for redistribution in a nitrogen ambient but not necessarily so for an oxidizing ambient. After the through diffusion, or even before for light doses, the junction depth will eventually decrease due to the reduction of the film thickness or due to the

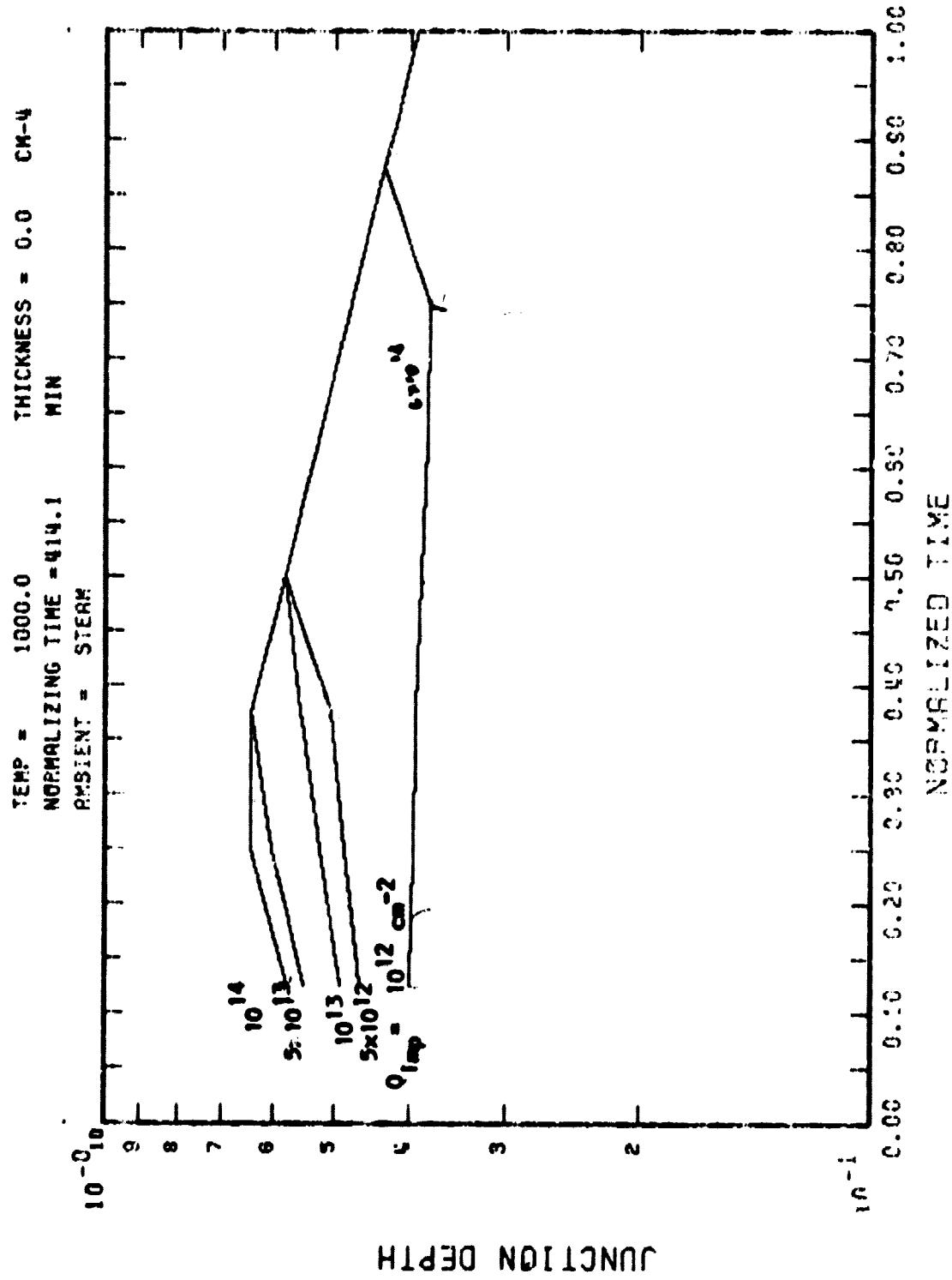


Figure 3.5 Junction position with respect to Si-SiO₂ Interface for Boron redistribution.

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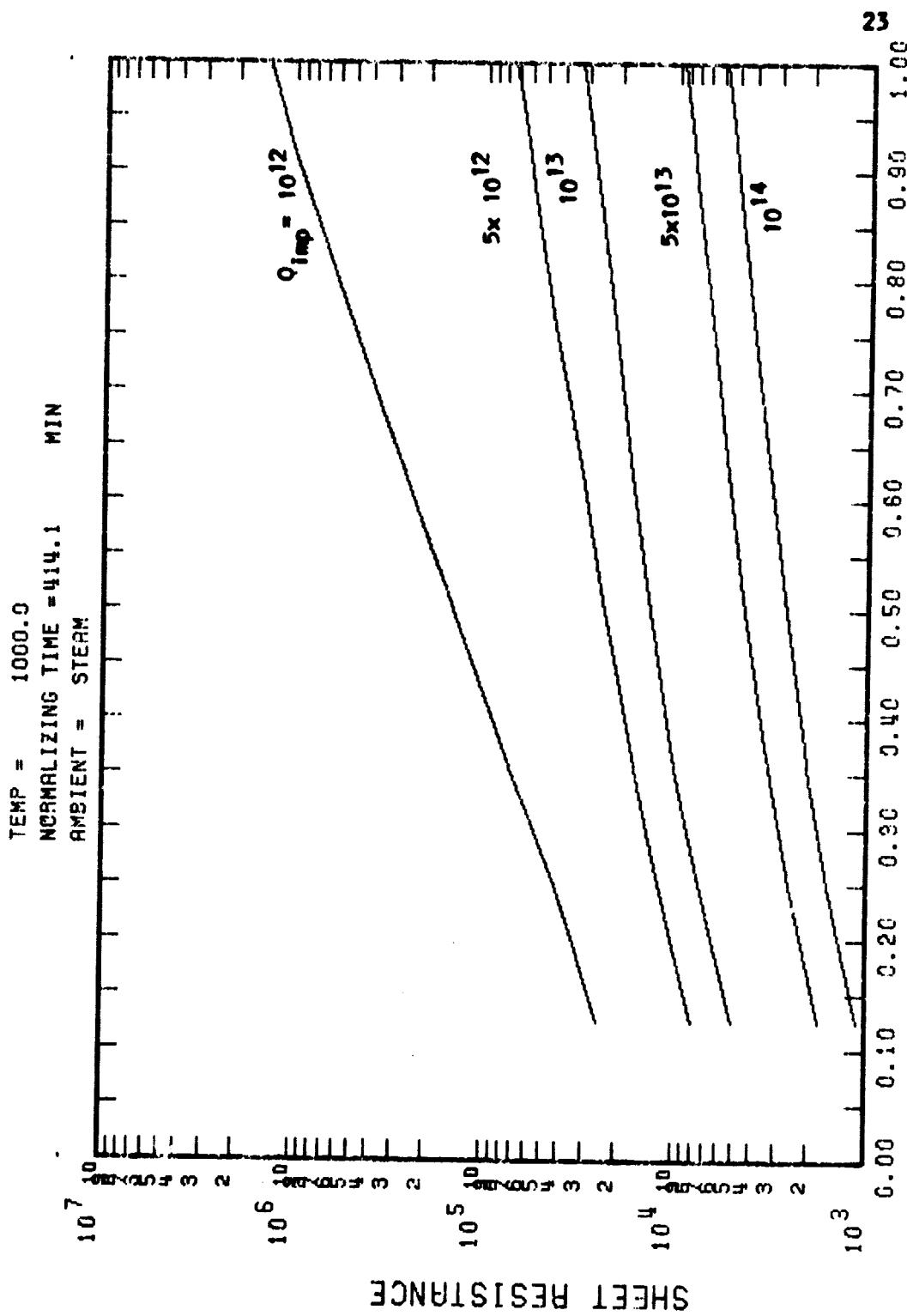
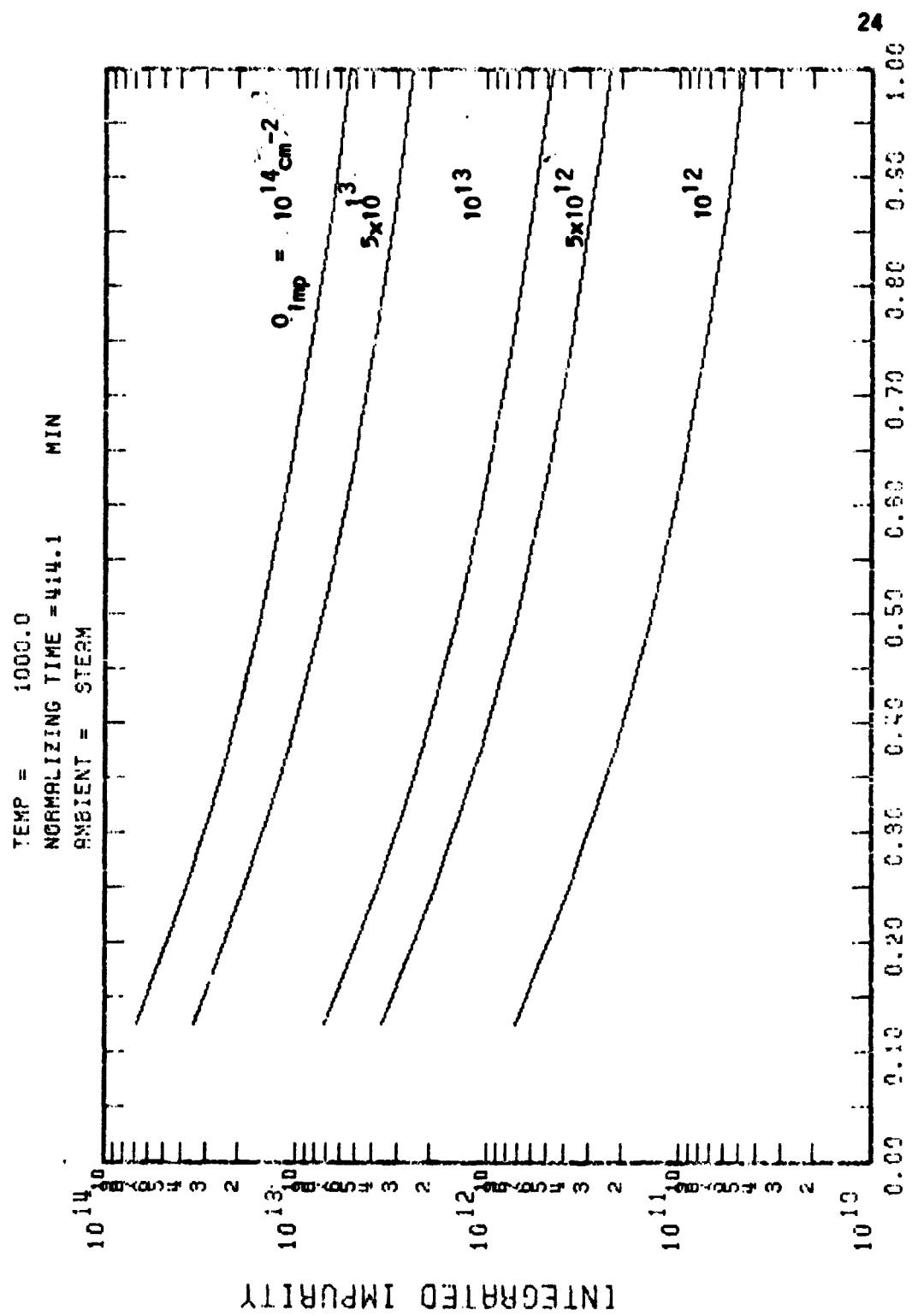


Figure 3.6 Sheet resistance for Boron redistribution.

Figure 3.7 Variation of Dose for Boron redistribution.



B

relatively slow advancement of the junction with respect to the moving Si-SiO₂ interface. In some of the data presented in the appendix, the junction appears to remain almost stationary for this same reason. The variation of the sheet resistance and dose with redistribution time also may appear strange when compared with results for bulk silicon; however, consideration of the previously mentioned factors also explains these results.

Two-dimensional isoconcentration contours are given in the appendix for the various ambients and the two impurity types. The results are not as remarkable as those given in the last report which were for chemically pre-deposited boron. In that case, there was initially a heavy concentration of fast diffusing impurities at the Si-SiO₂ interface which were strongly retarded due to the segregation phenomena. This does not happen with the ion-implanted predeposit because the initial profile lies below the interface at which the segregation phenomena is effective.

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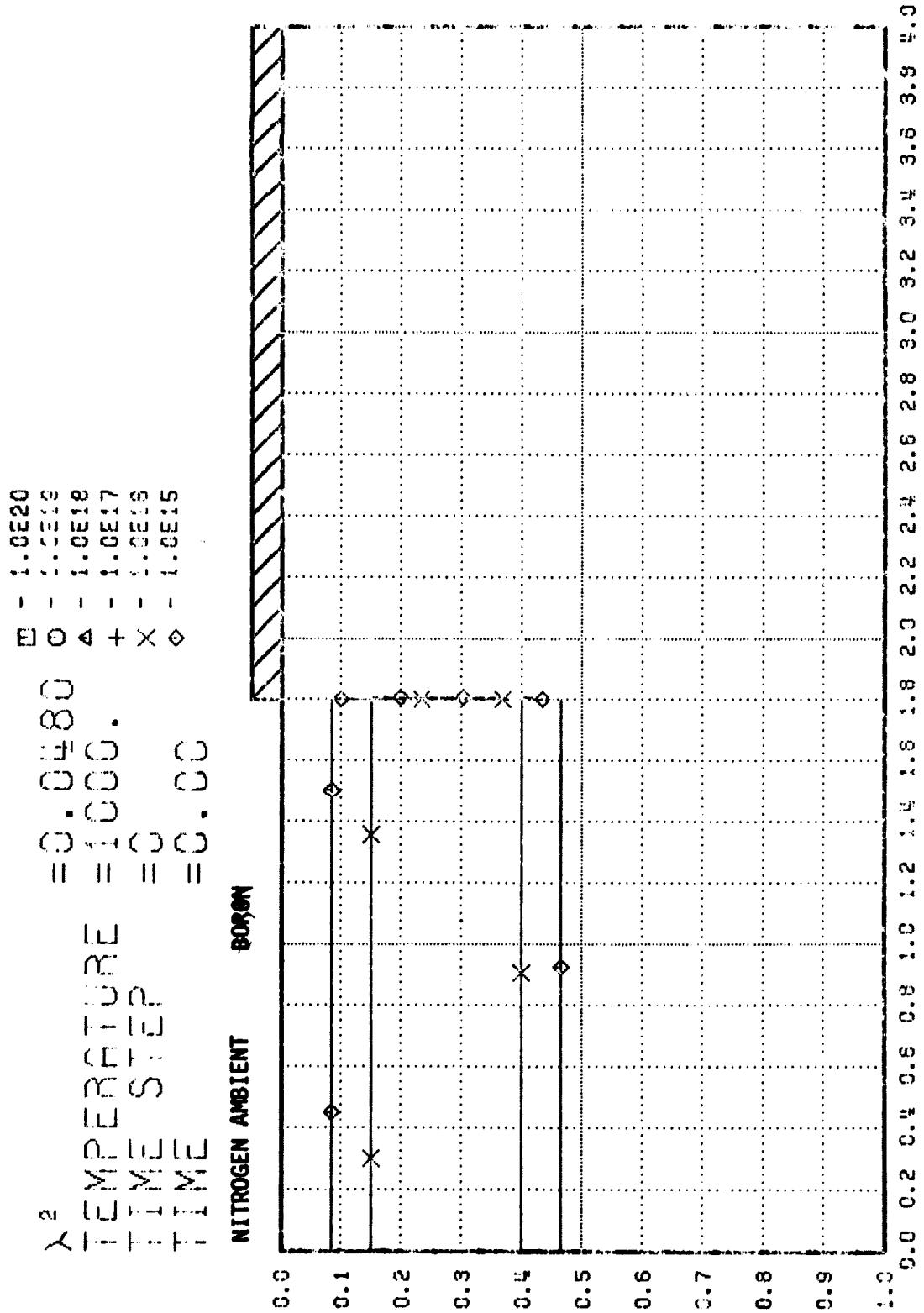
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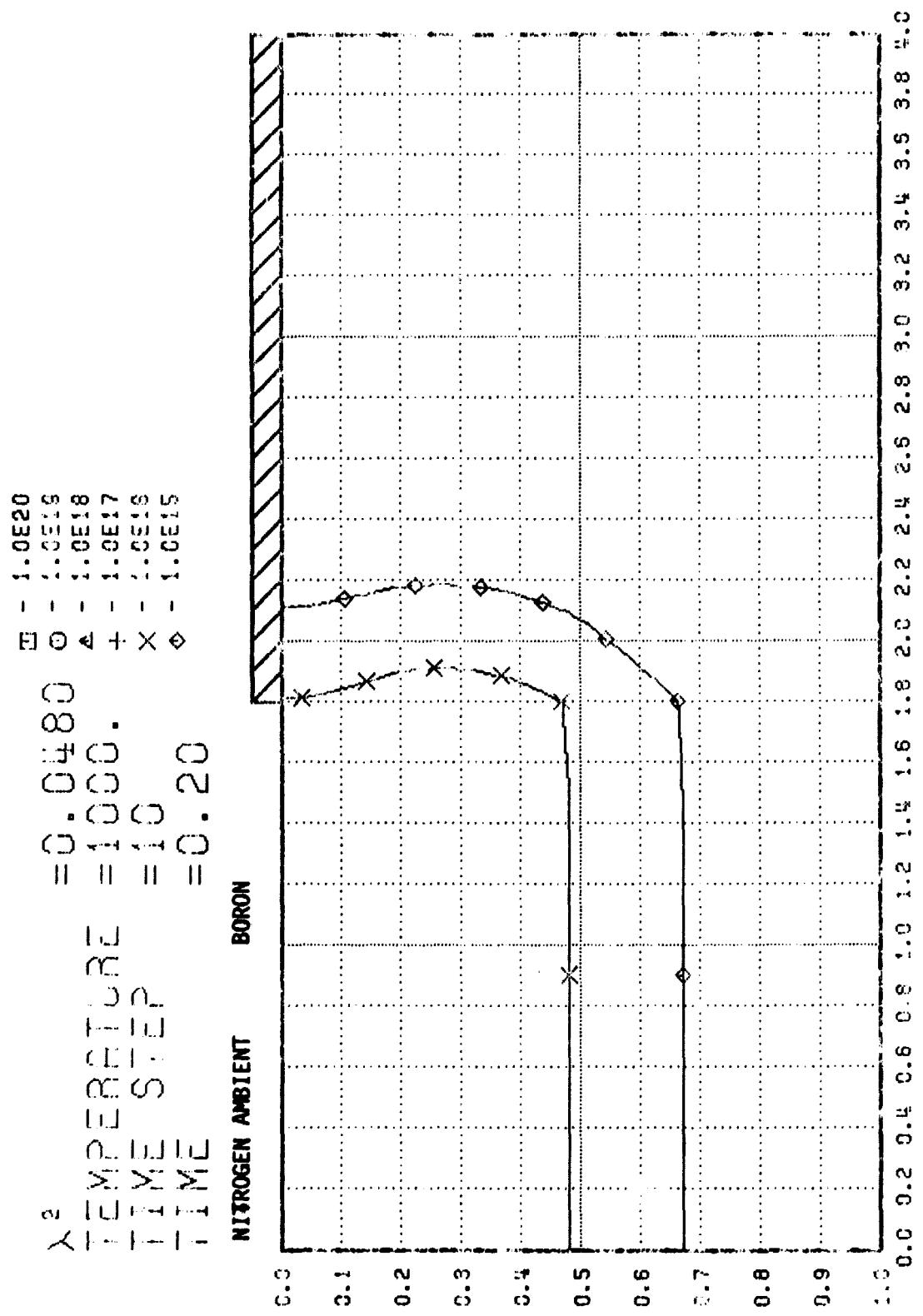
APPENDIX

BORON DATA

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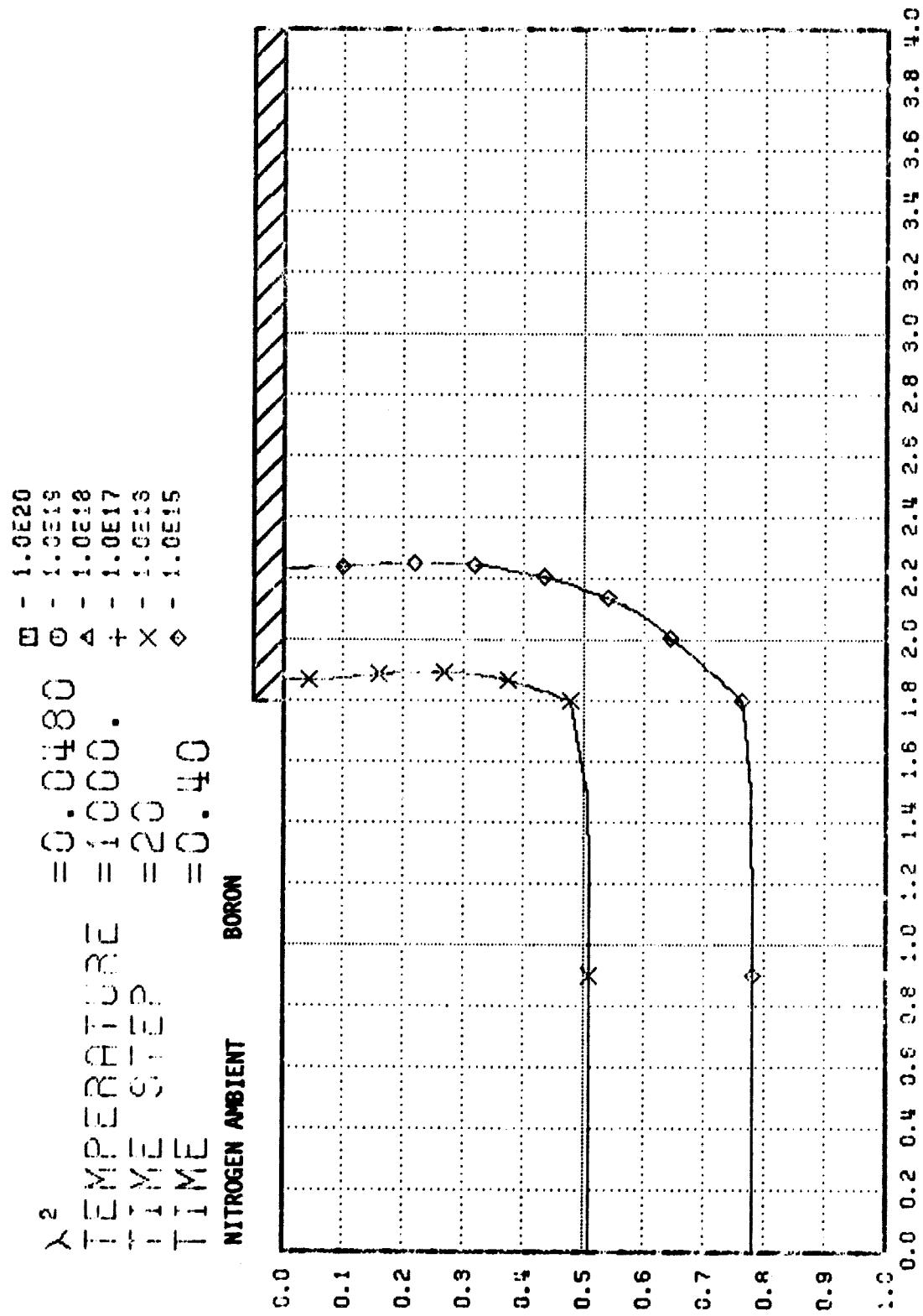
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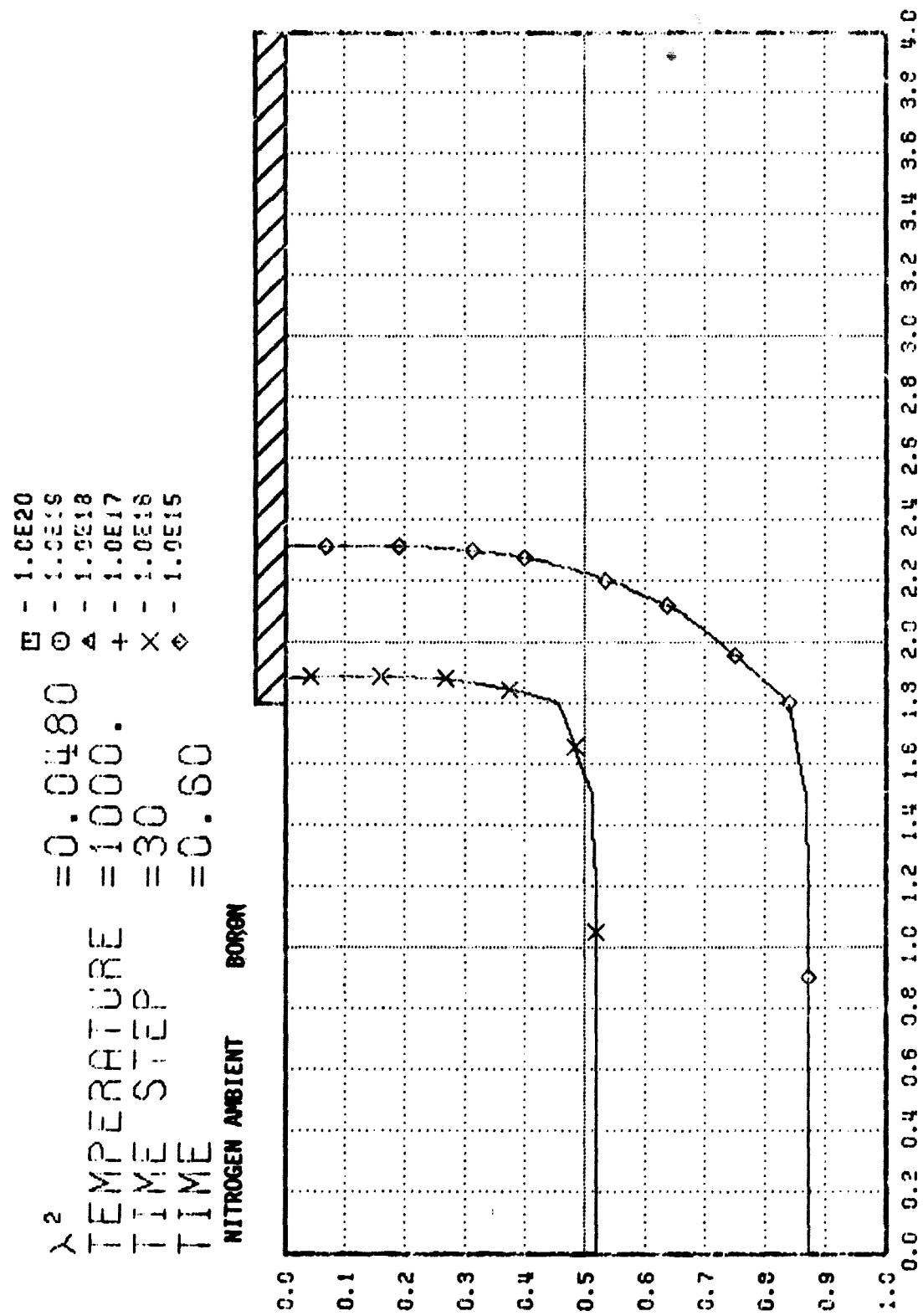




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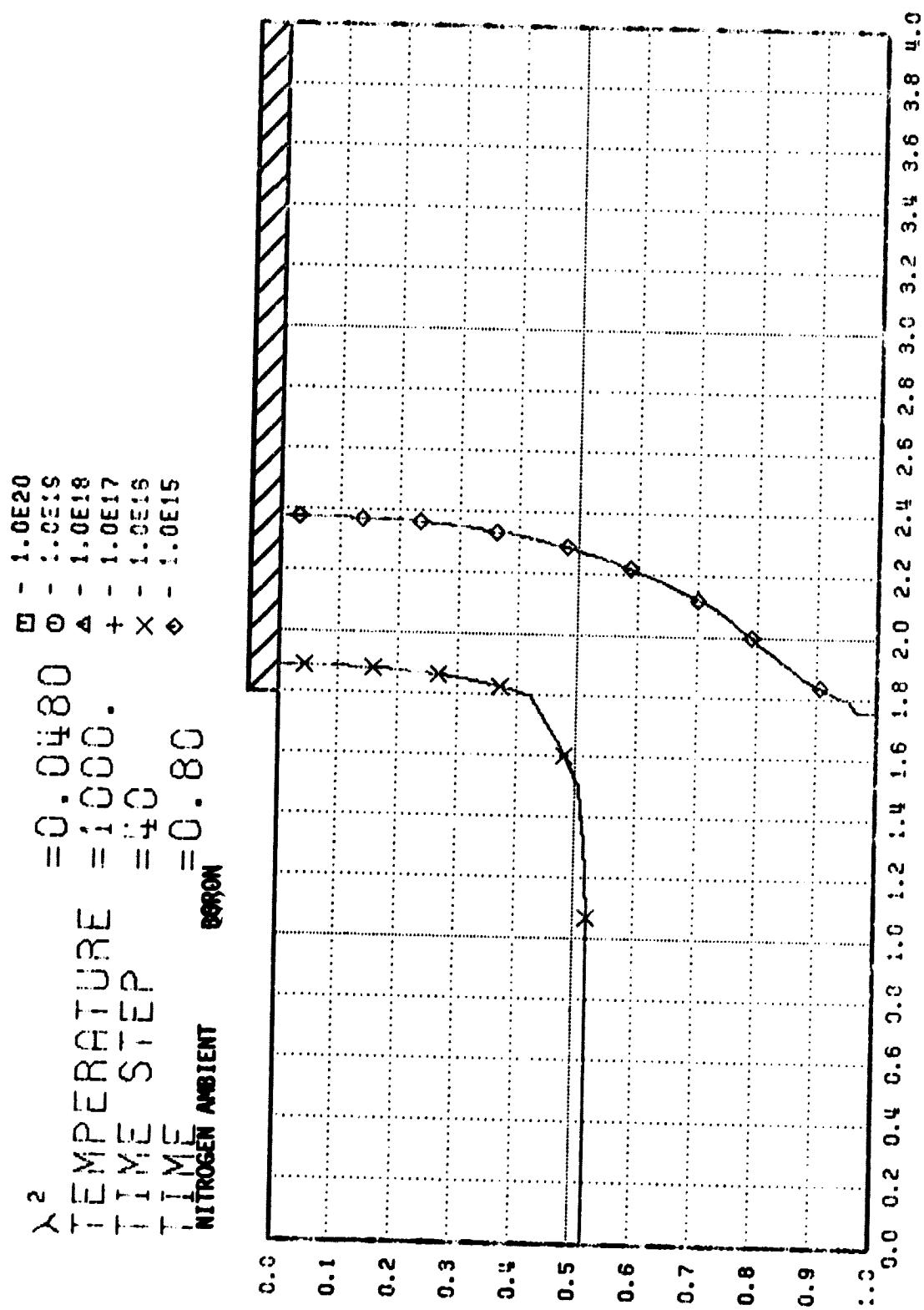
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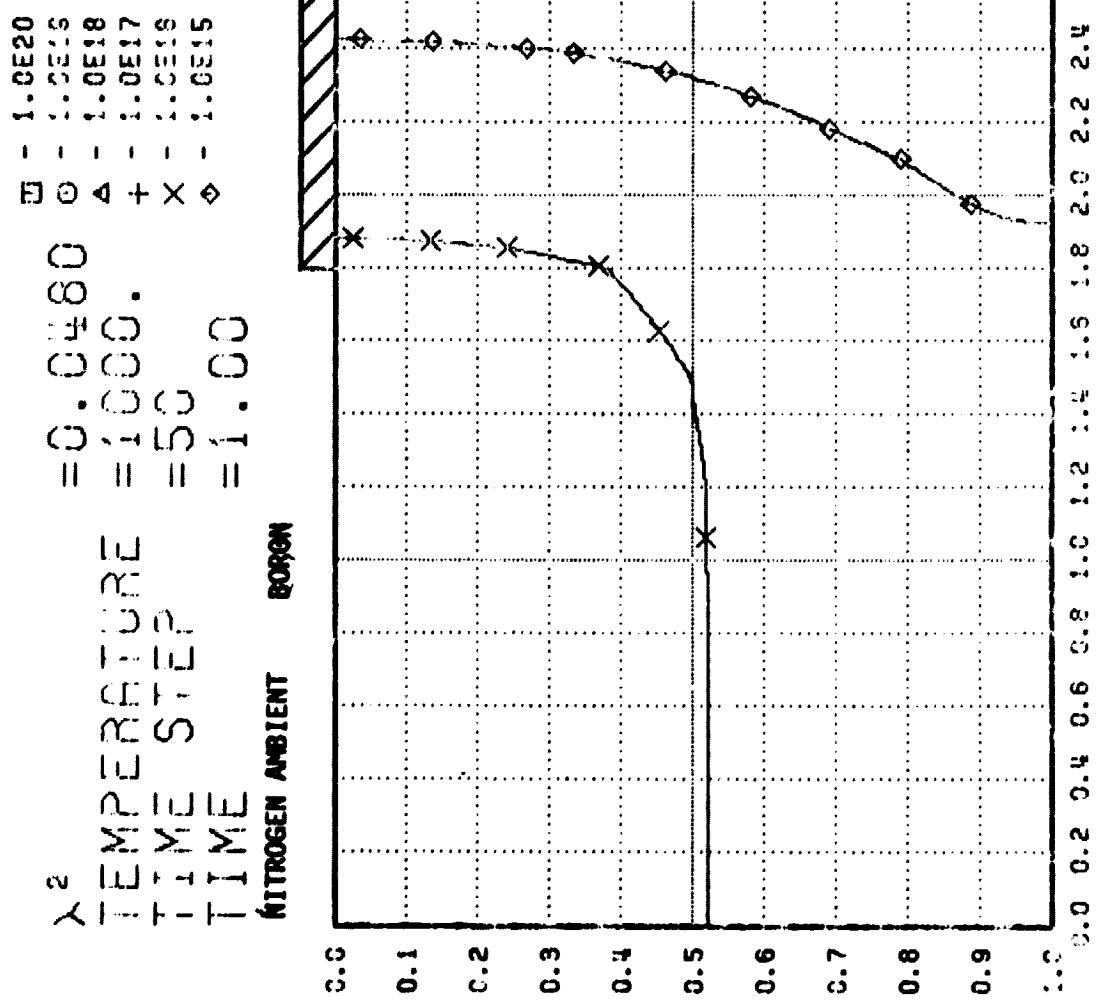




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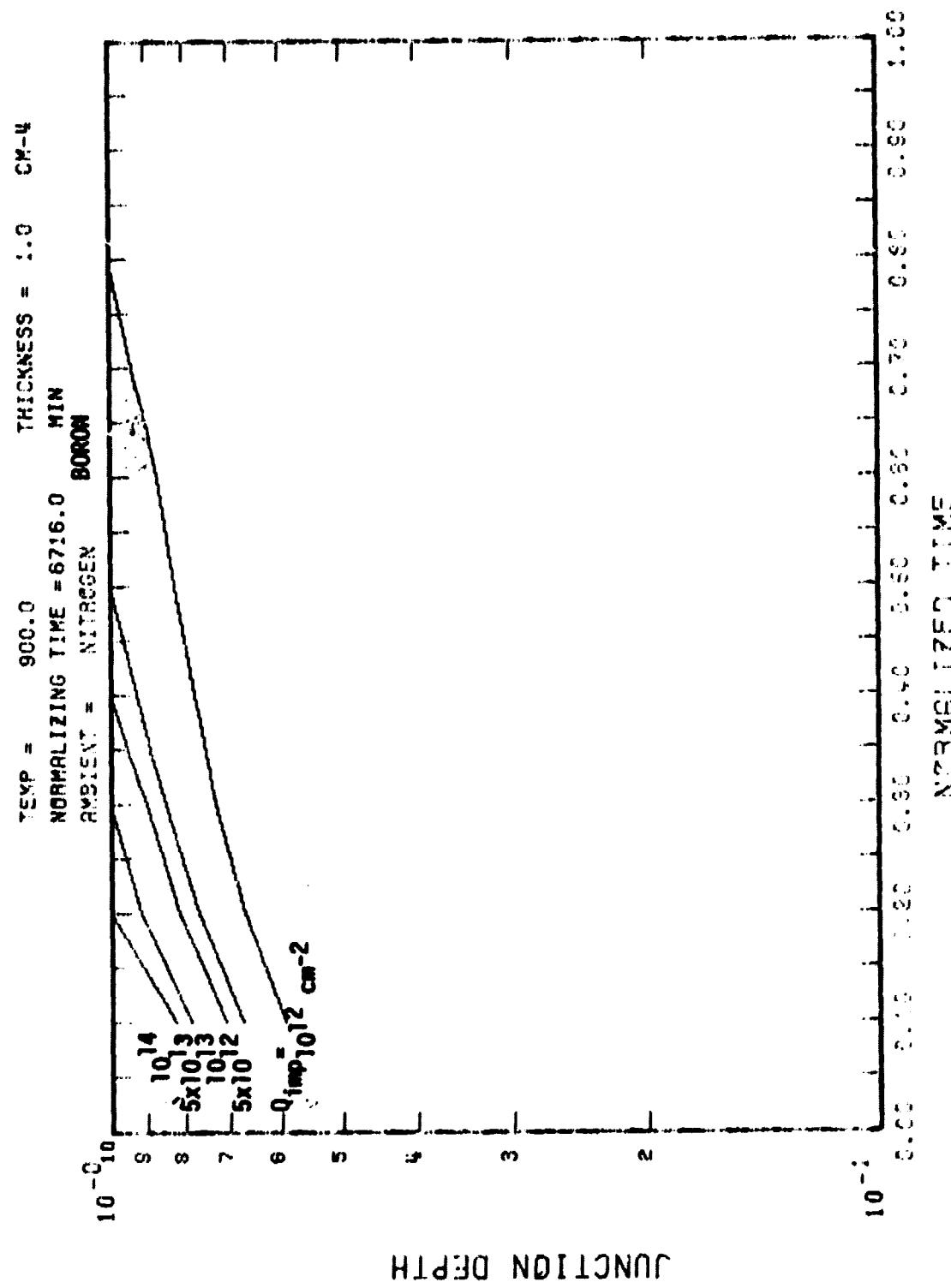
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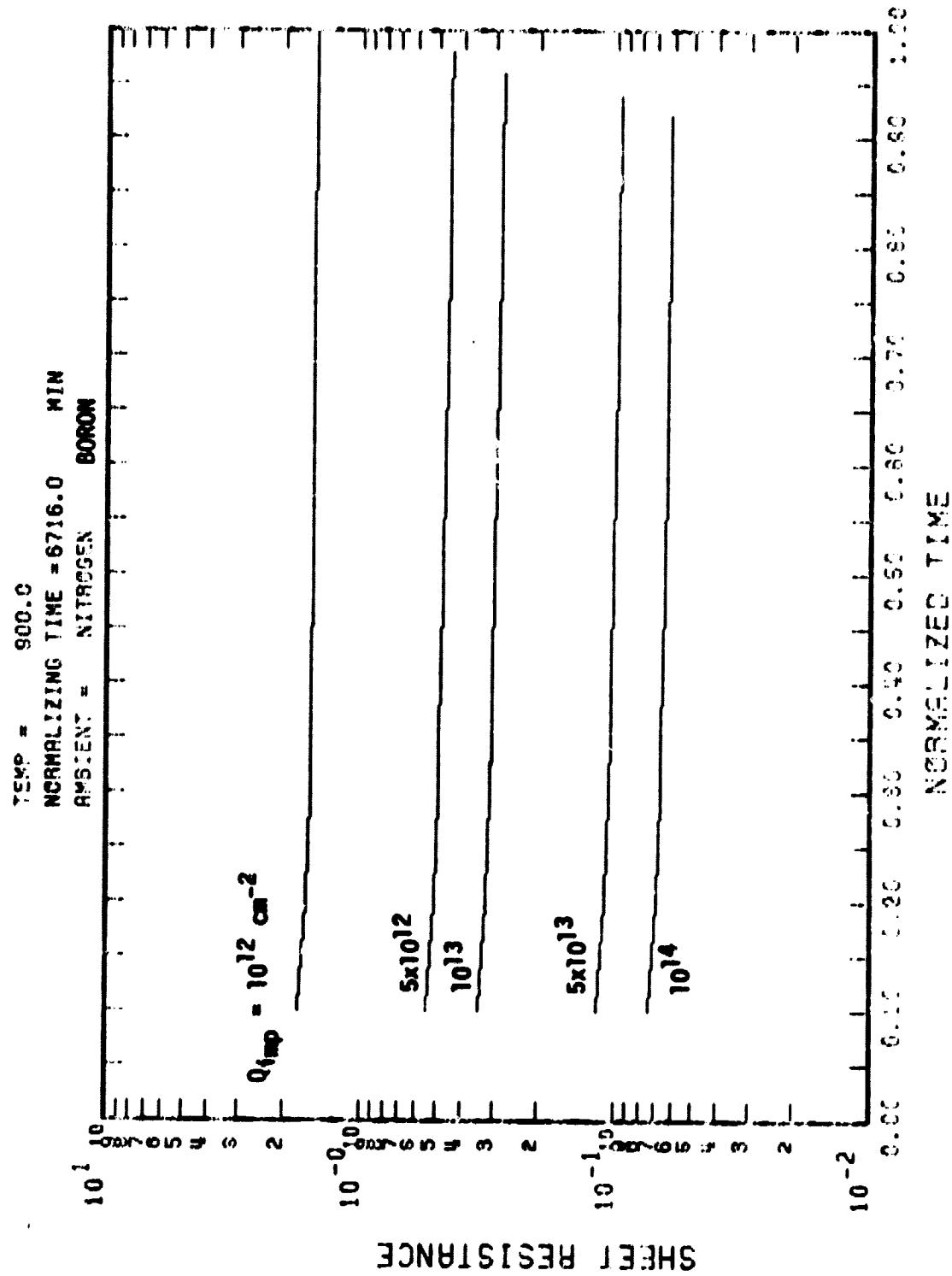
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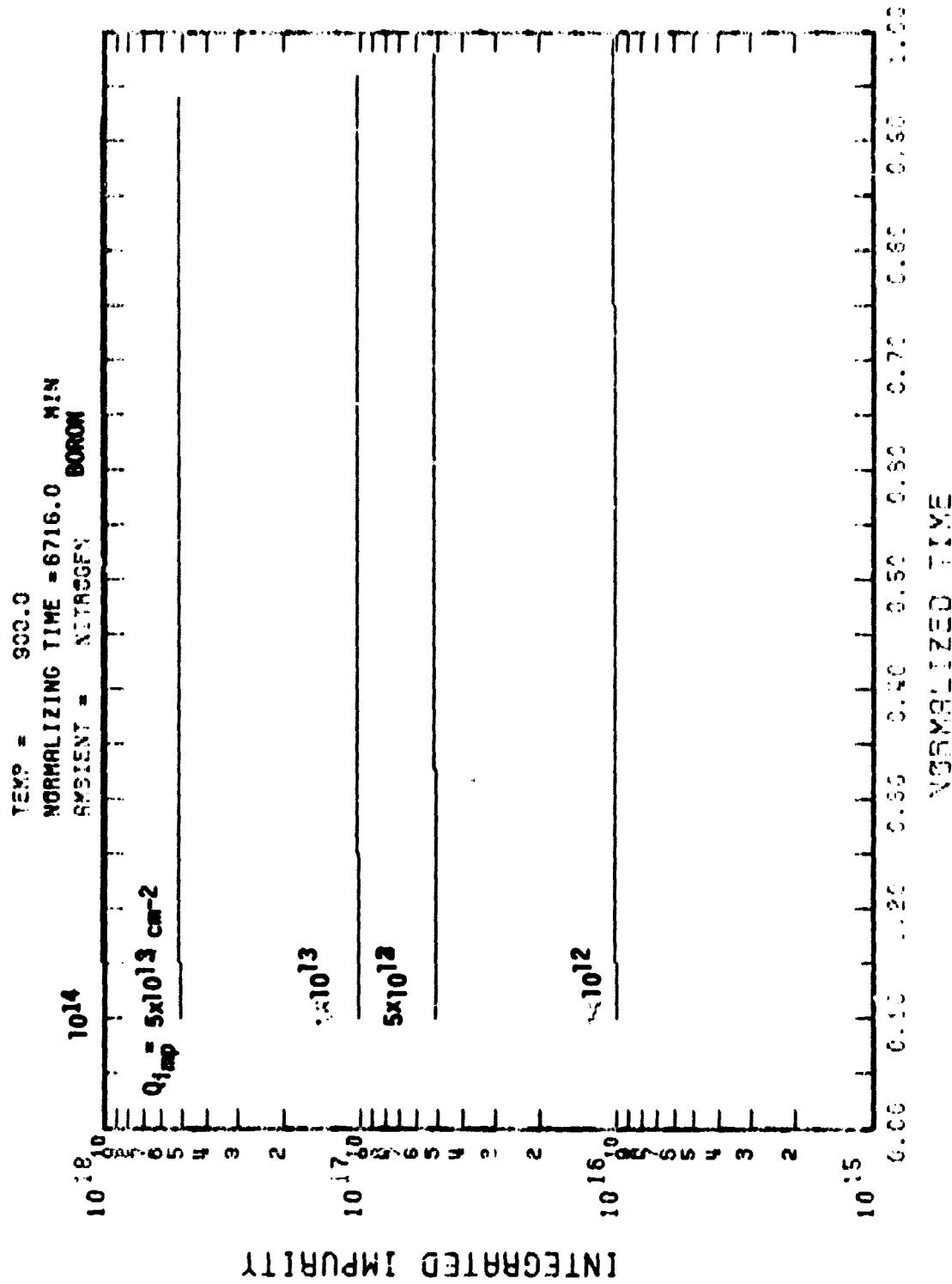
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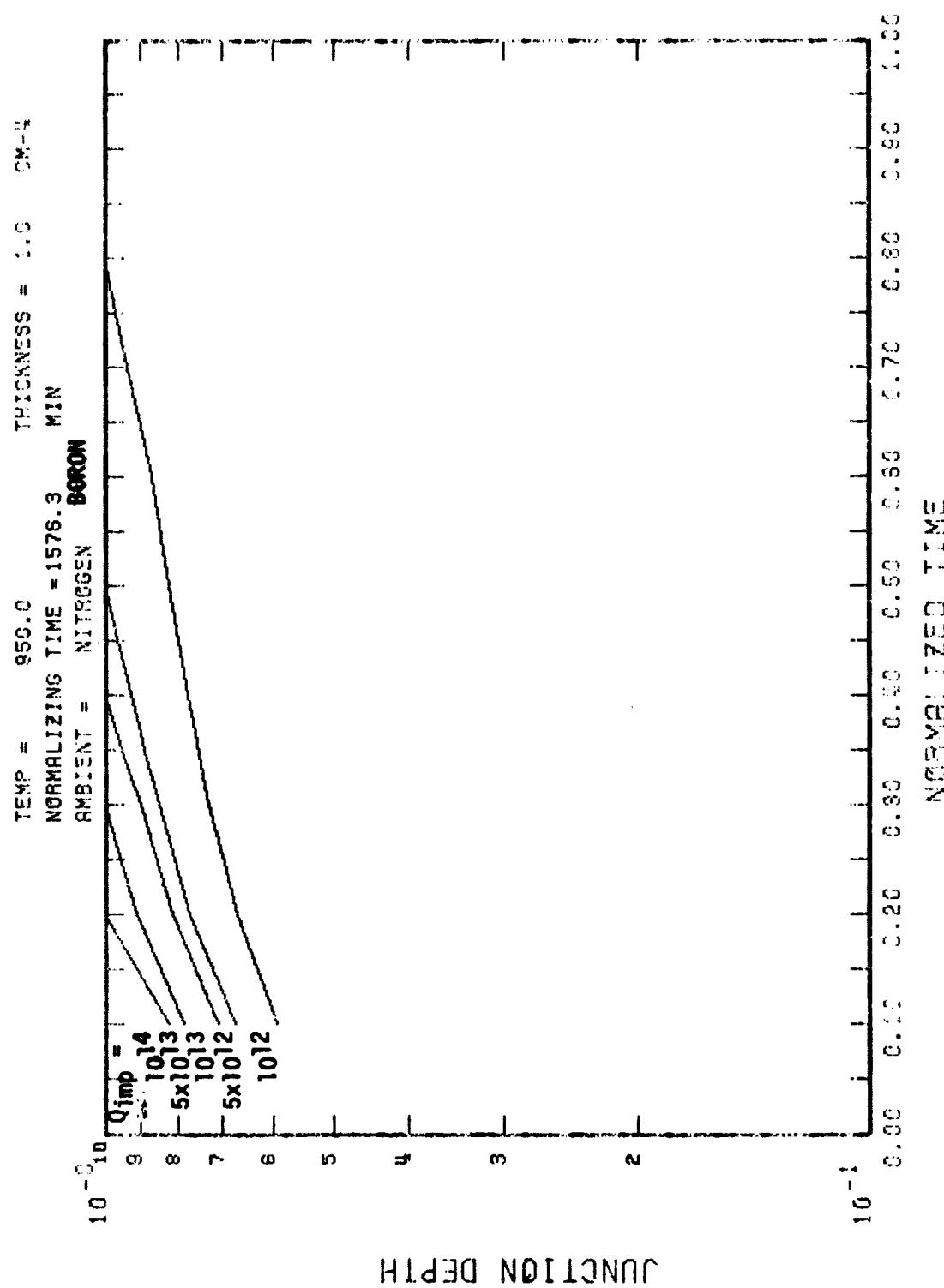
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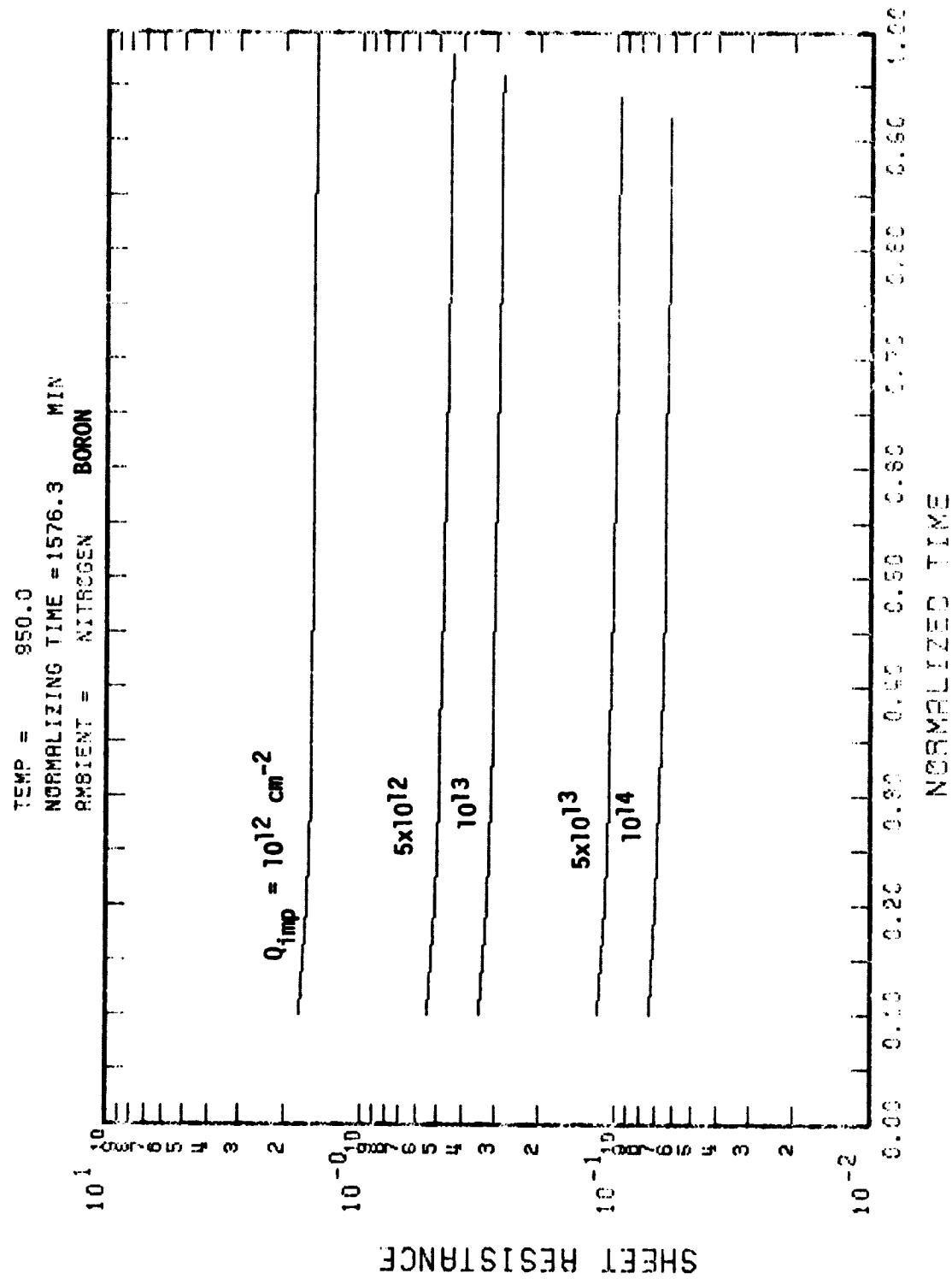


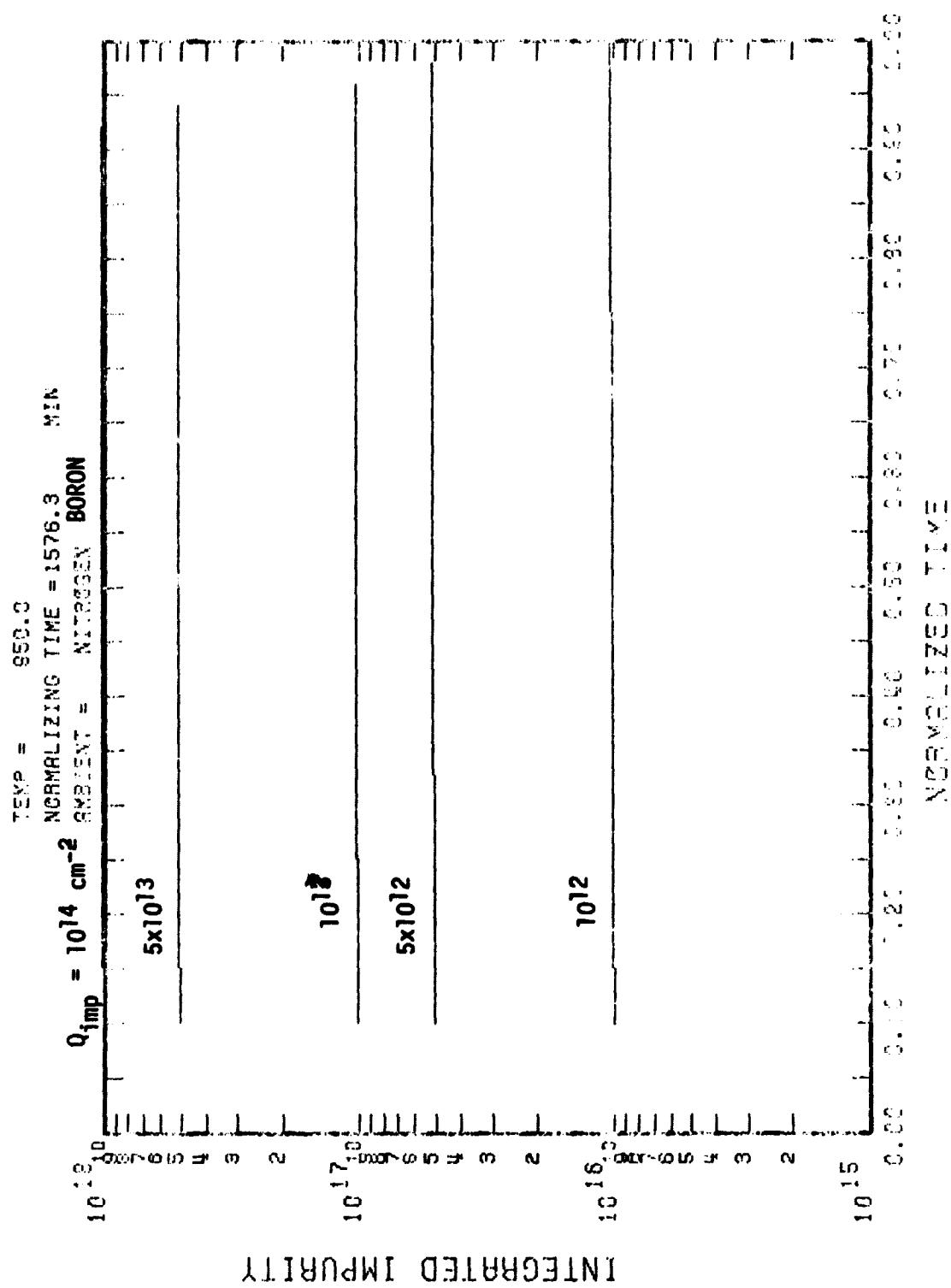
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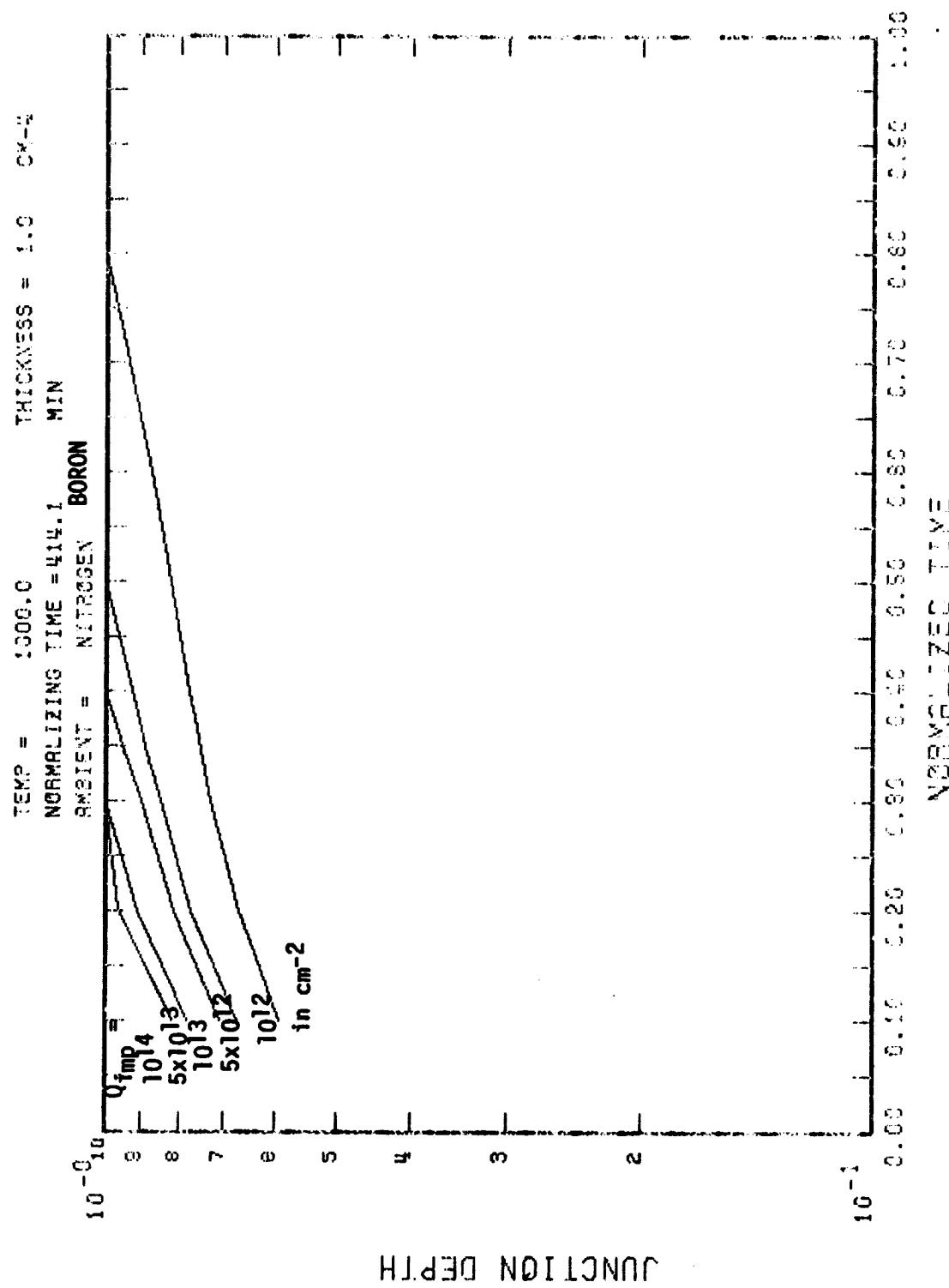


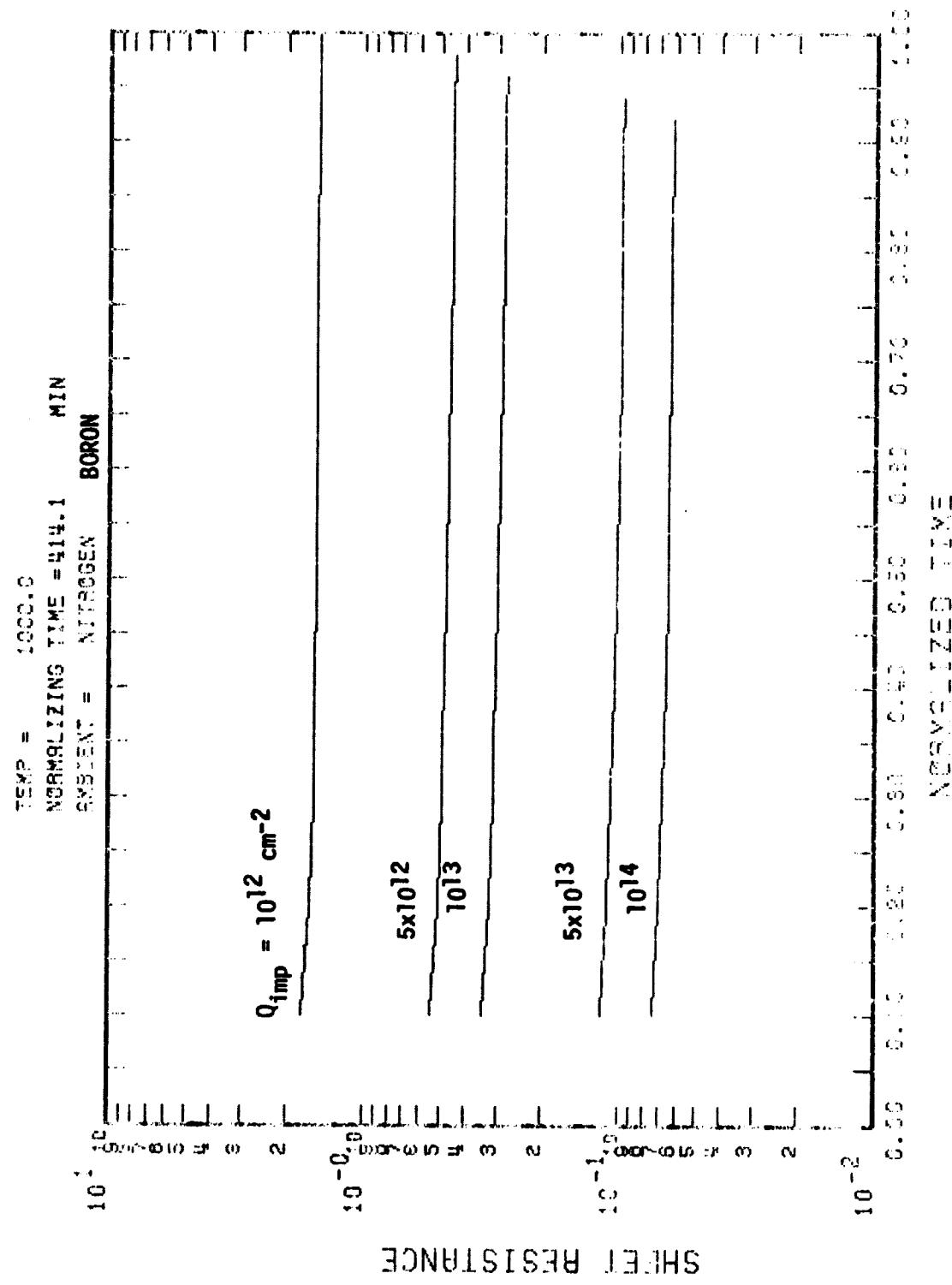
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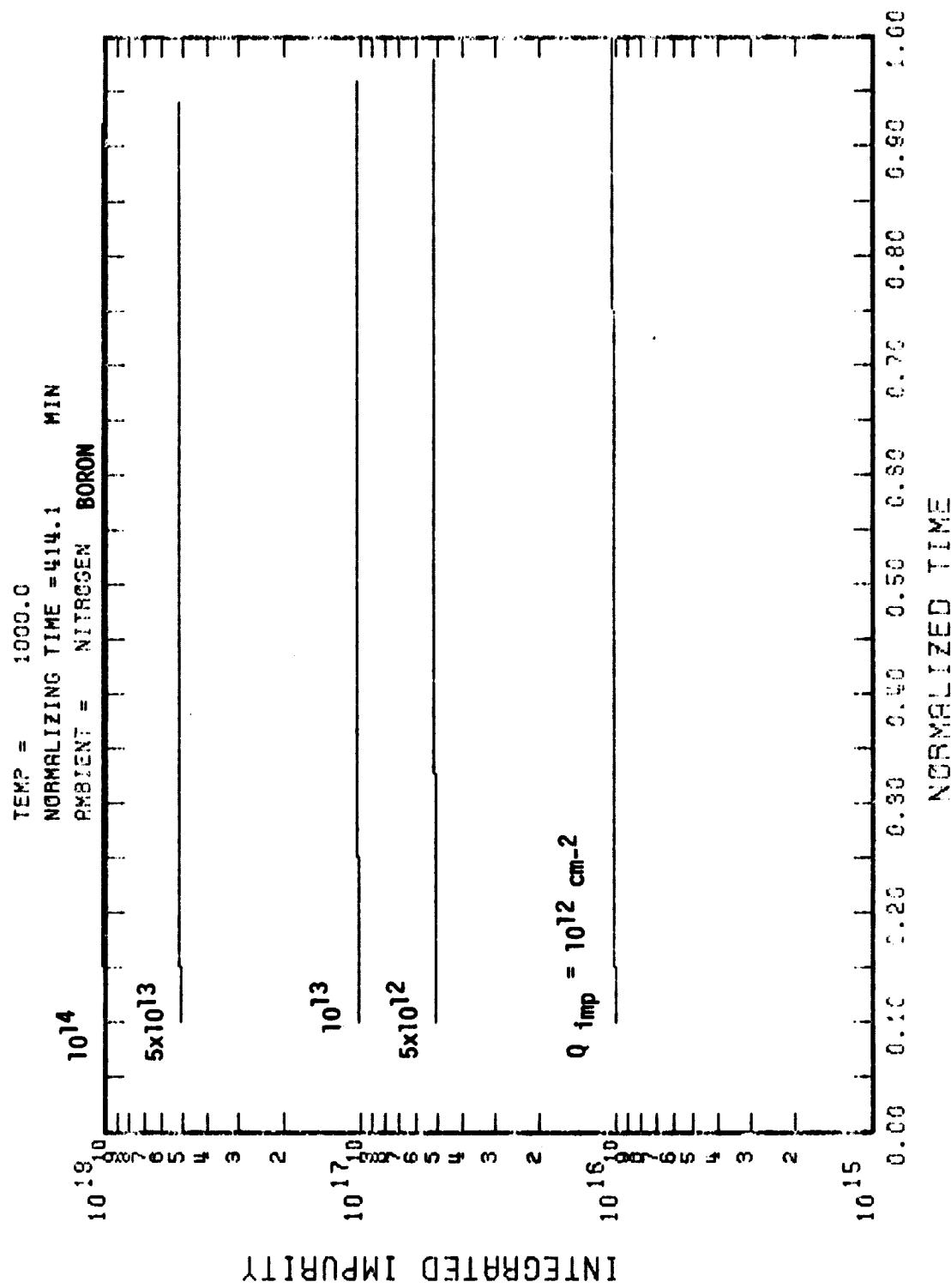
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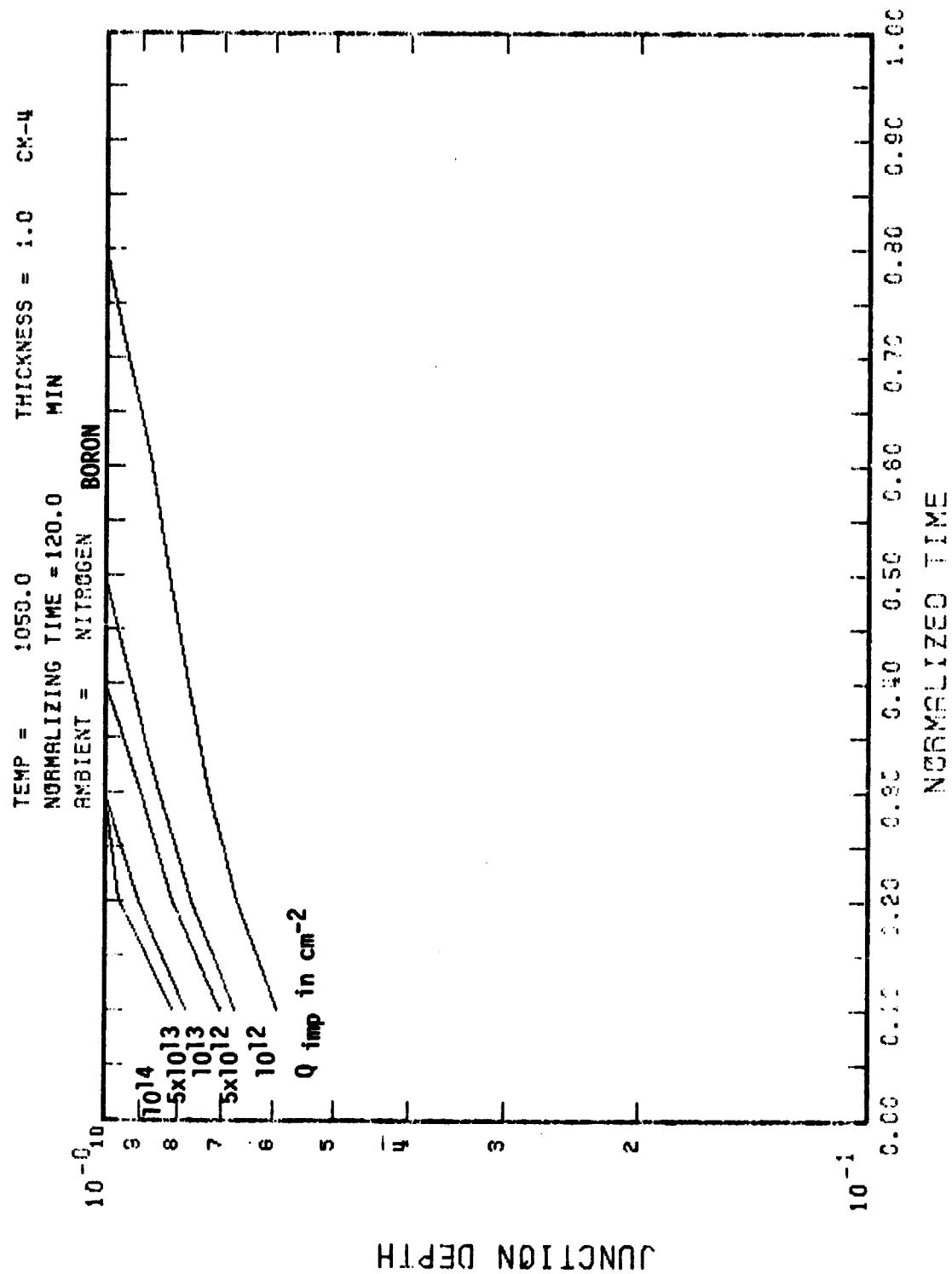
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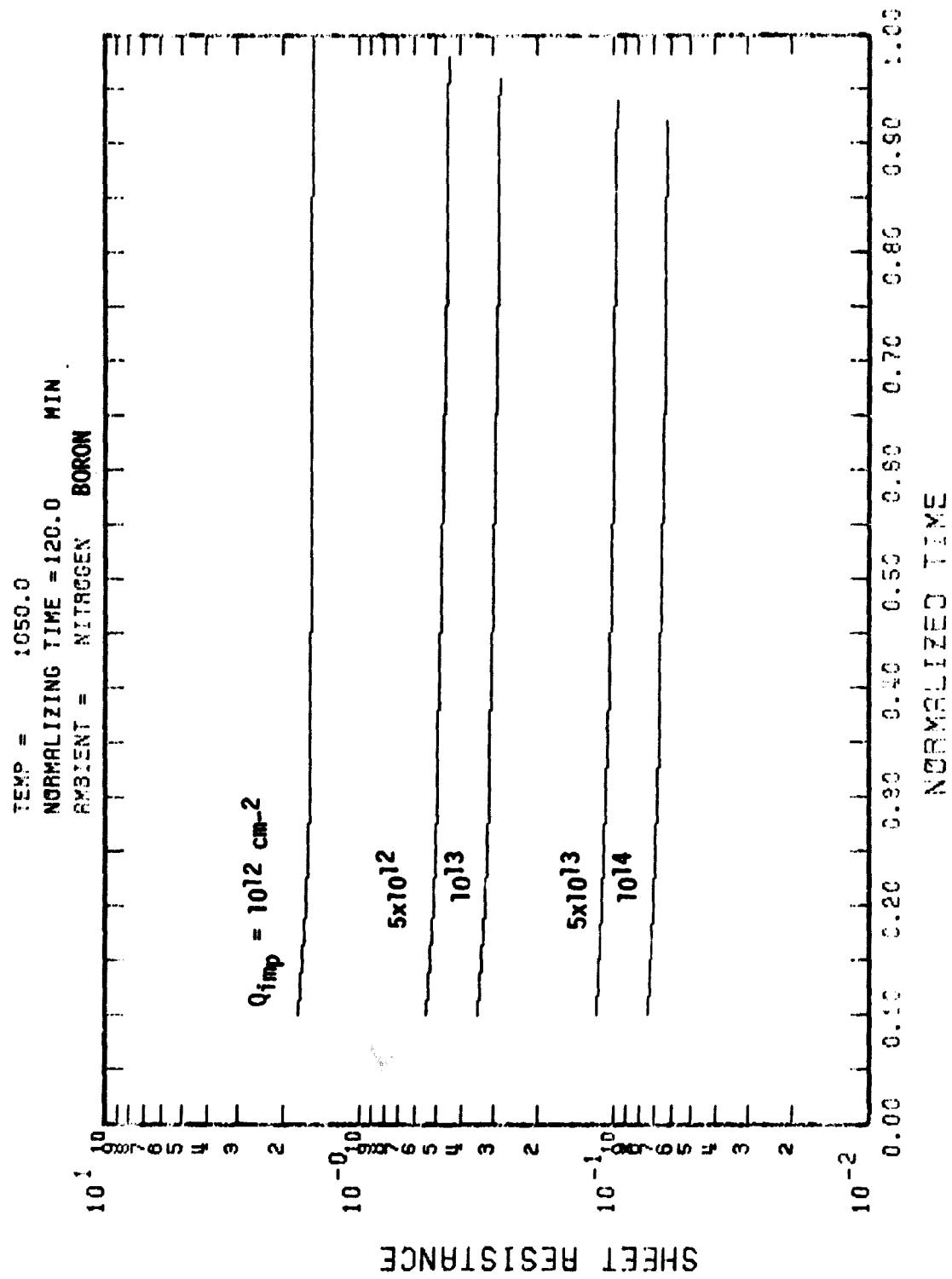
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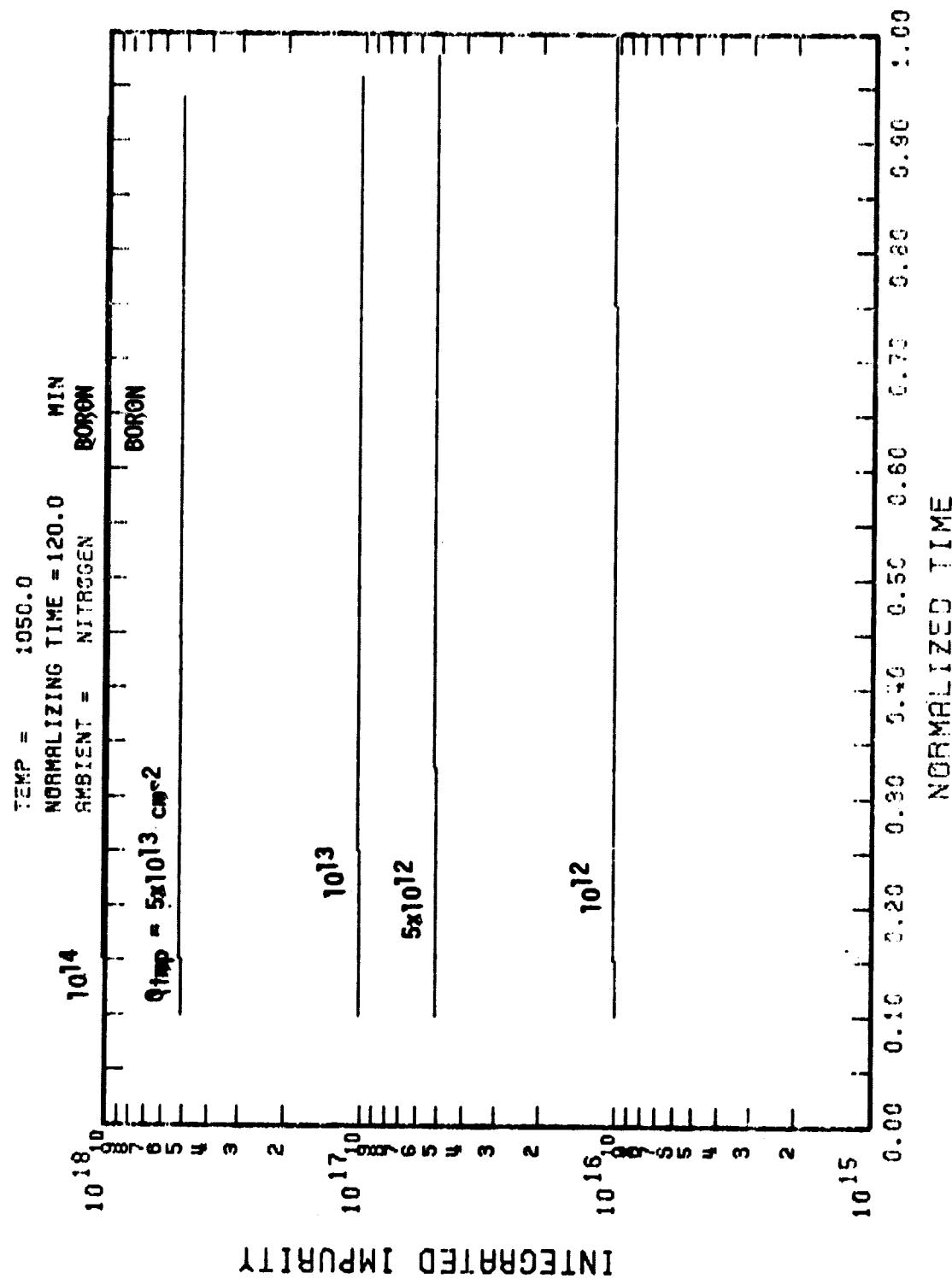
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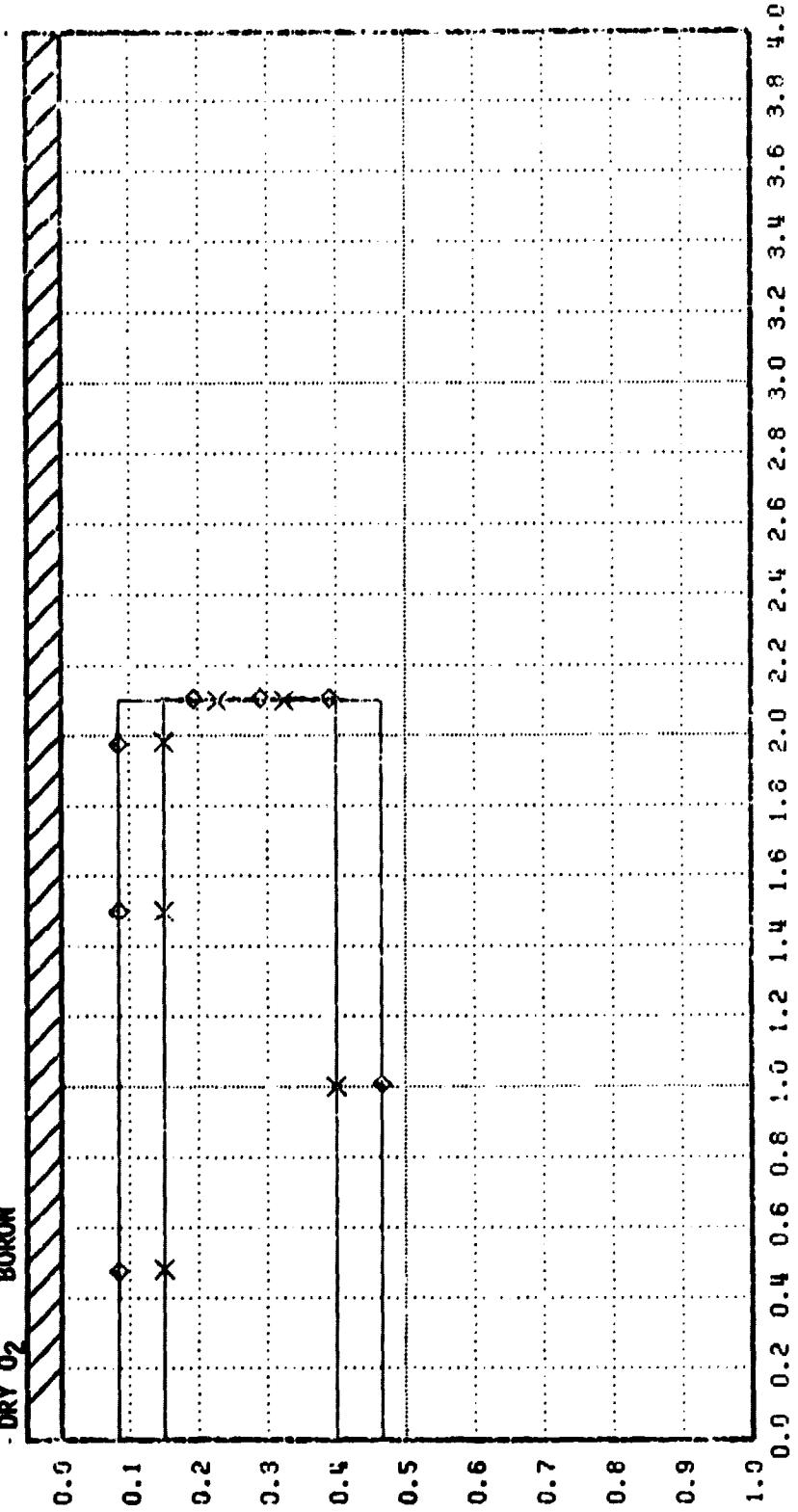


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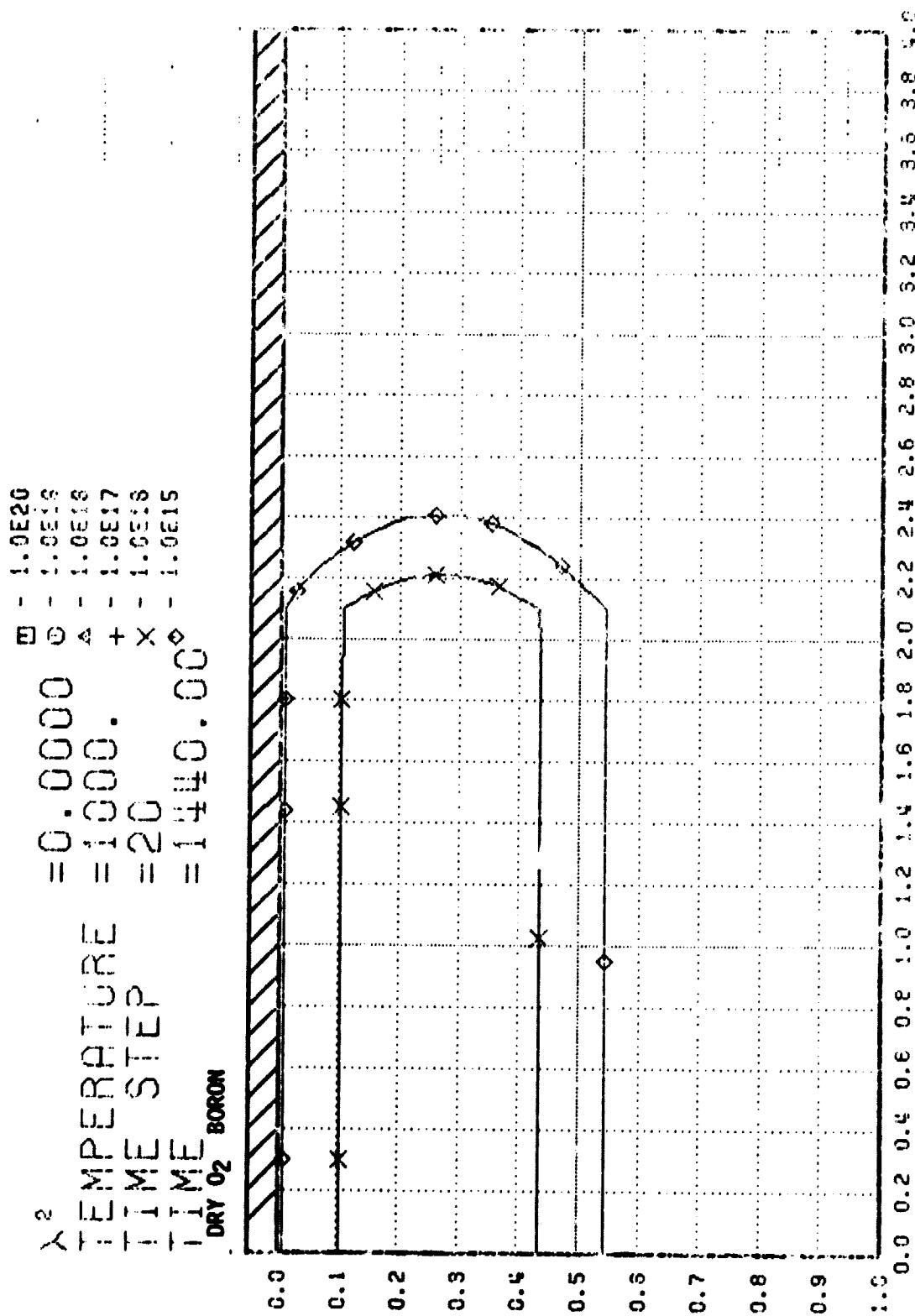


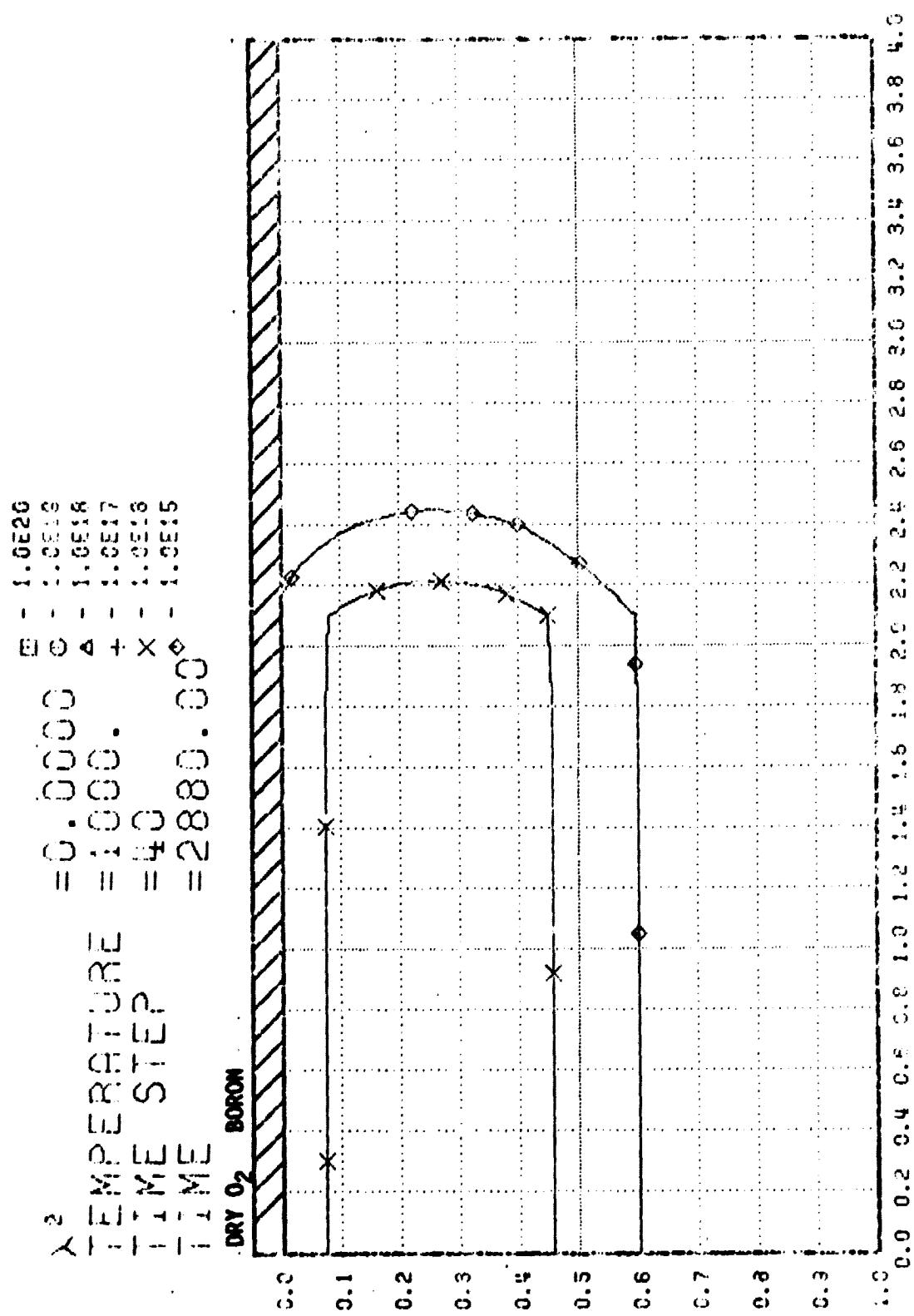
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 λ^2 = 0.0000
DRY O₂ BORON



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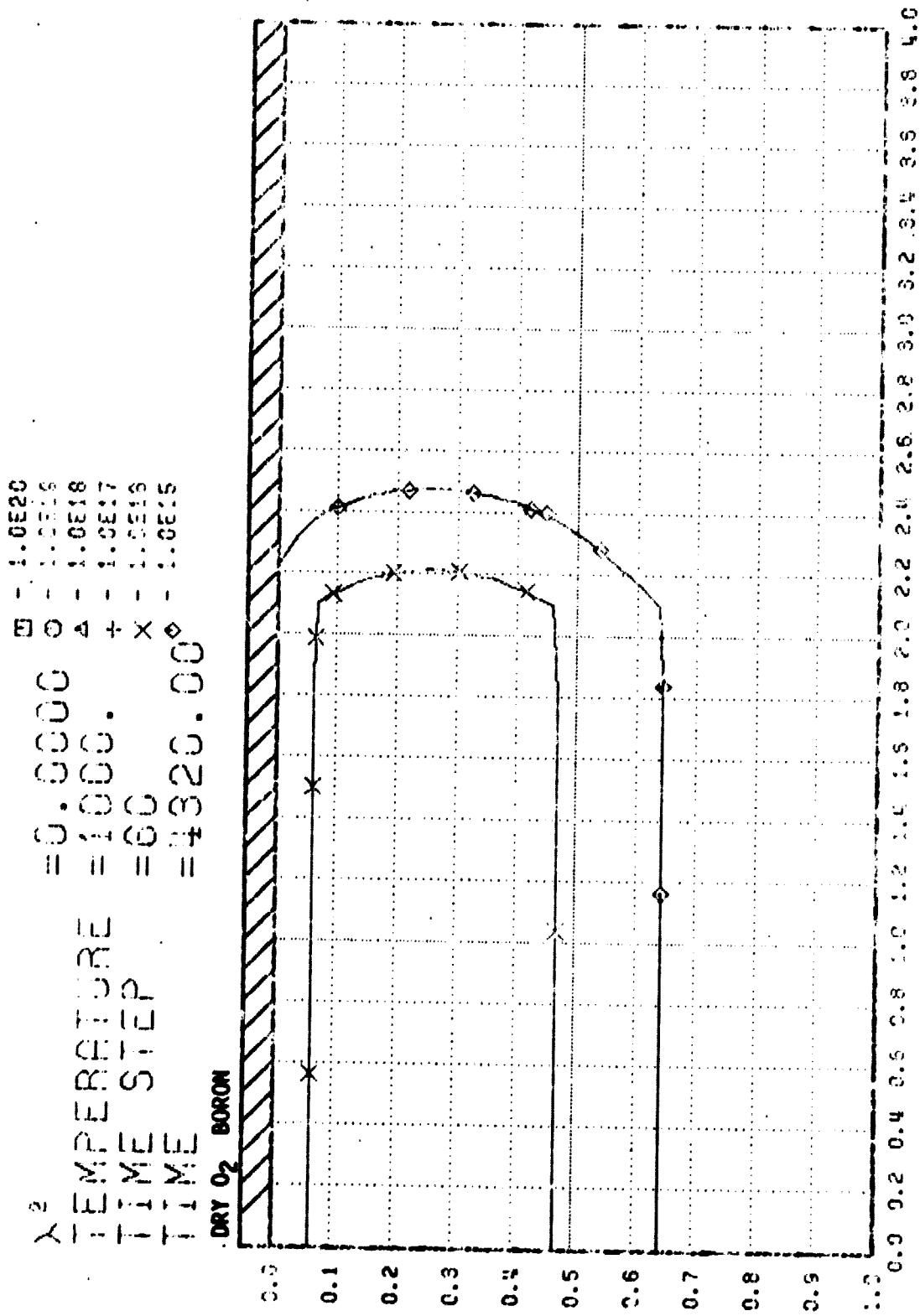
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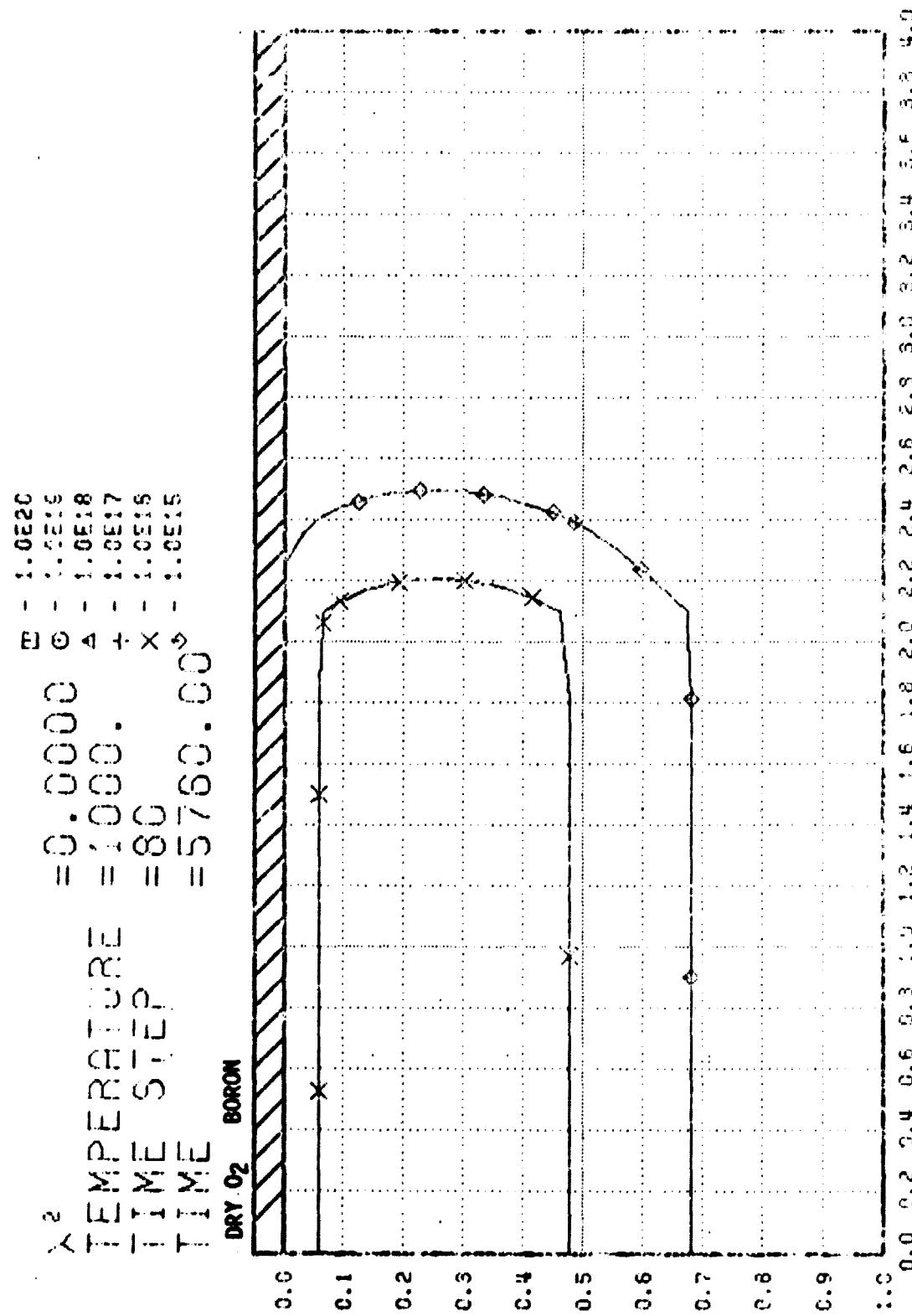




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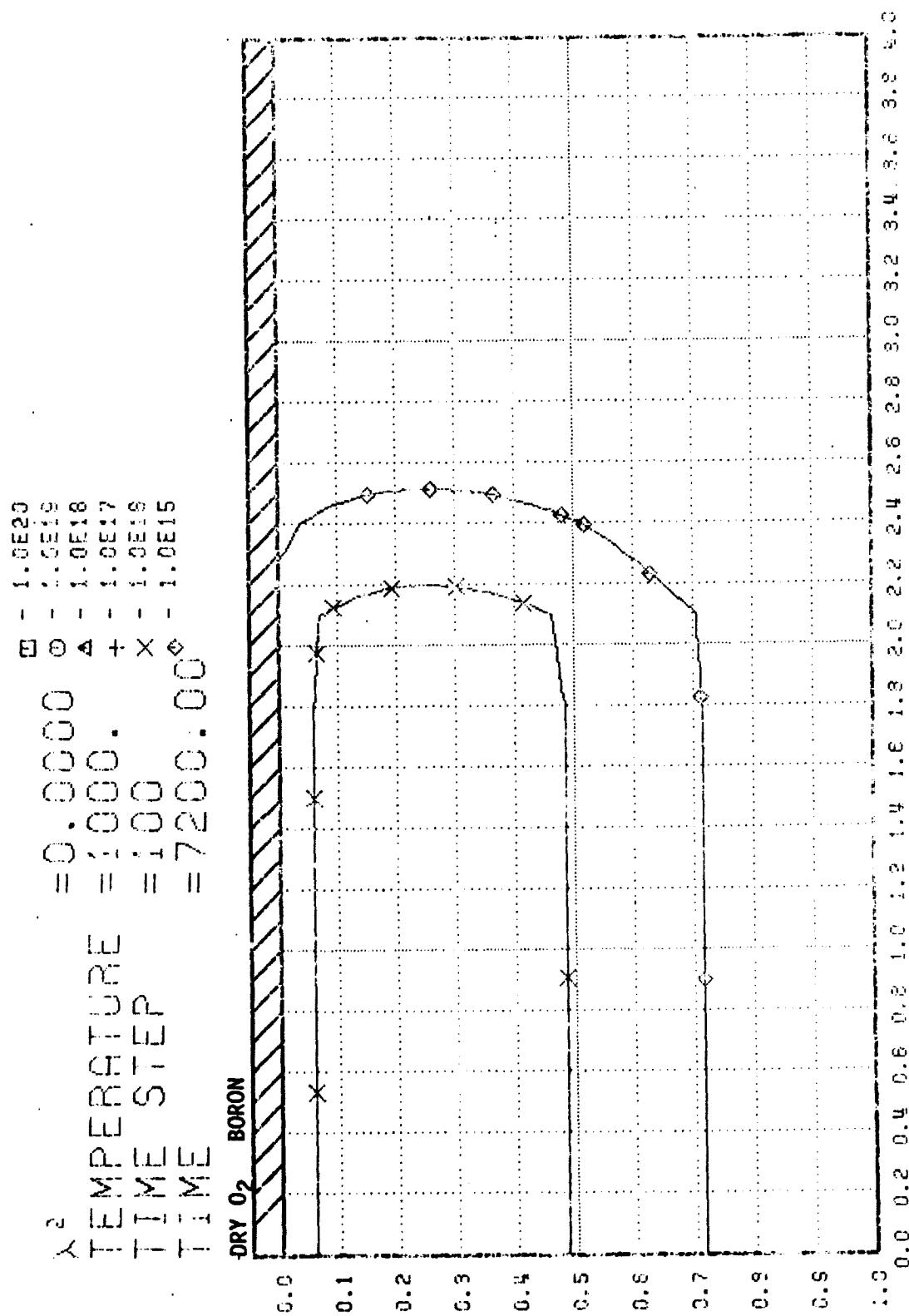
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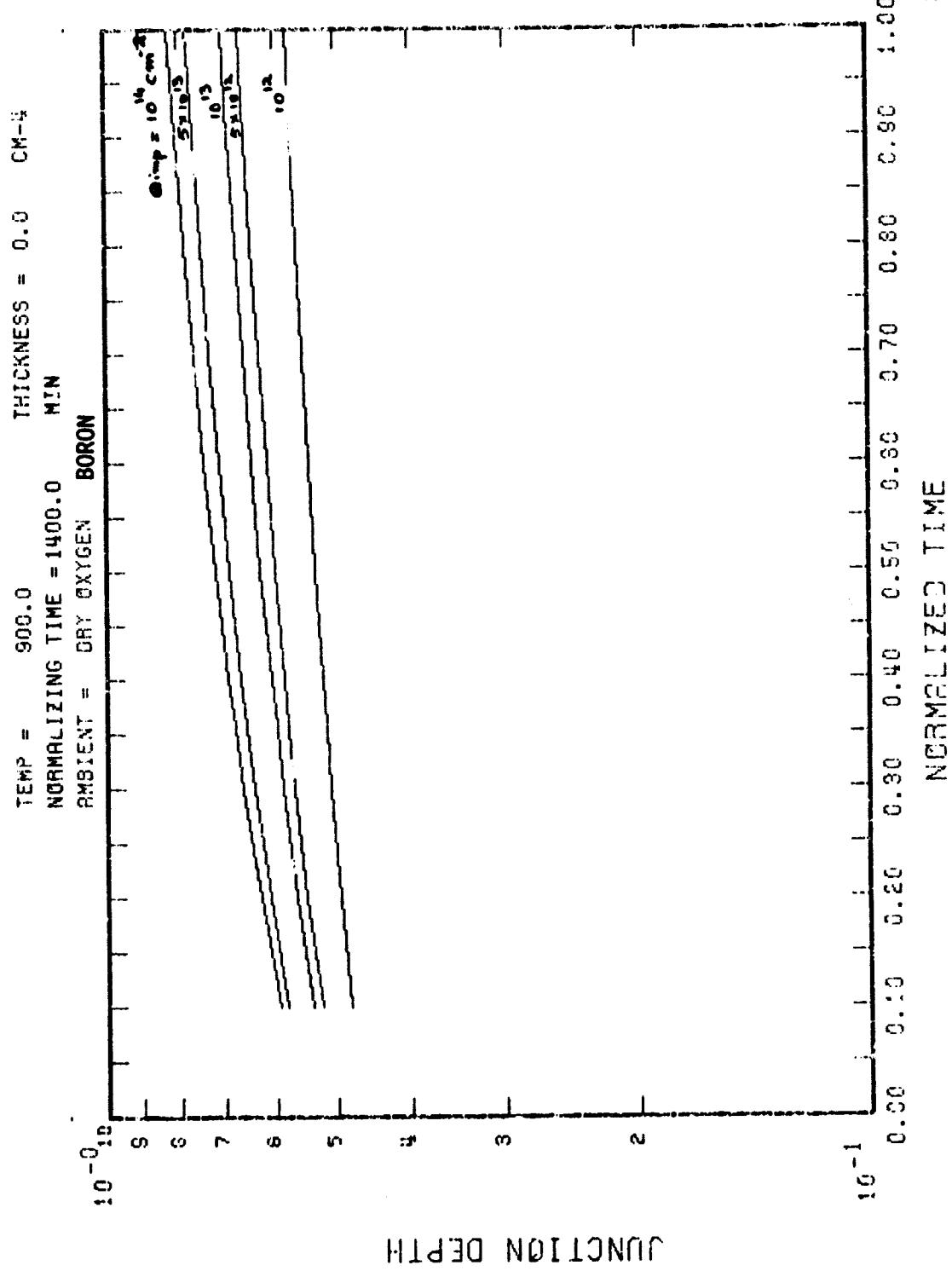


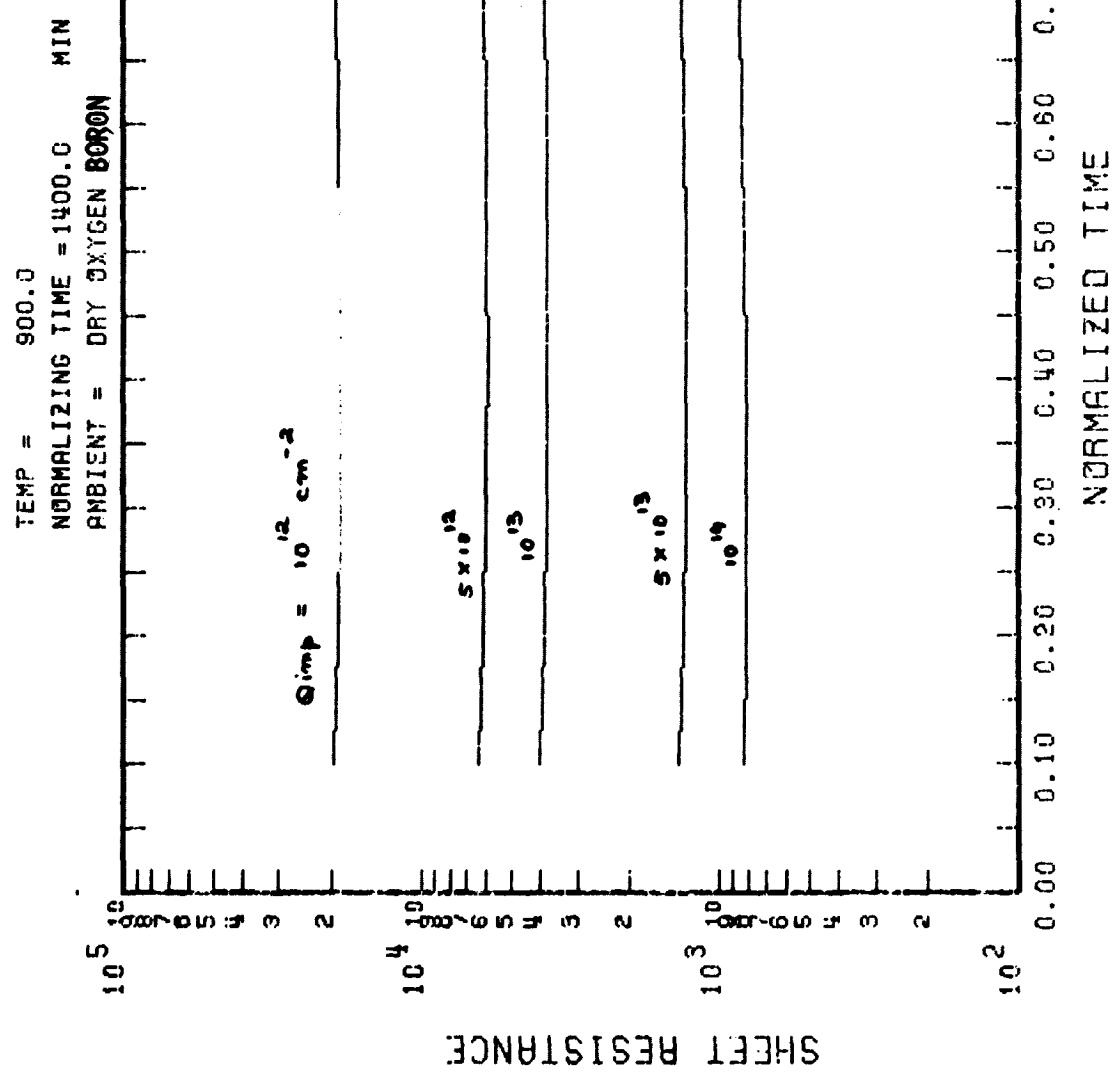


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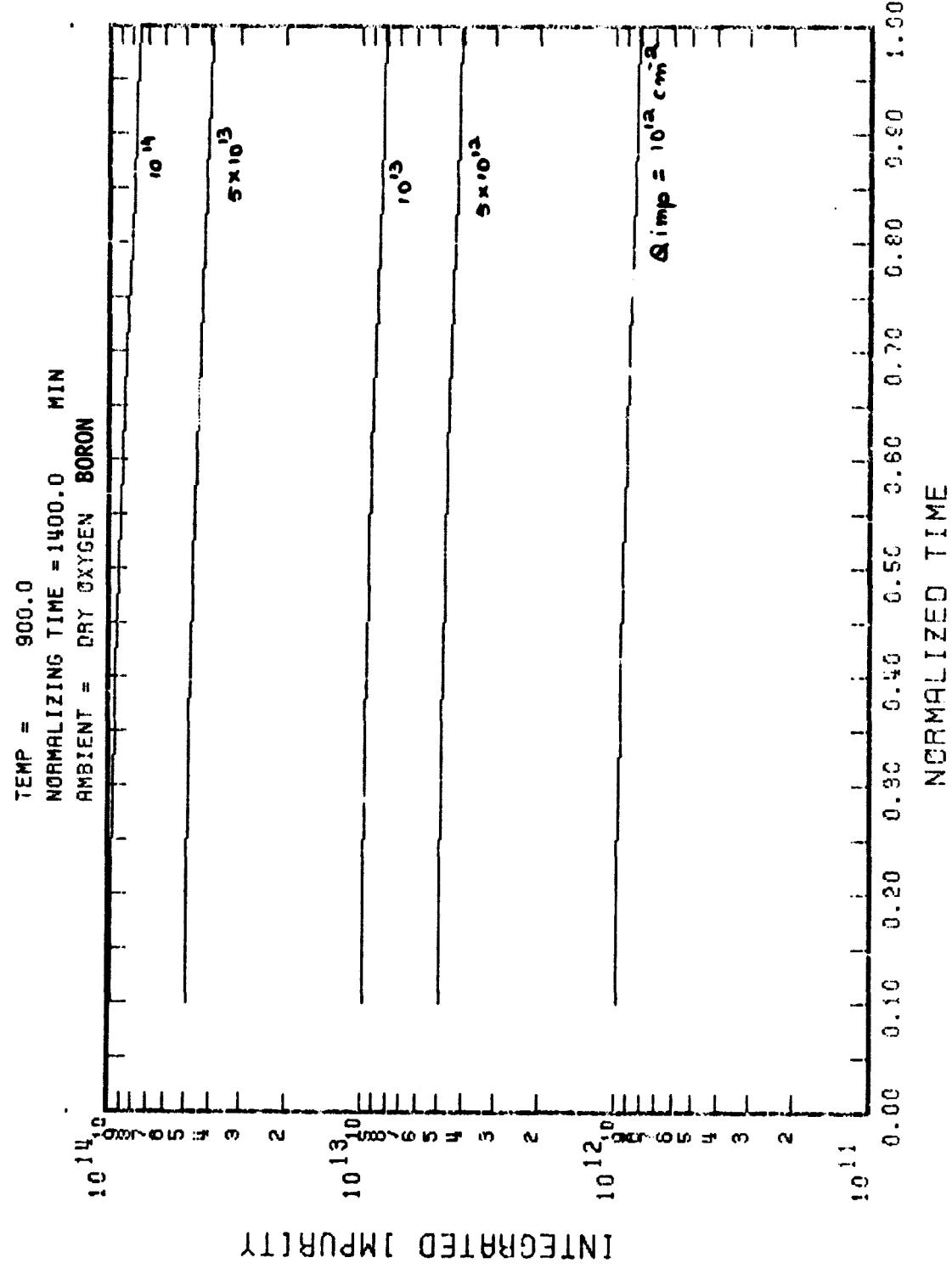


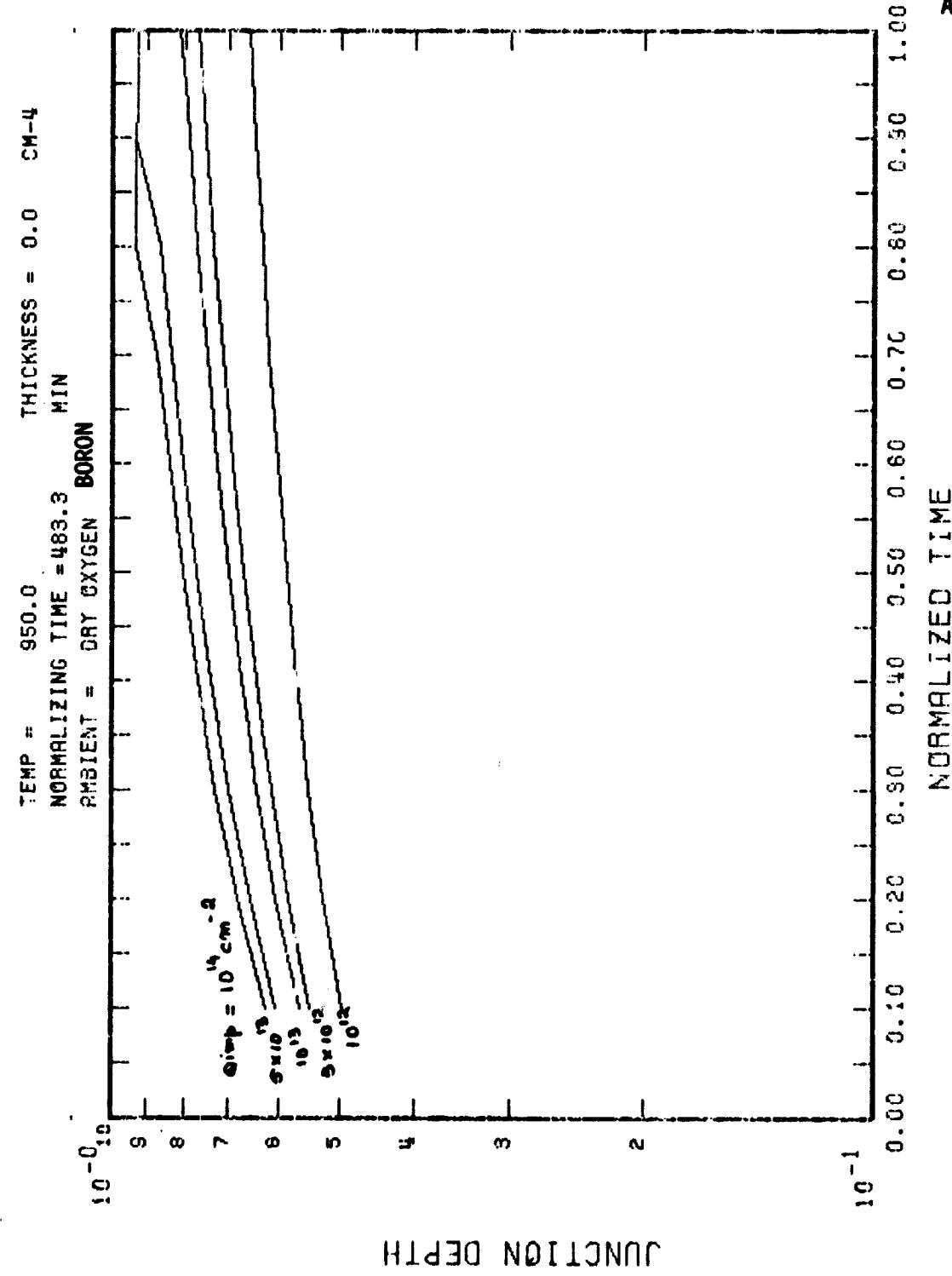




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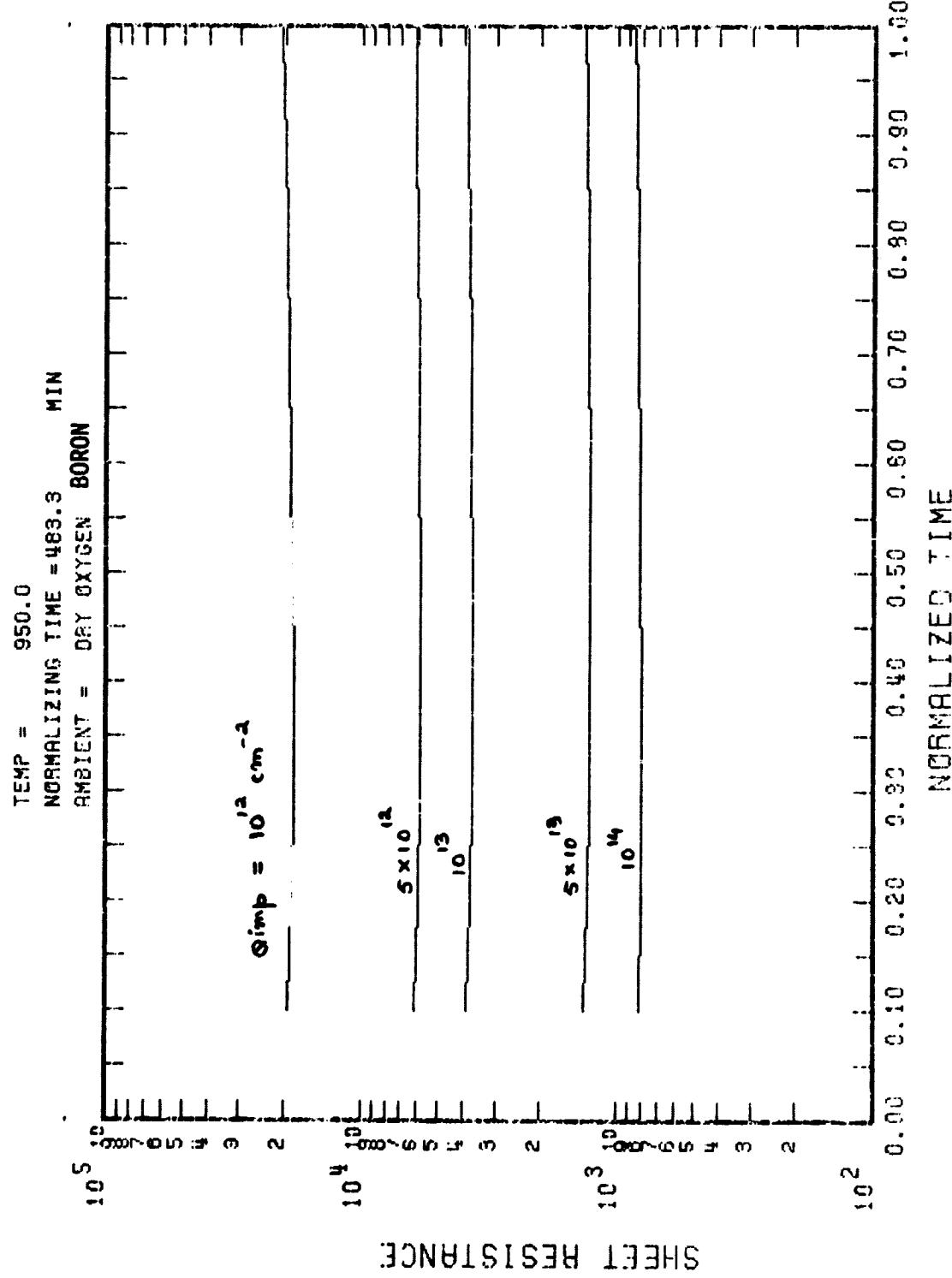
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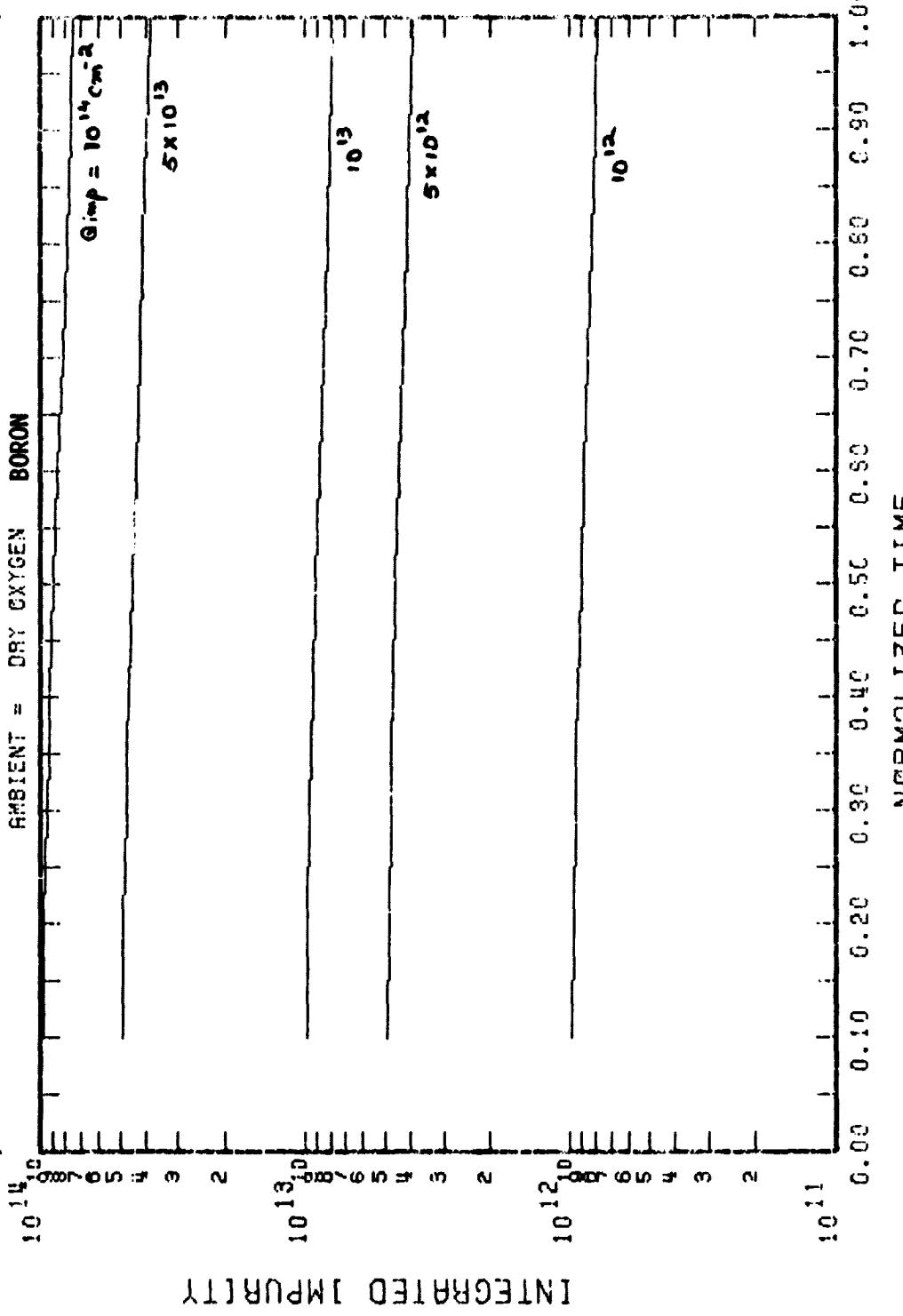
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30

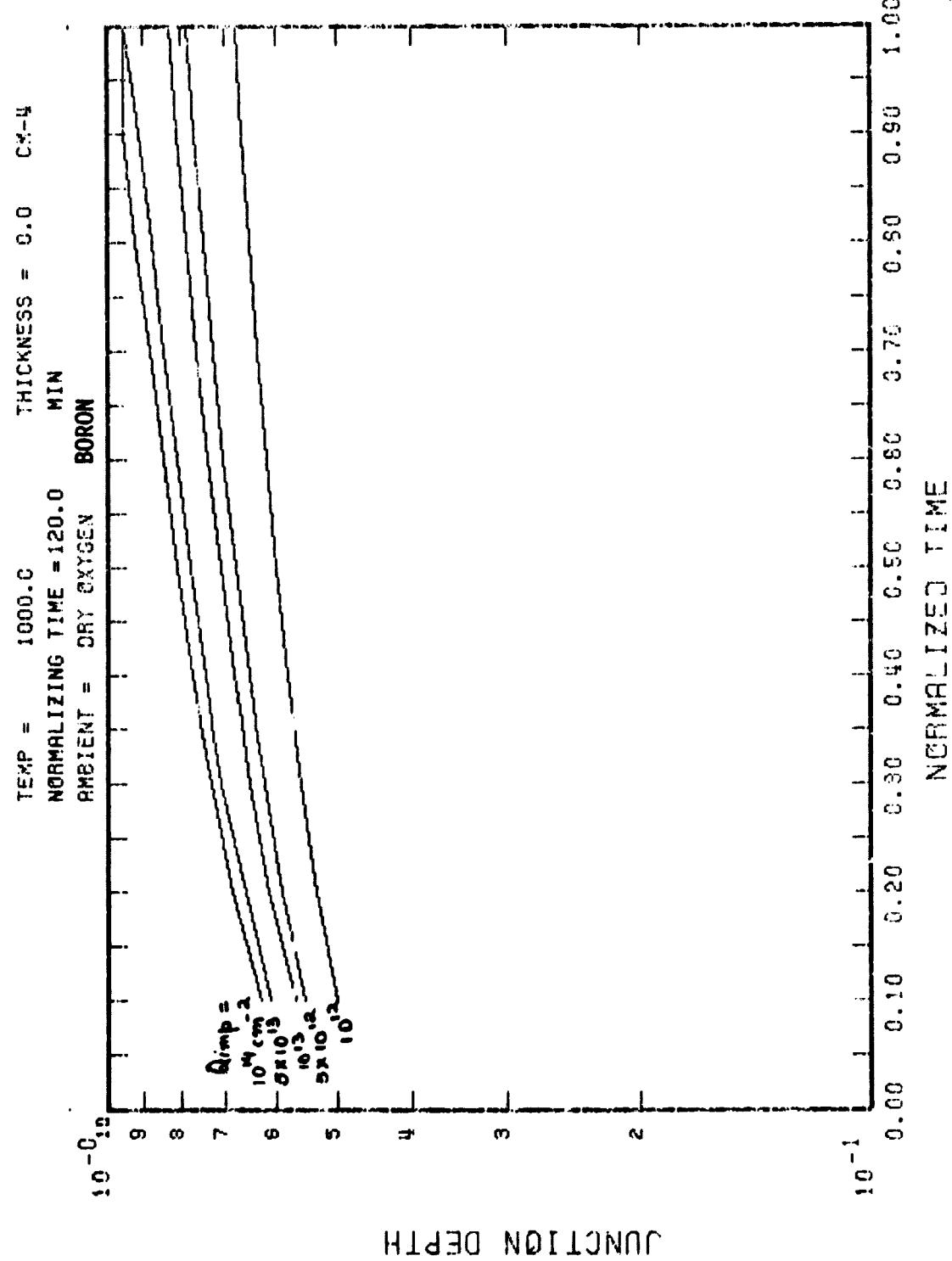
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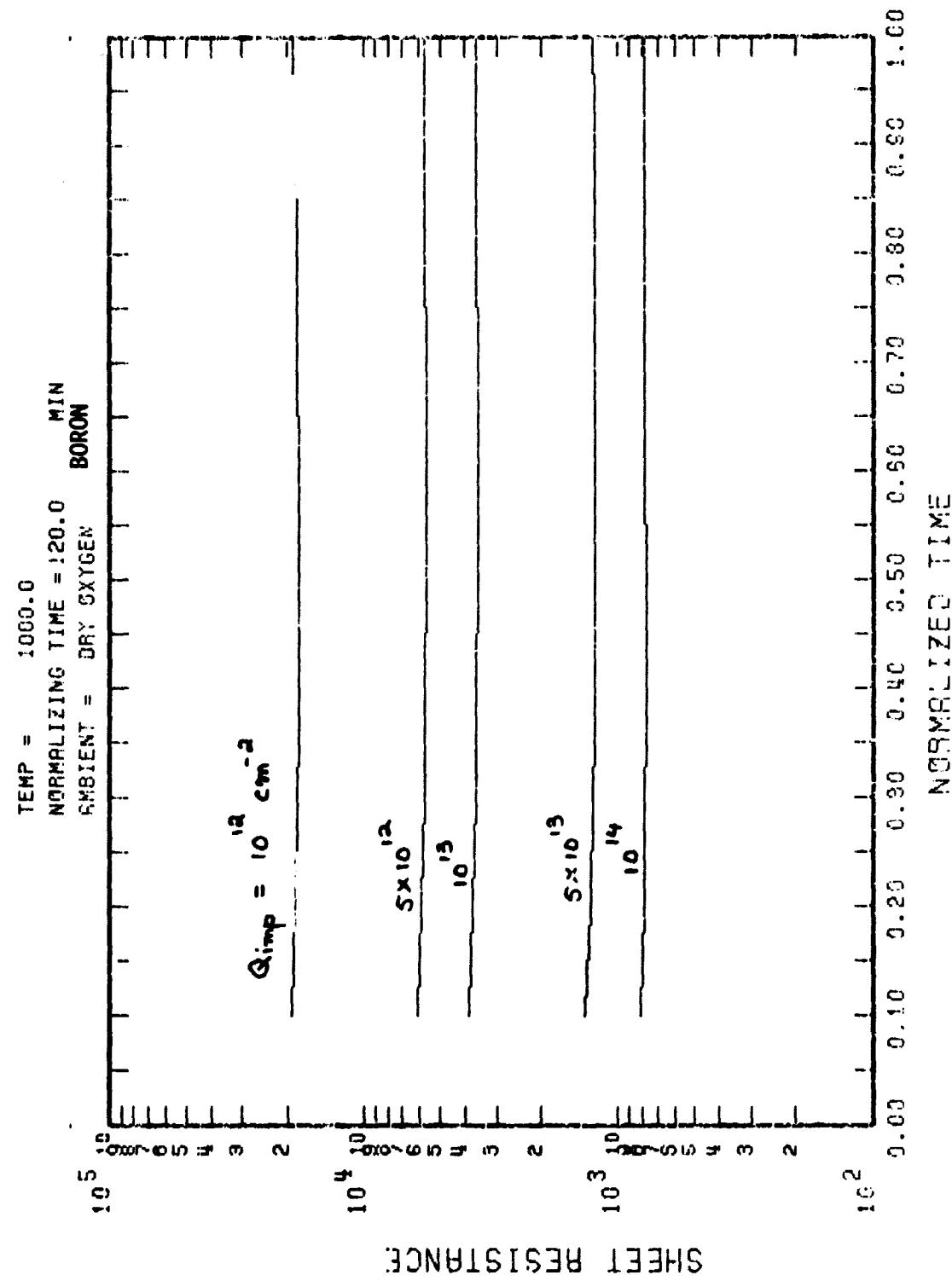


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A 31

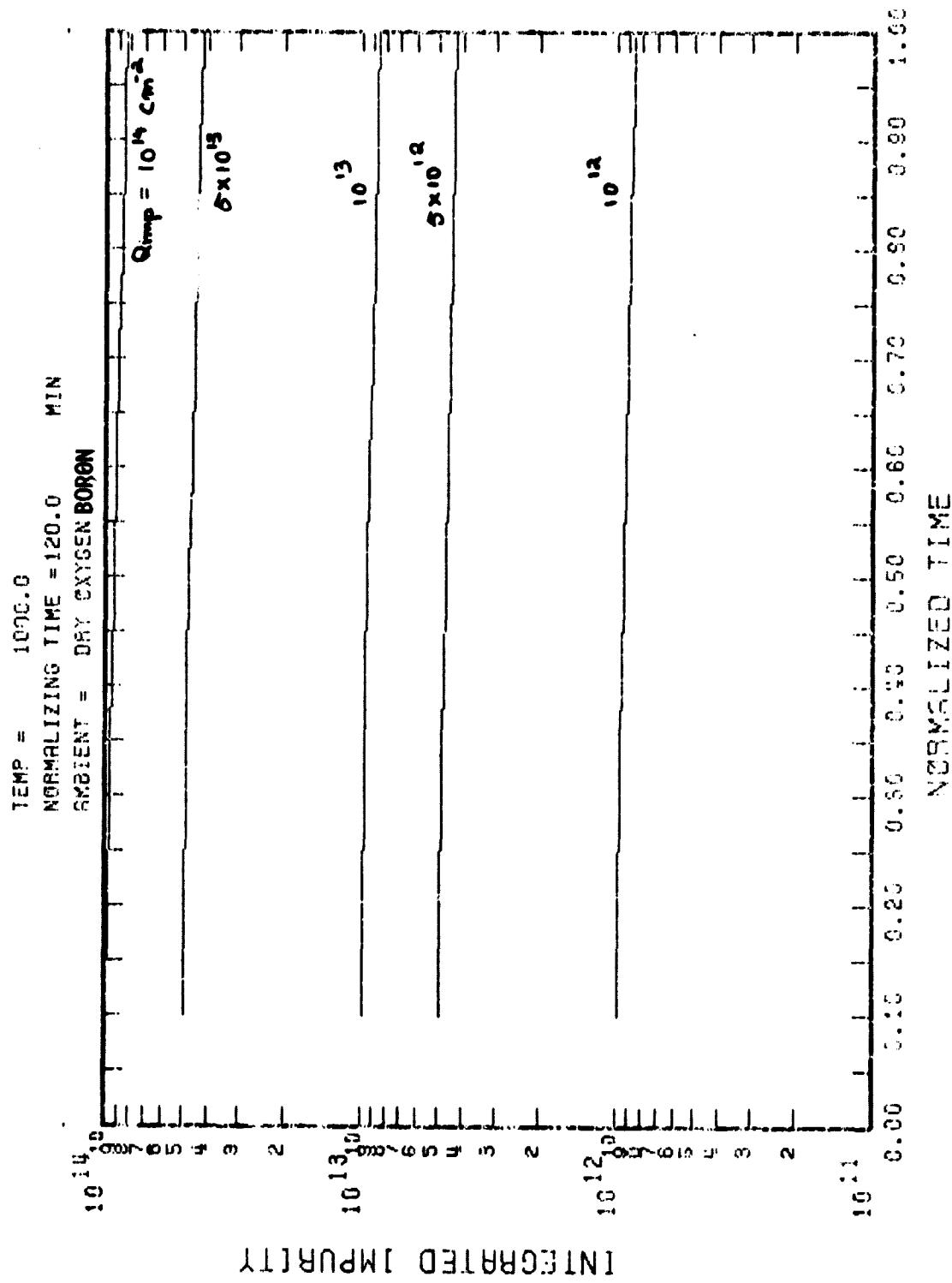


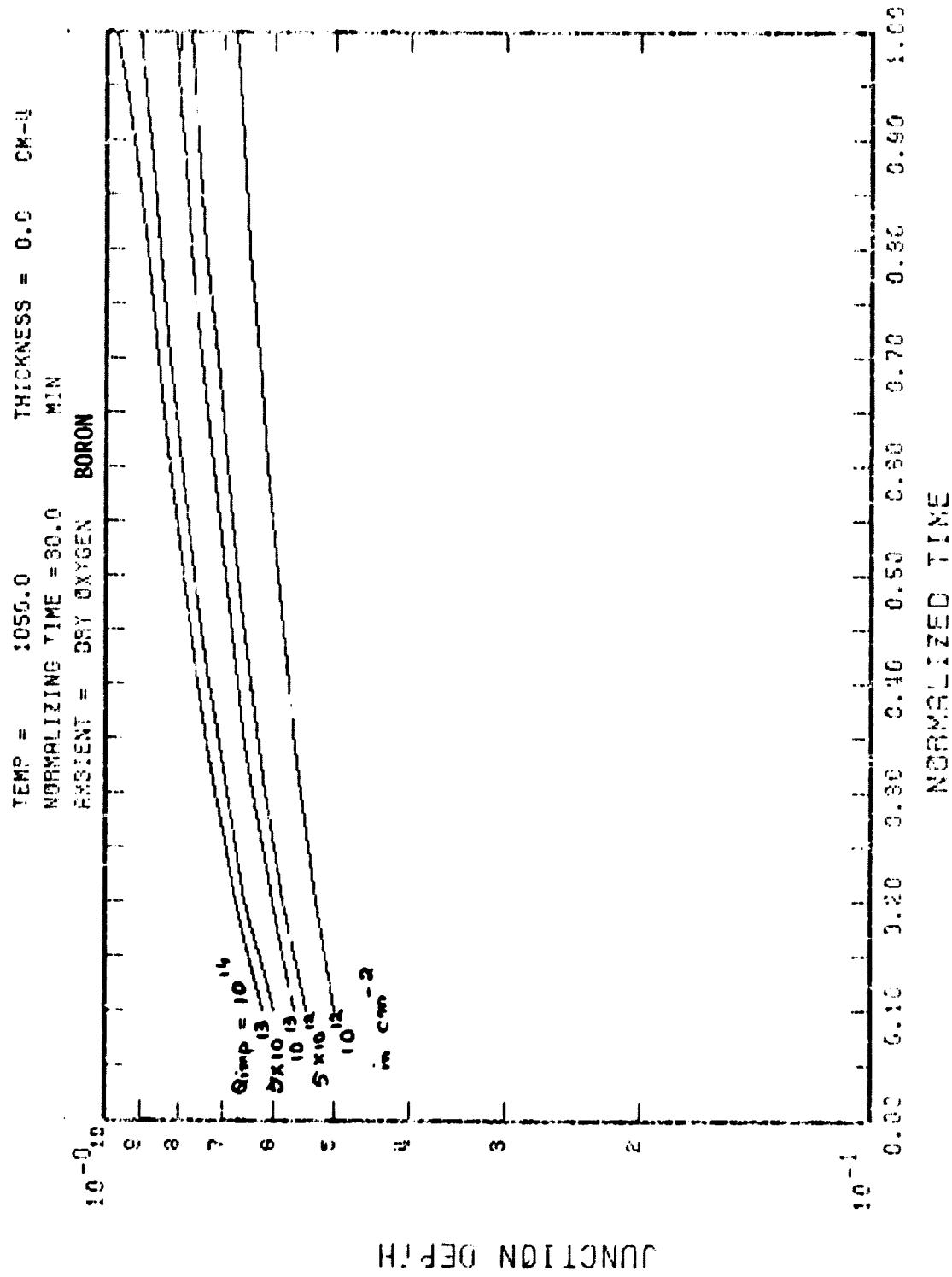
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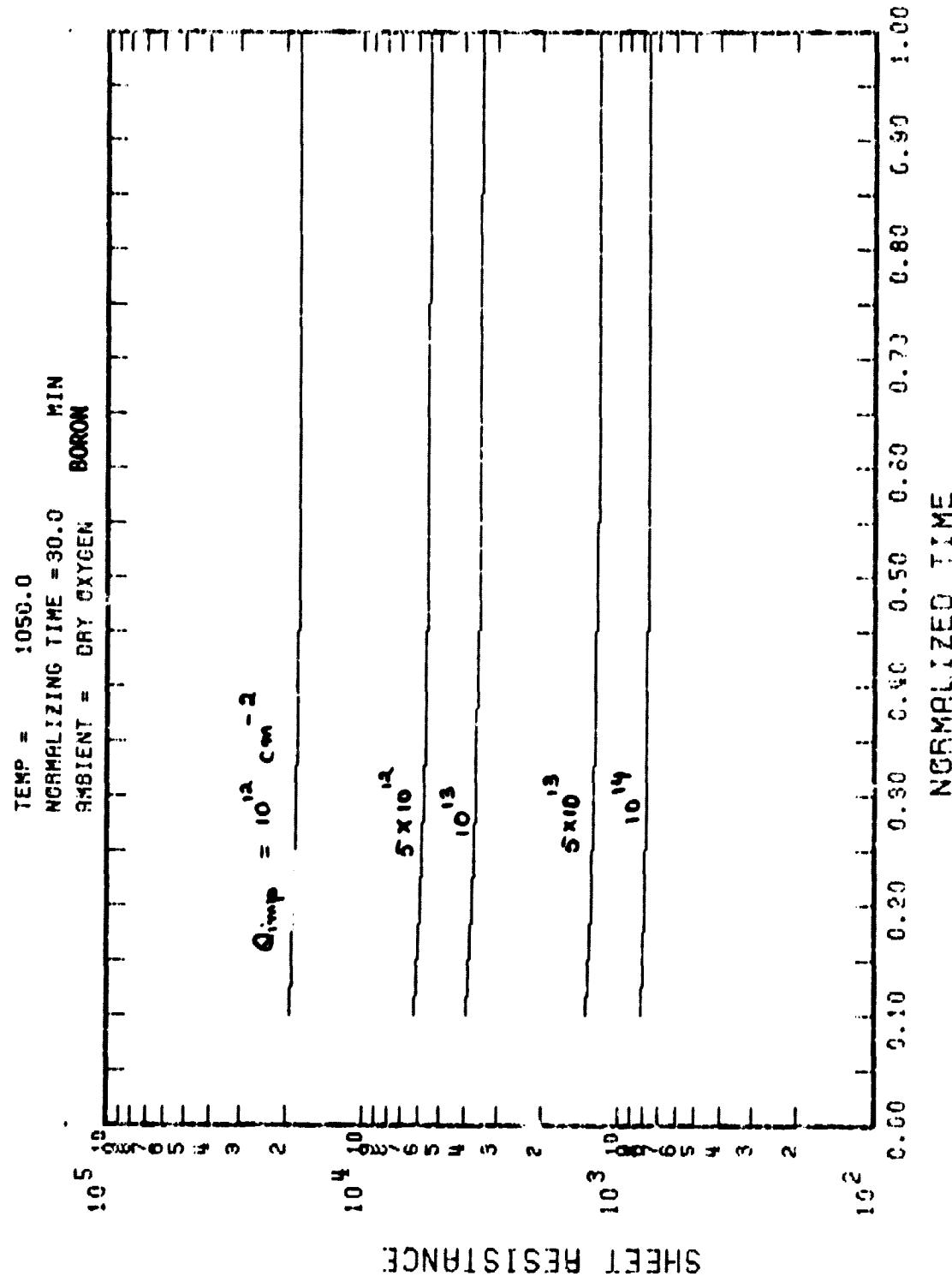
13
A 33





ORIGINAL PAGE IS
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A 35



TEMP = 1050.0 NORMALIZING TIME = 30.0 MIN
AMBIENT = DRY OXYGEN BORON

EDITORIAL

5×10^{13}

39

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10

19.1 0.00 0.10 0.20 0.30 0.40 0.50 0.60 0.70 0.80 0.90 1.00

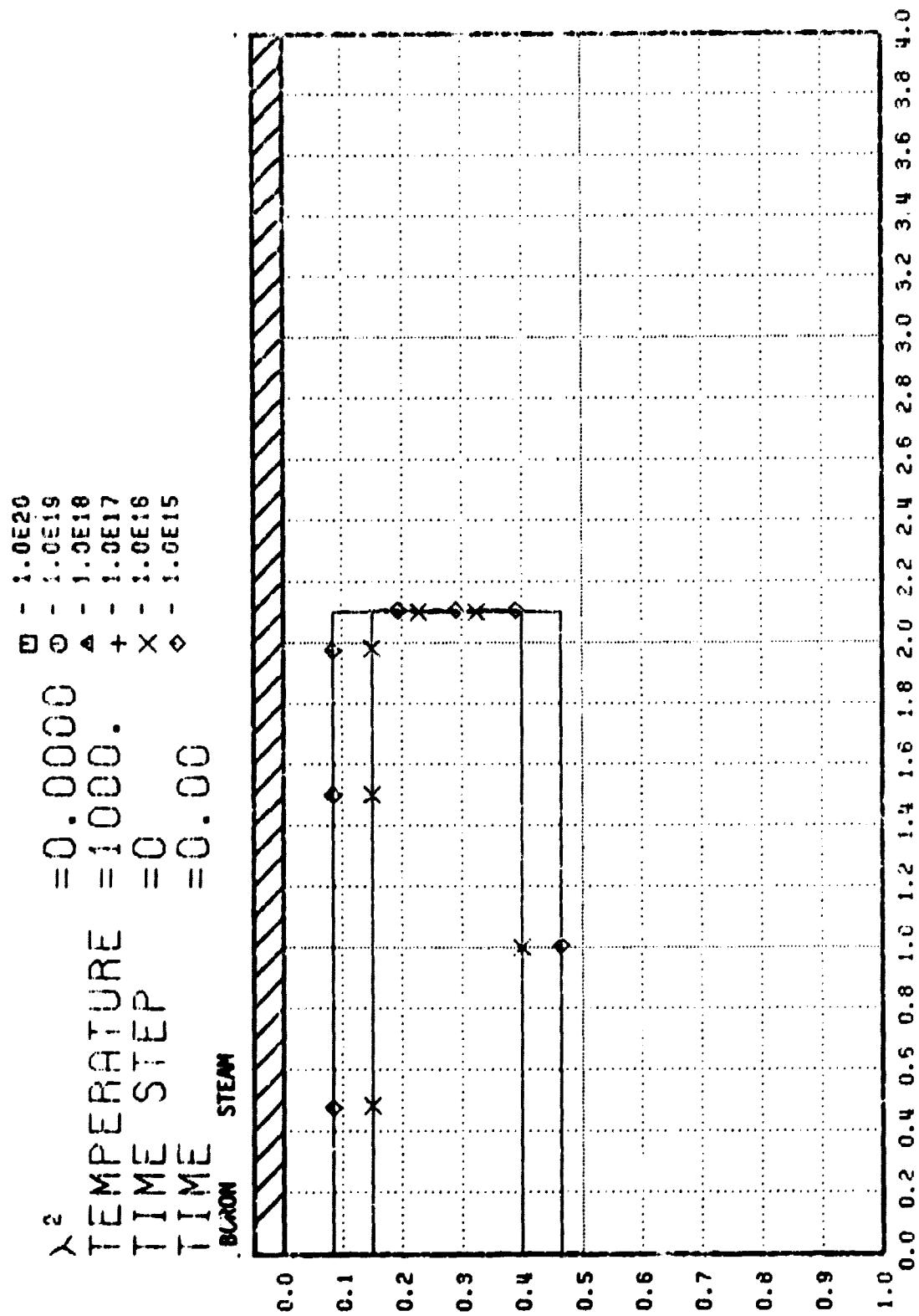
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A 36

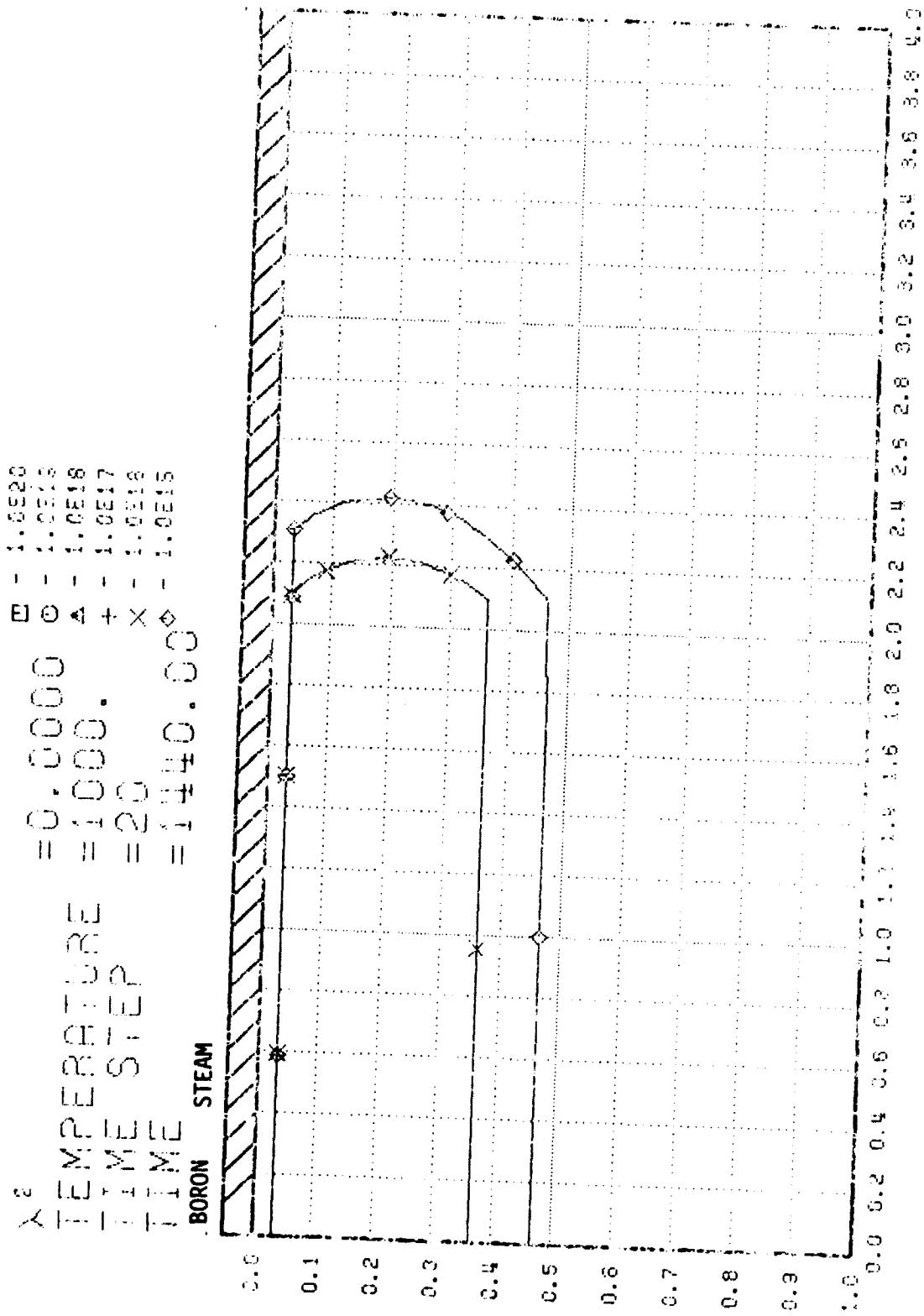
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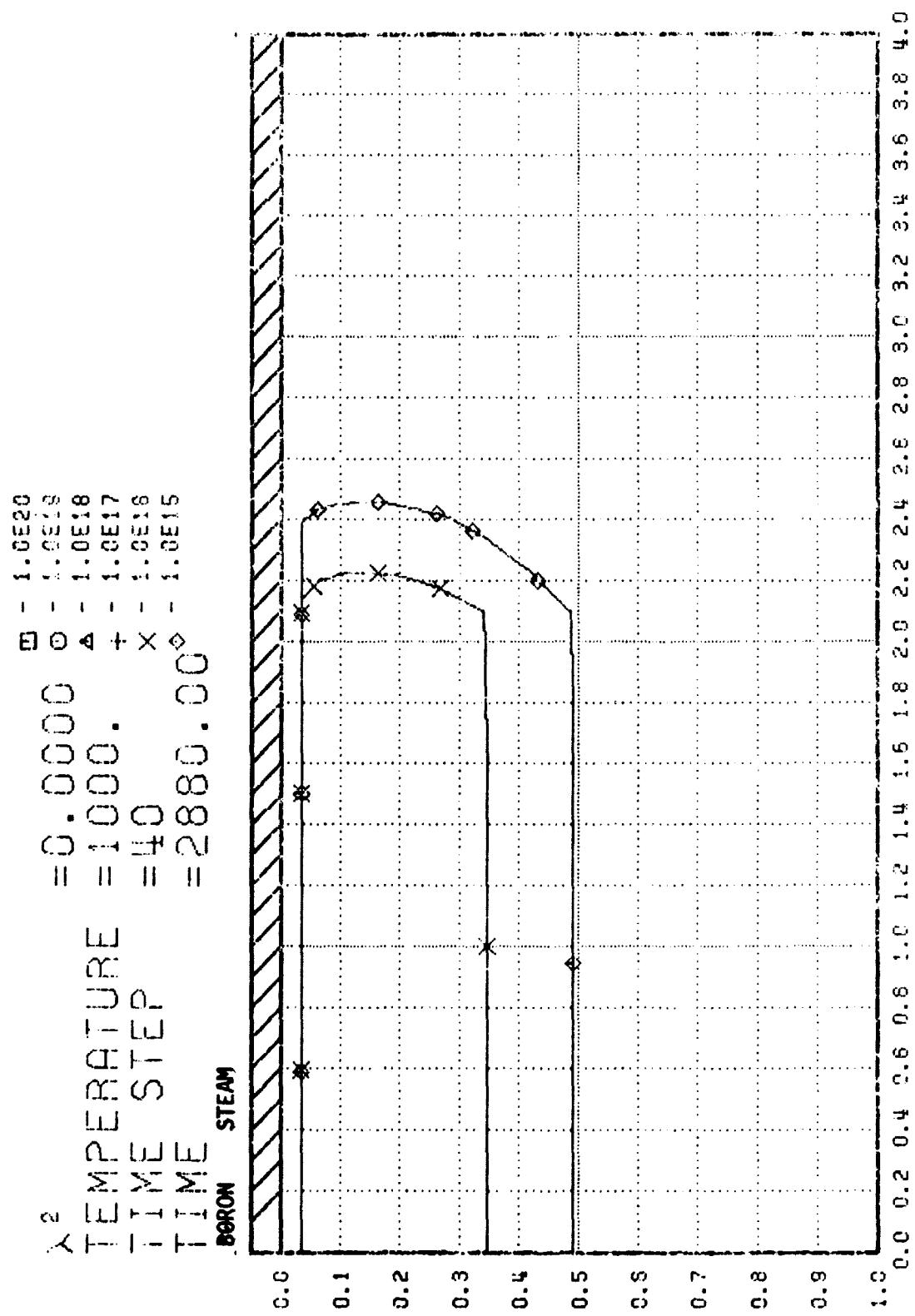
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A 37



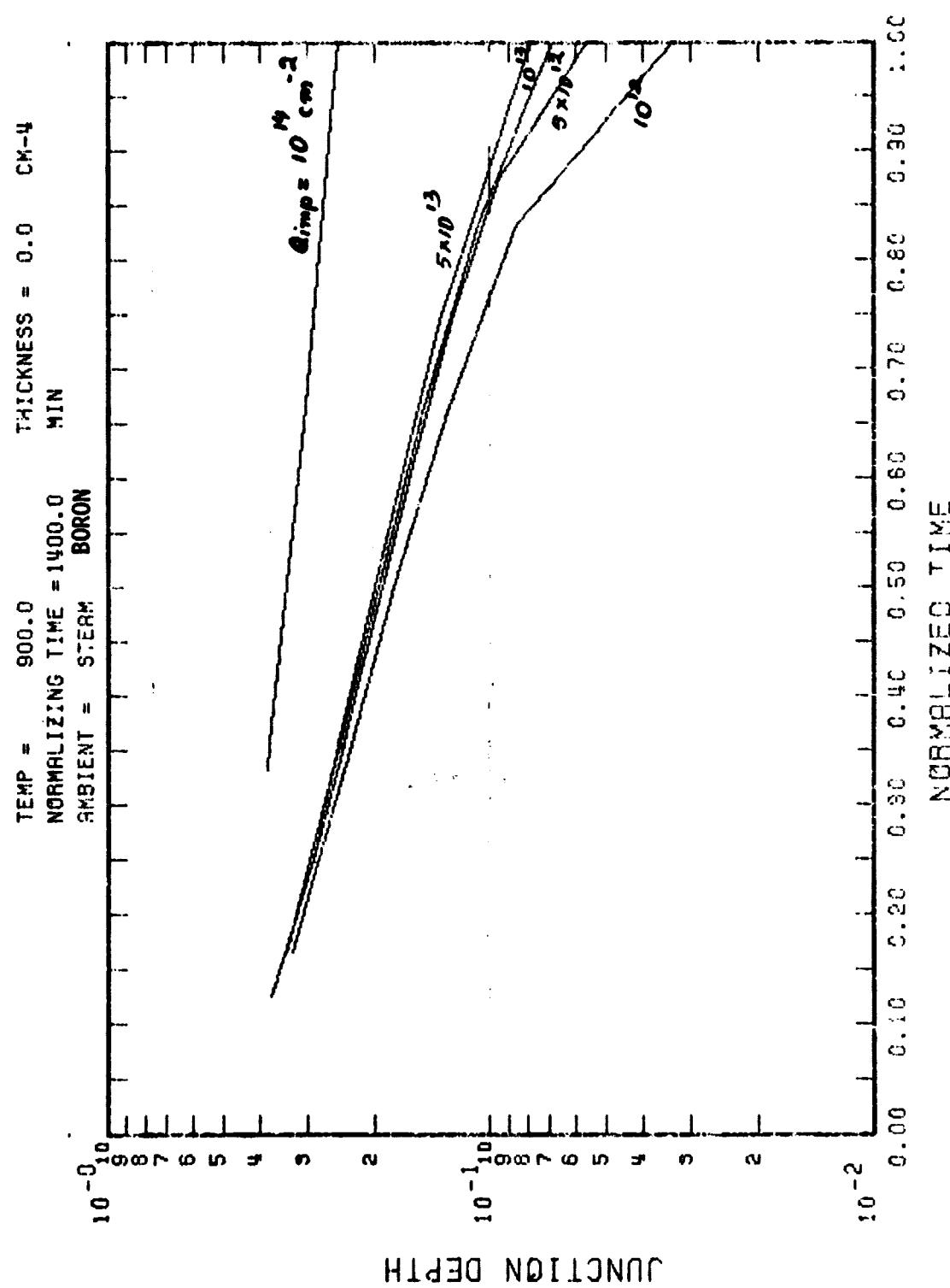
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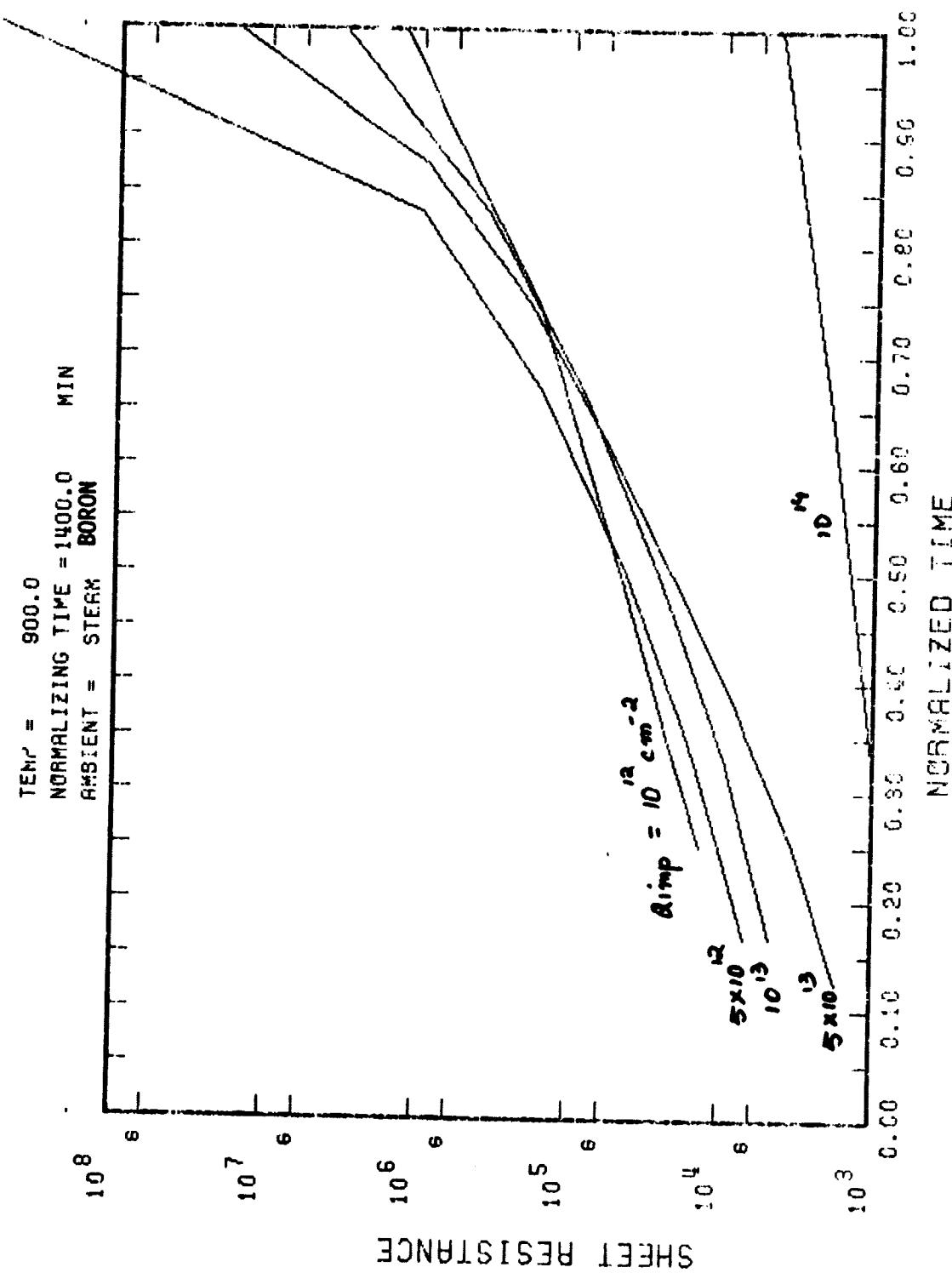




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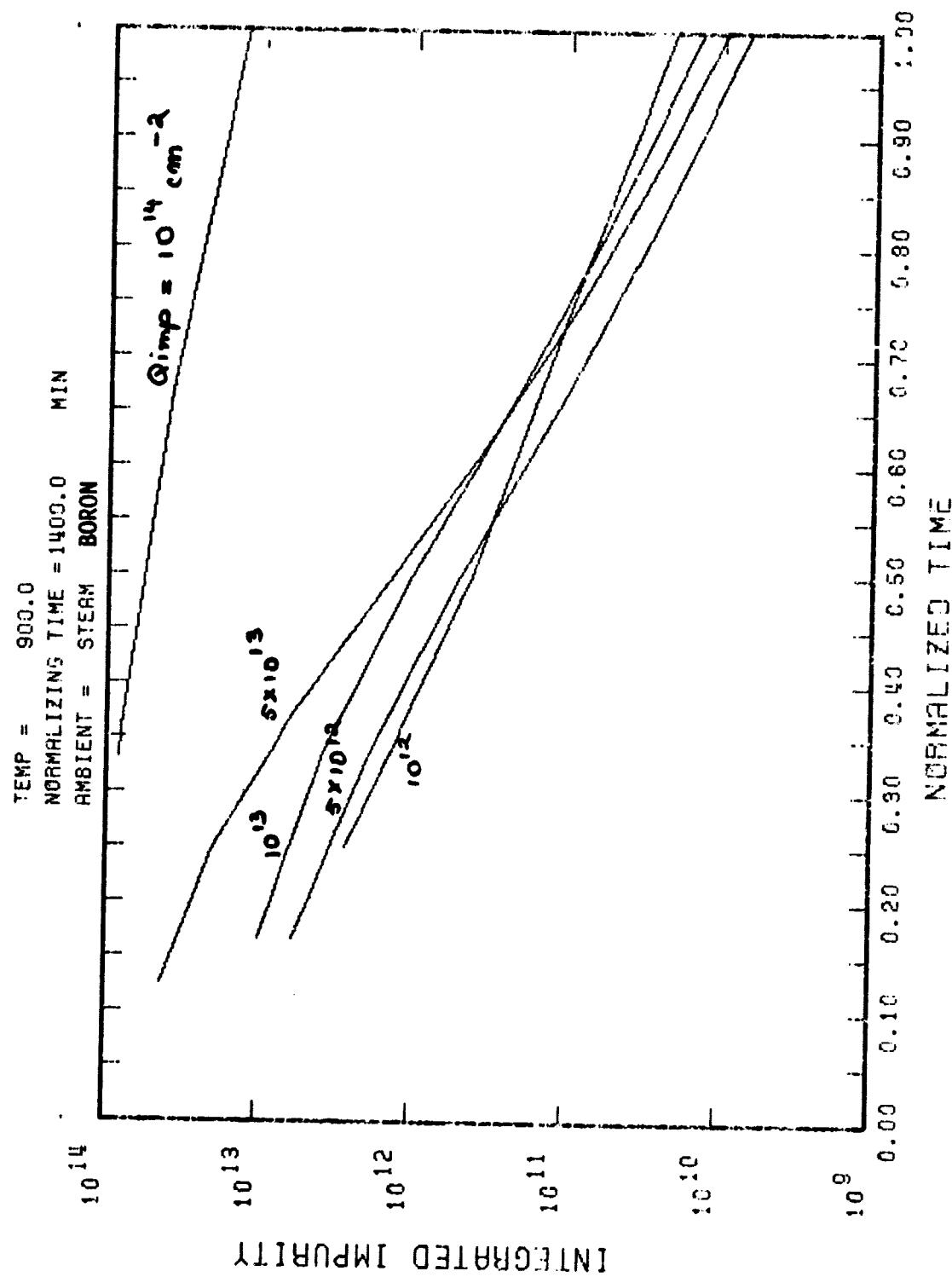
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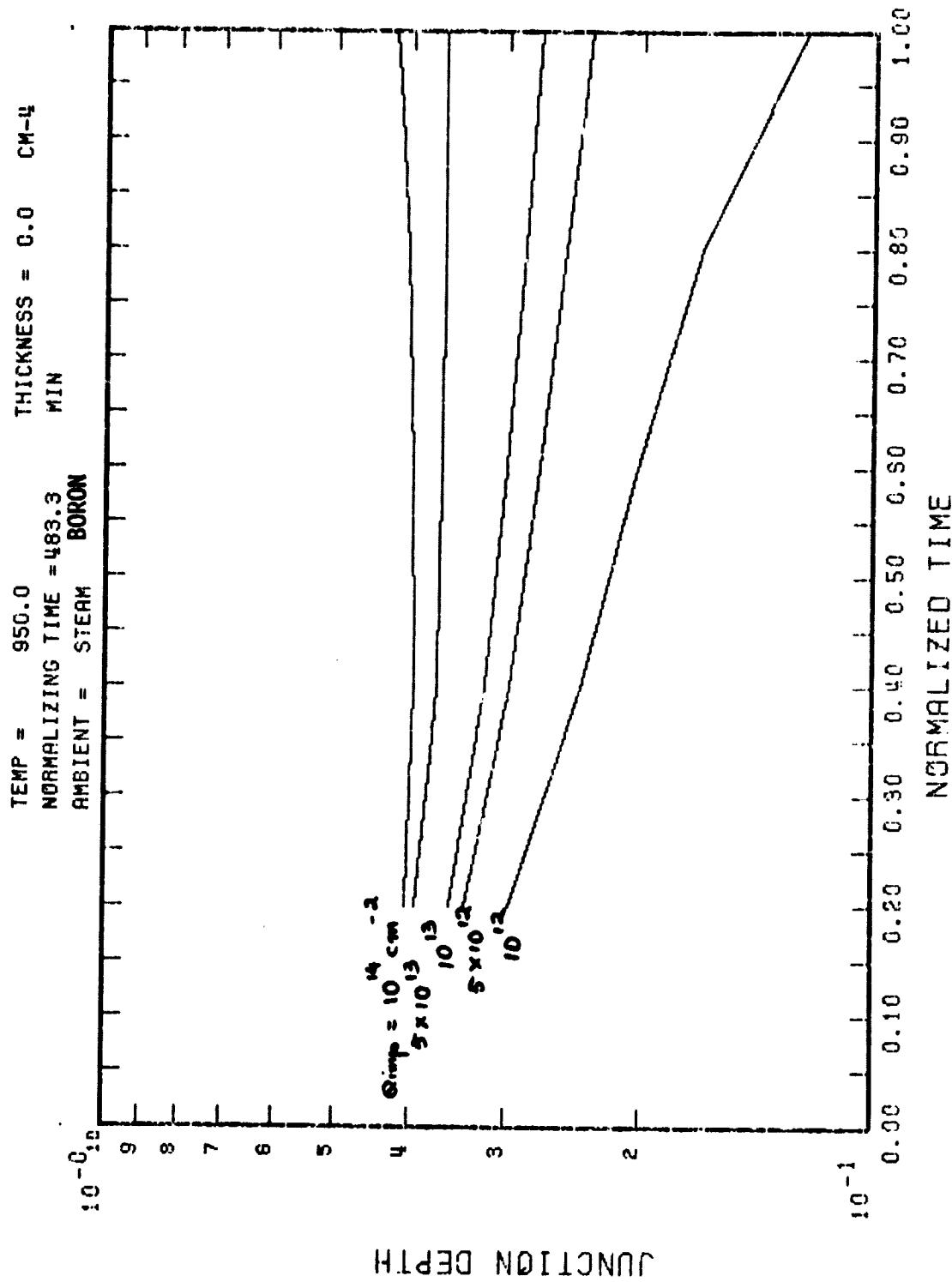


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A 42

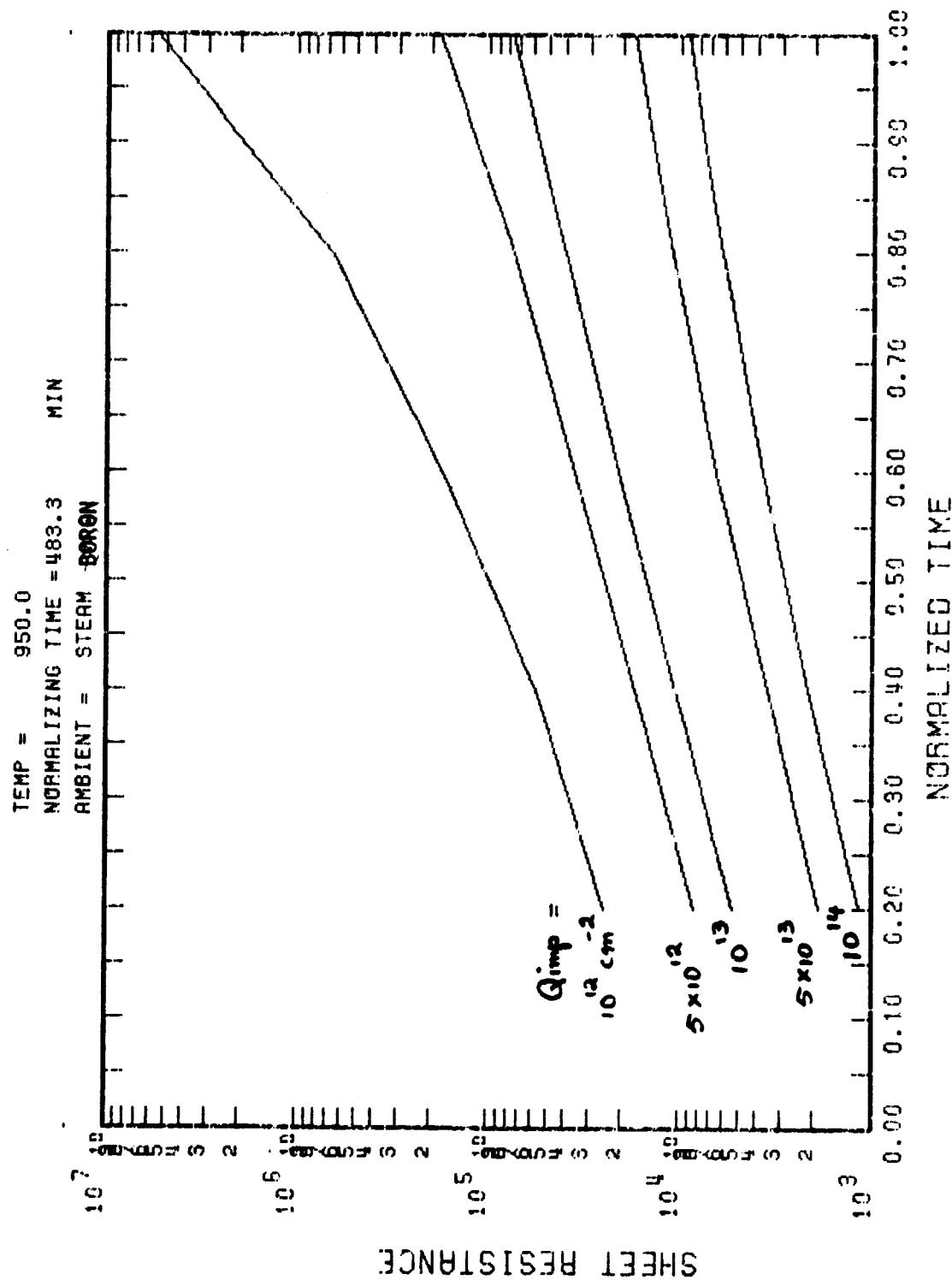


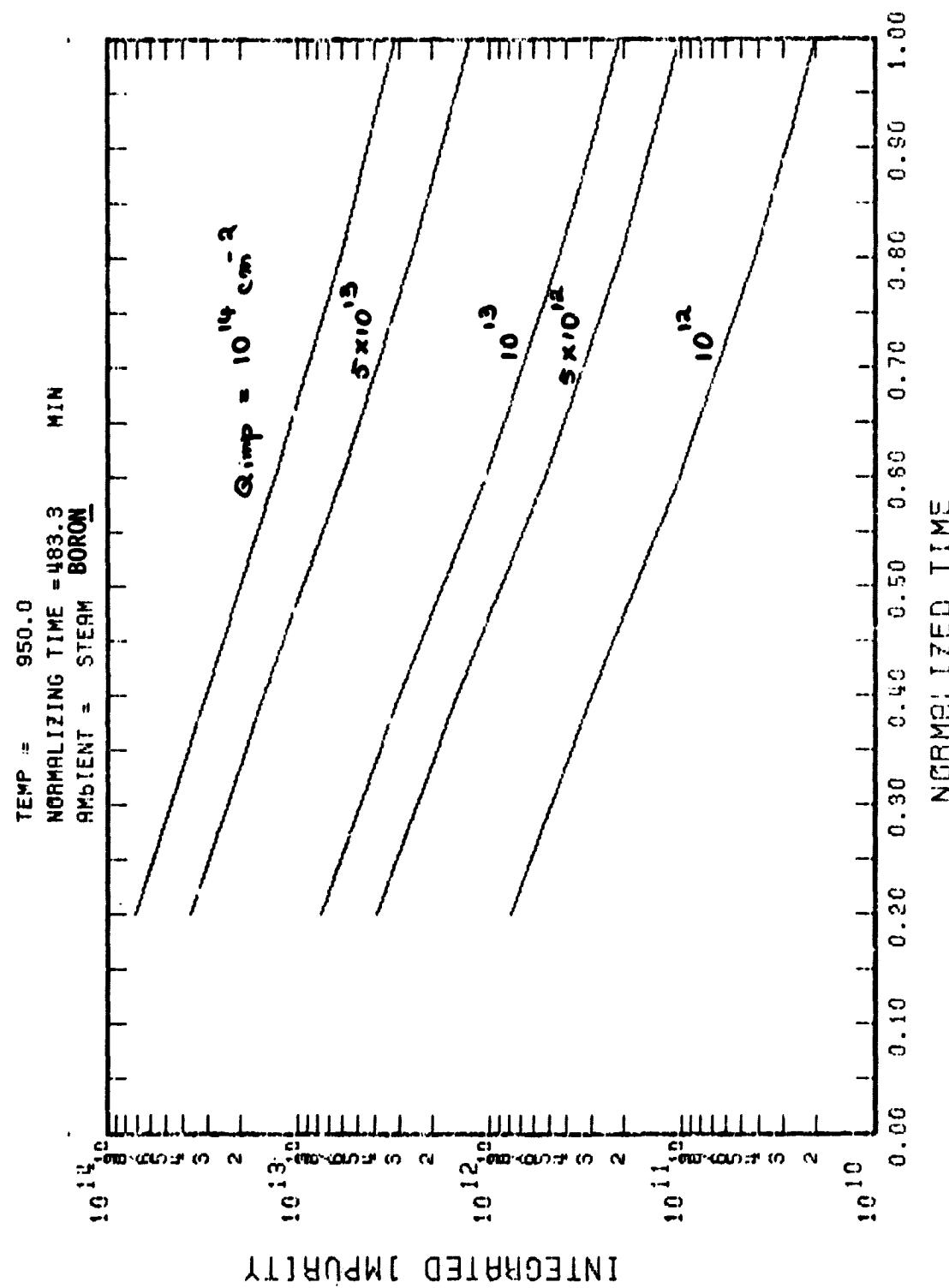
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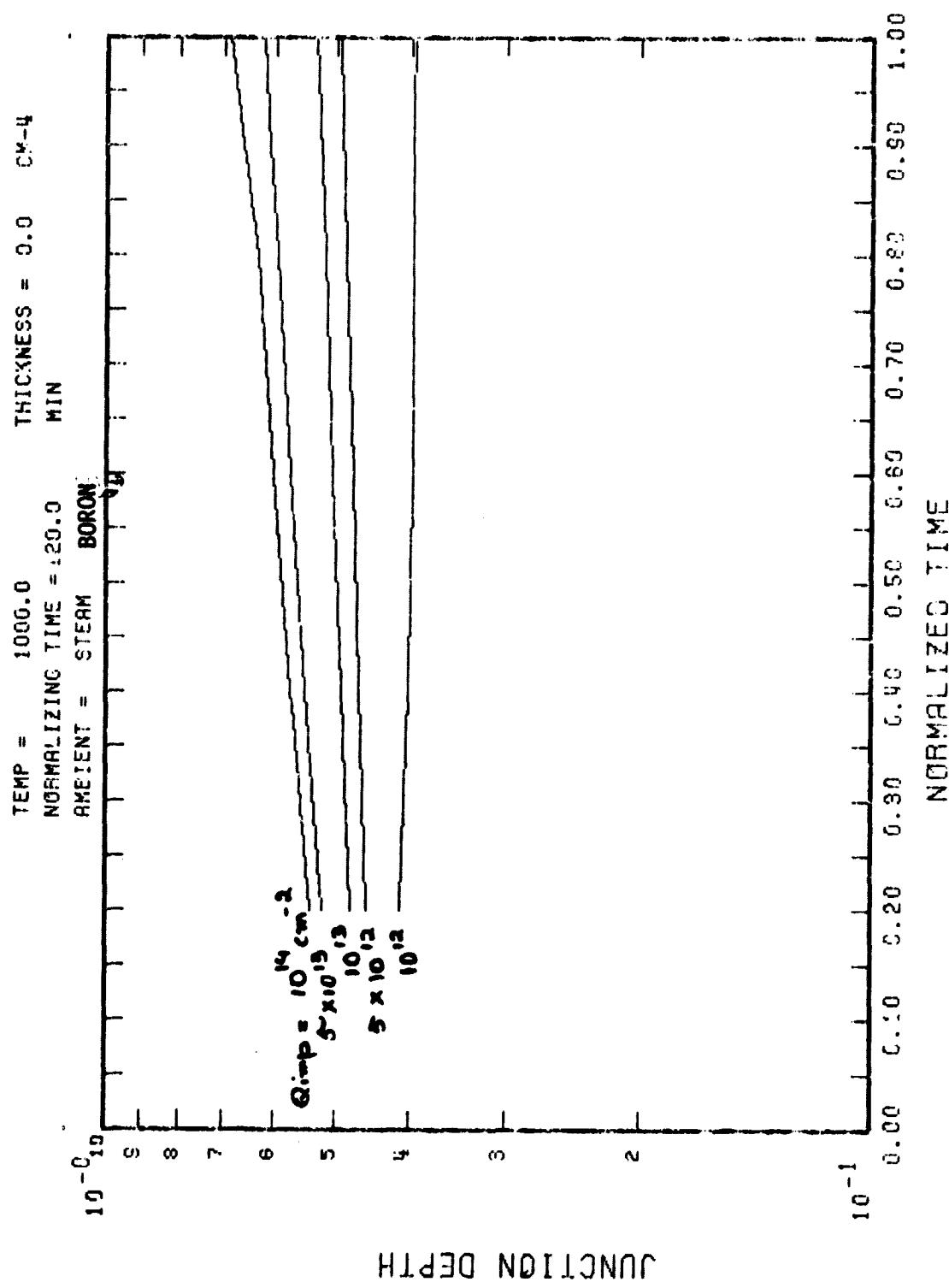
A 44



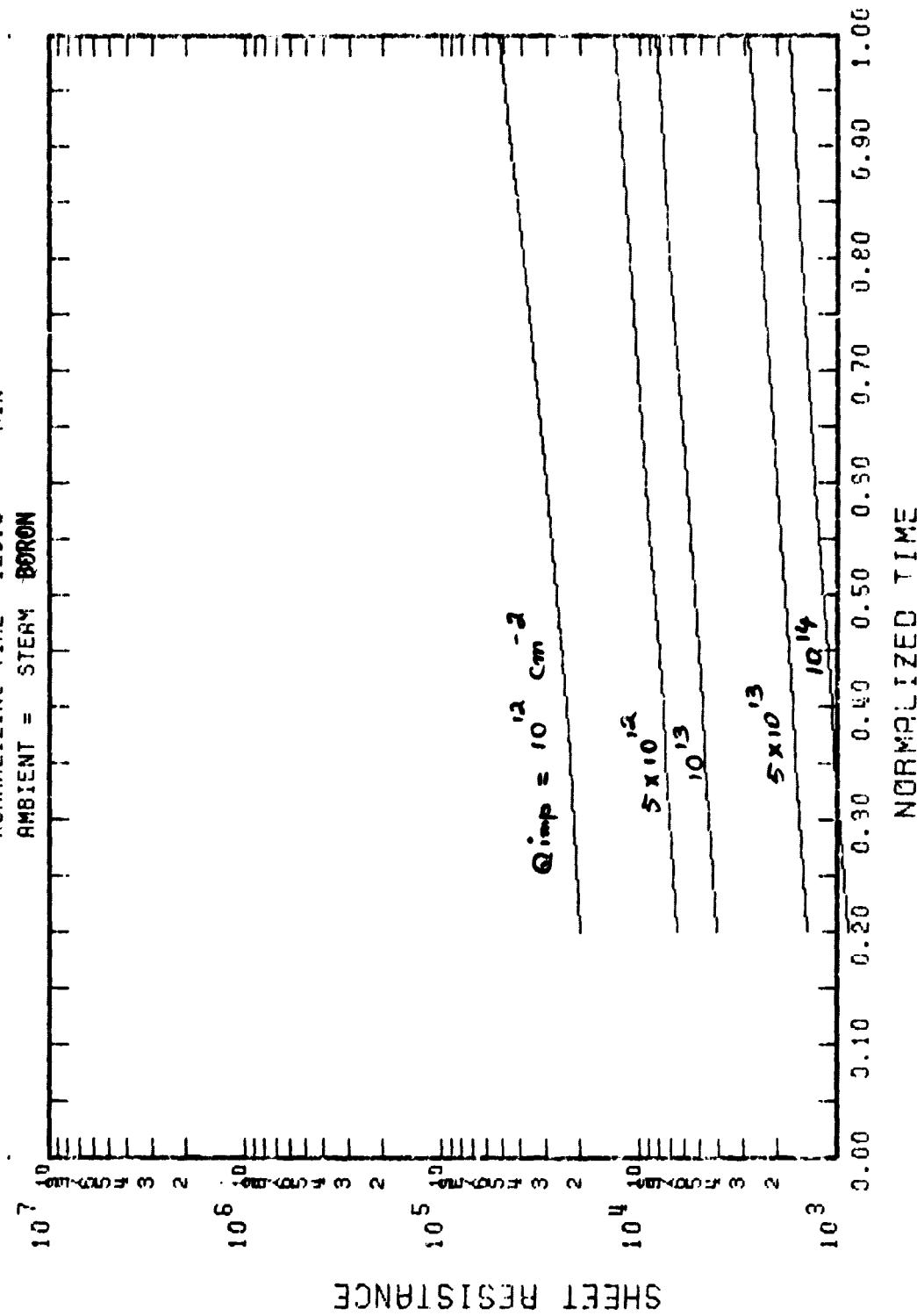


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A 46

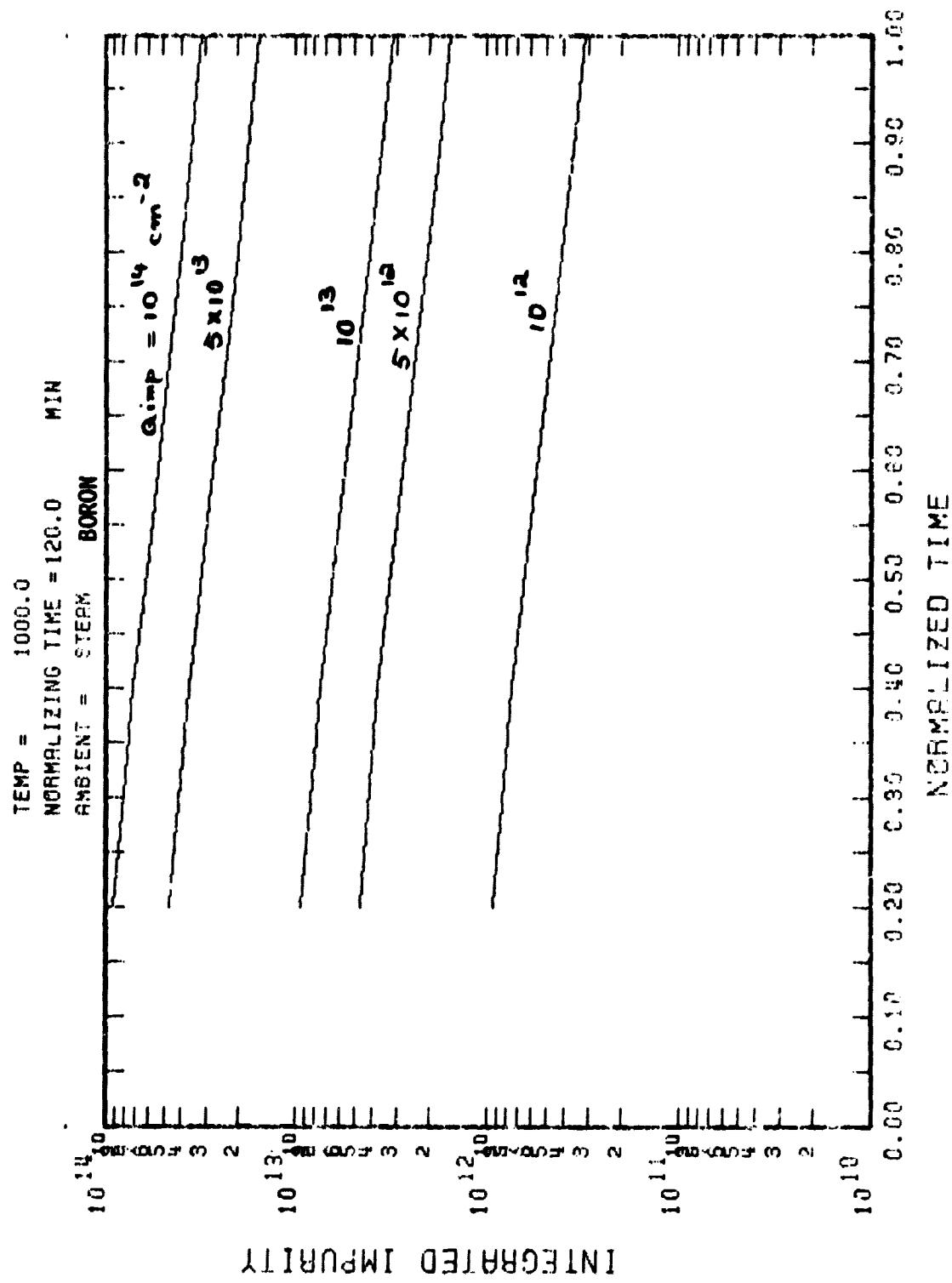


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AMBIENT = STERN BORON

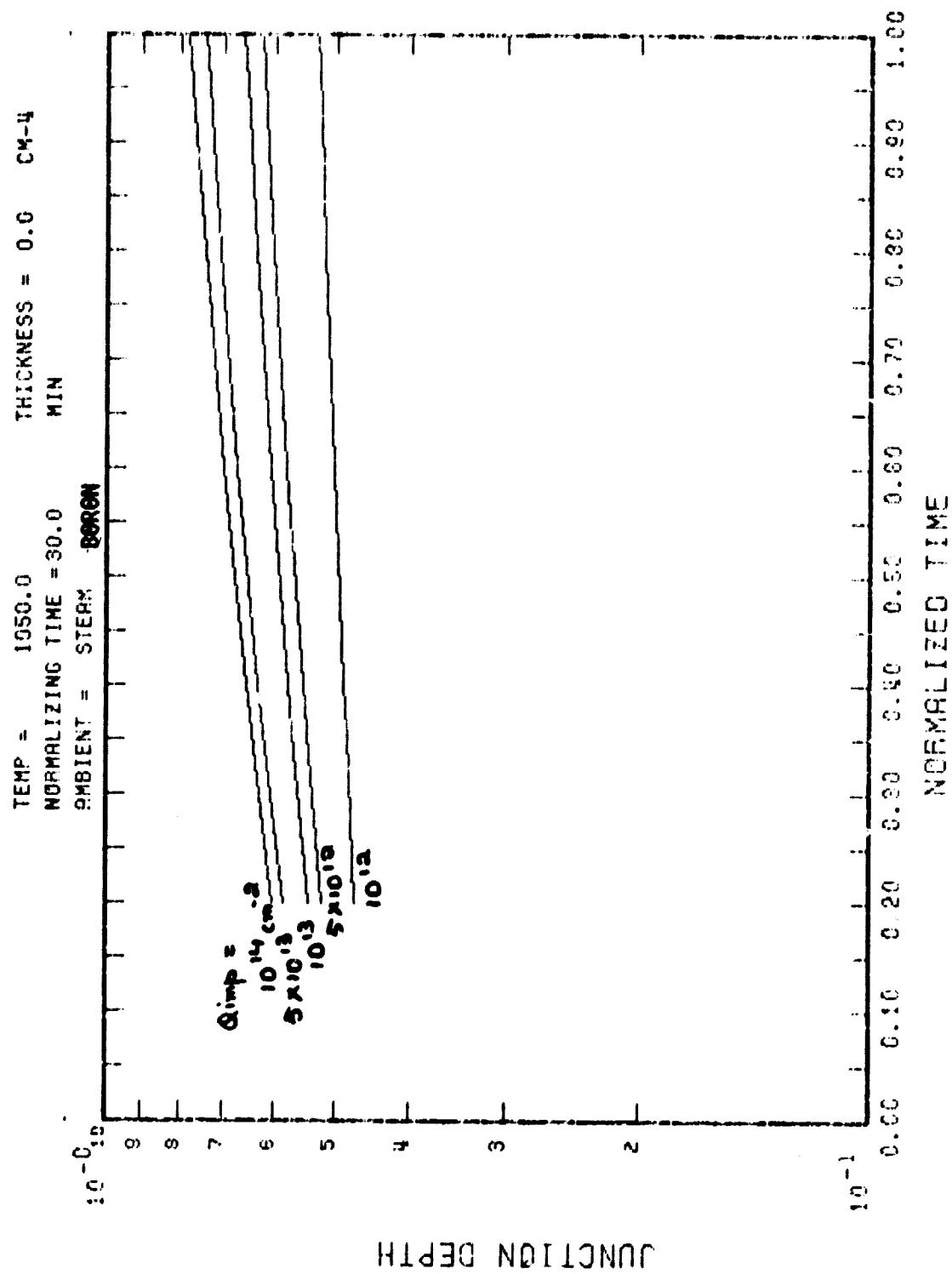


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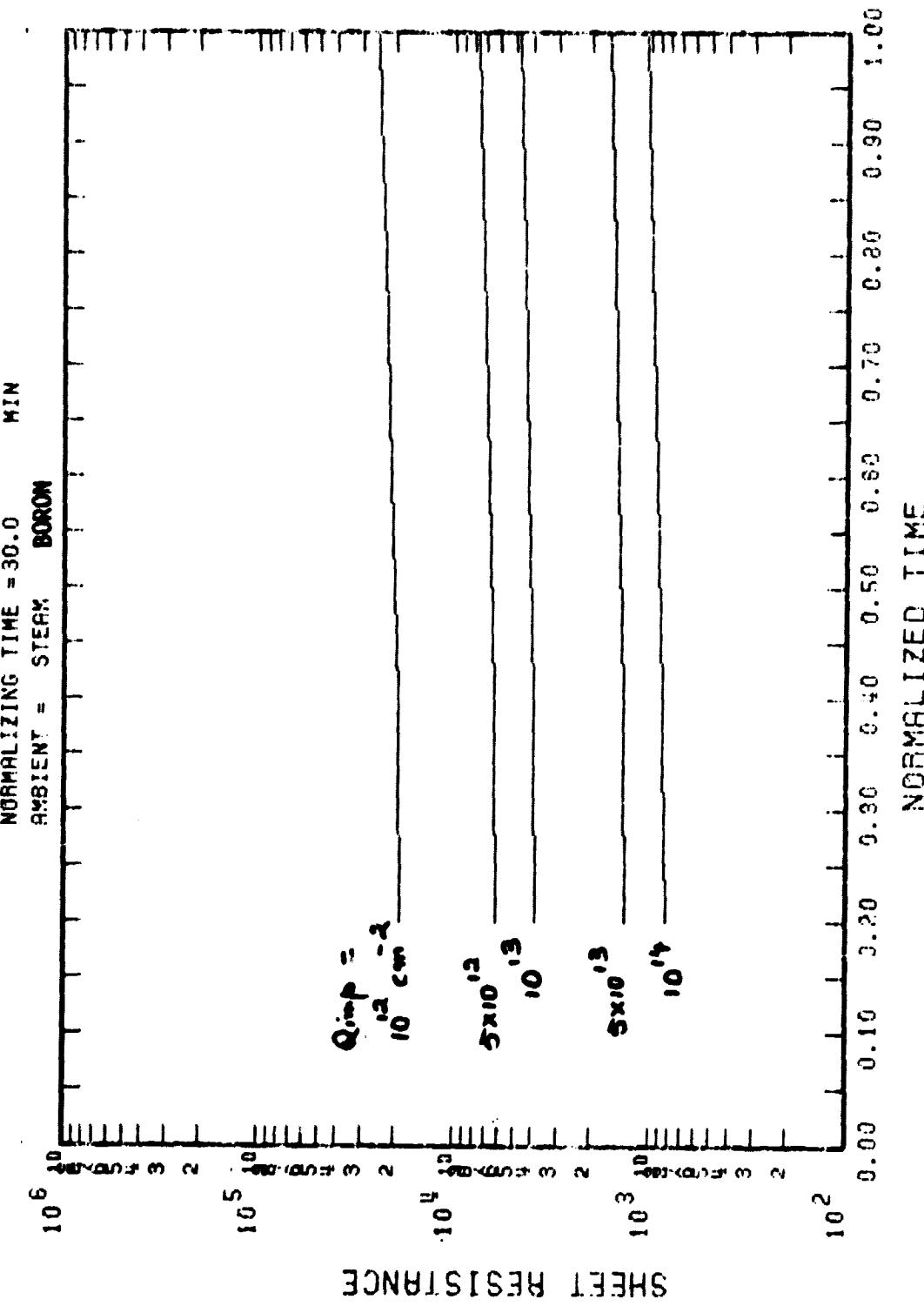
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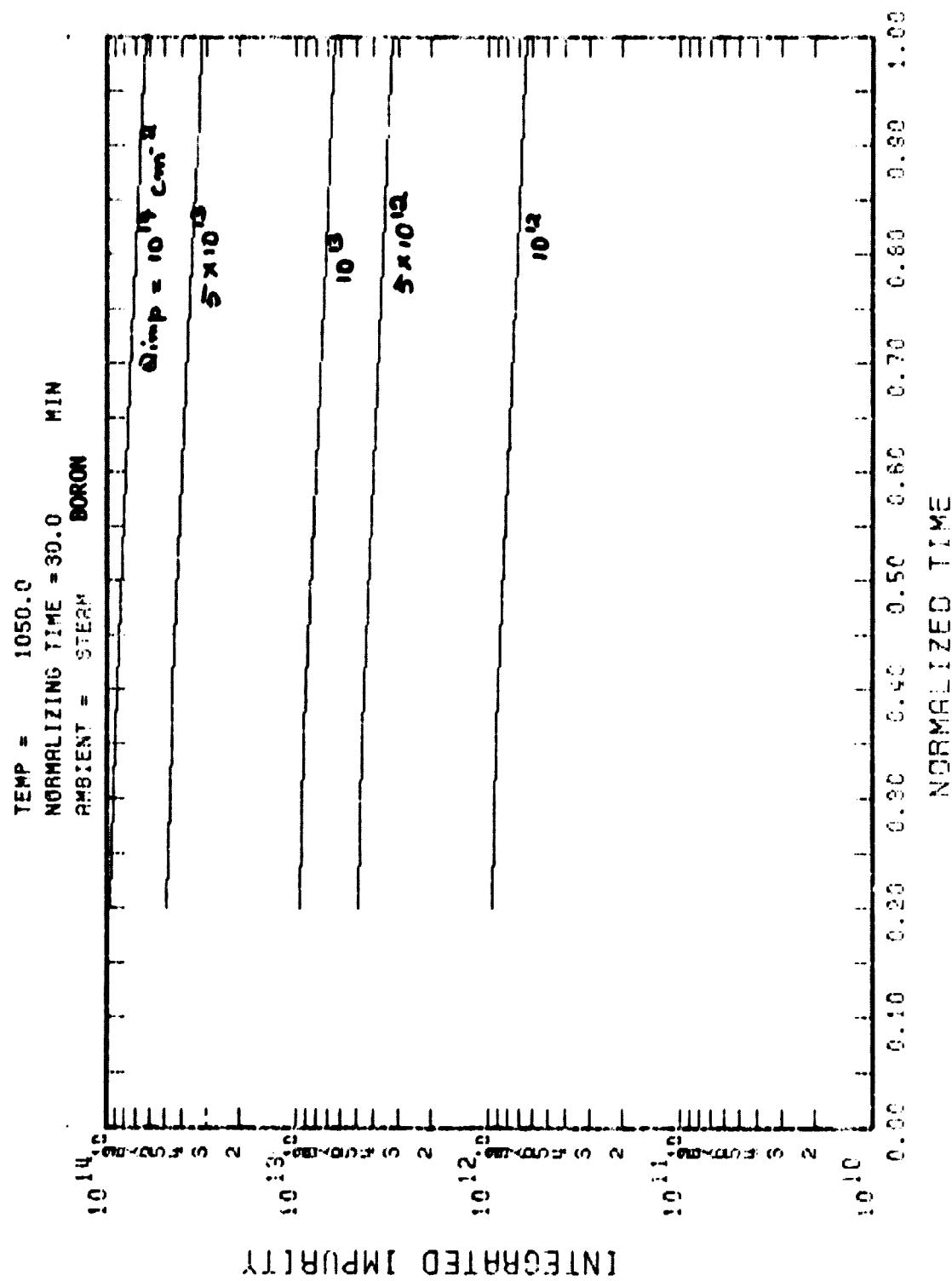
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AMBIENT = STEAM BORON MIN



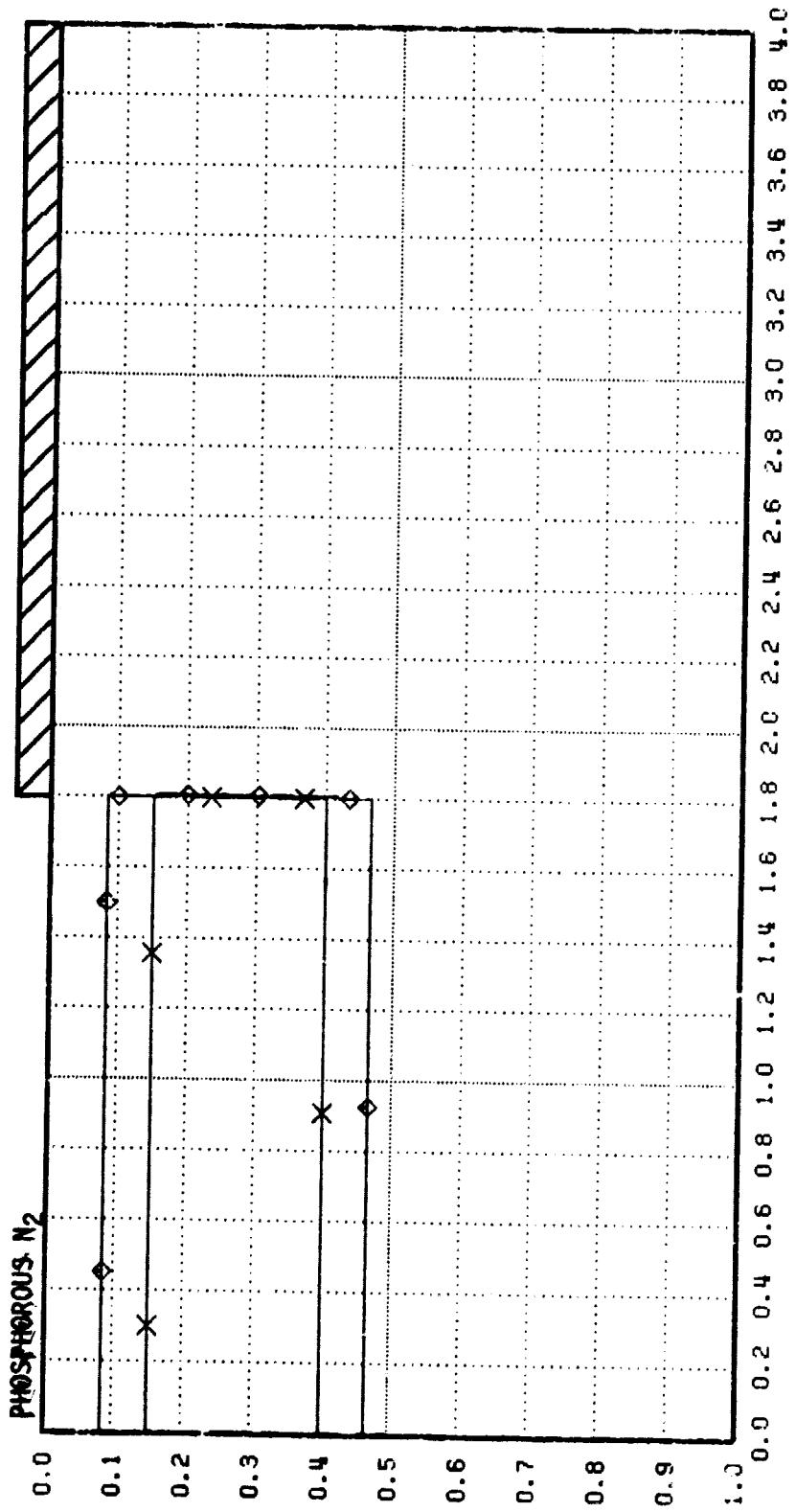
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APPENDIX

PHOSPHORUS DATA

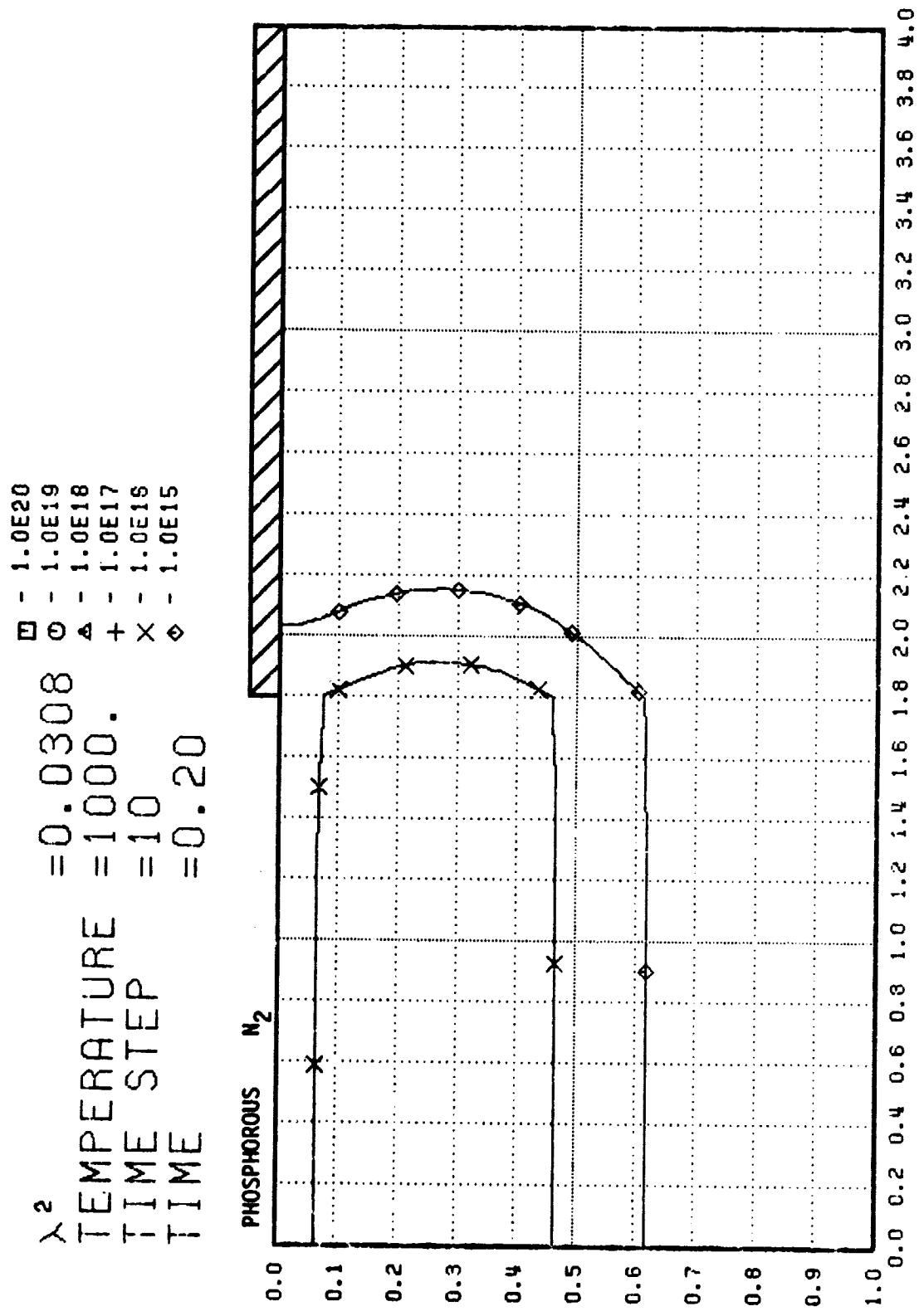
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 TIME = 0.00
 TIME = 0.00



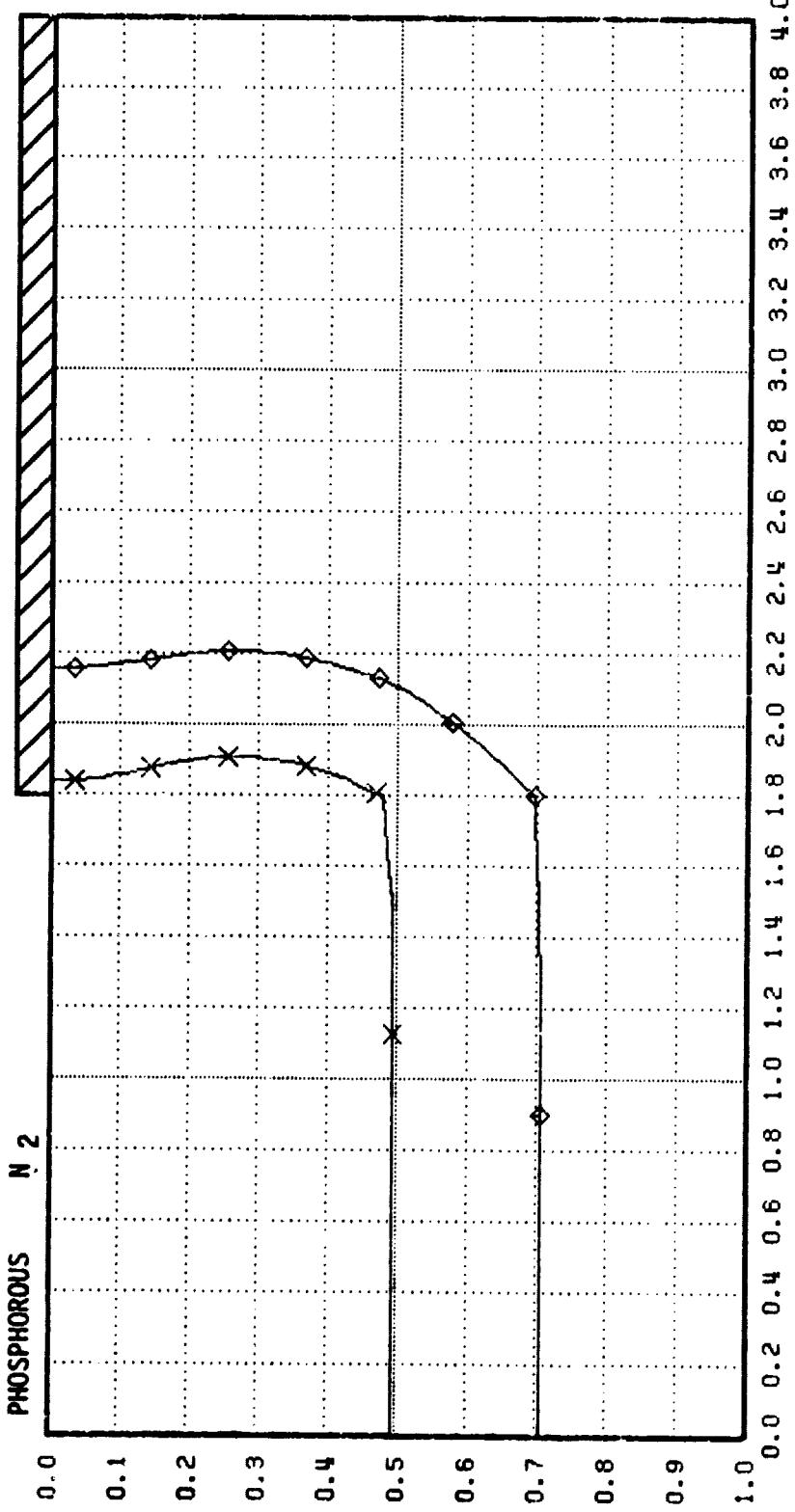
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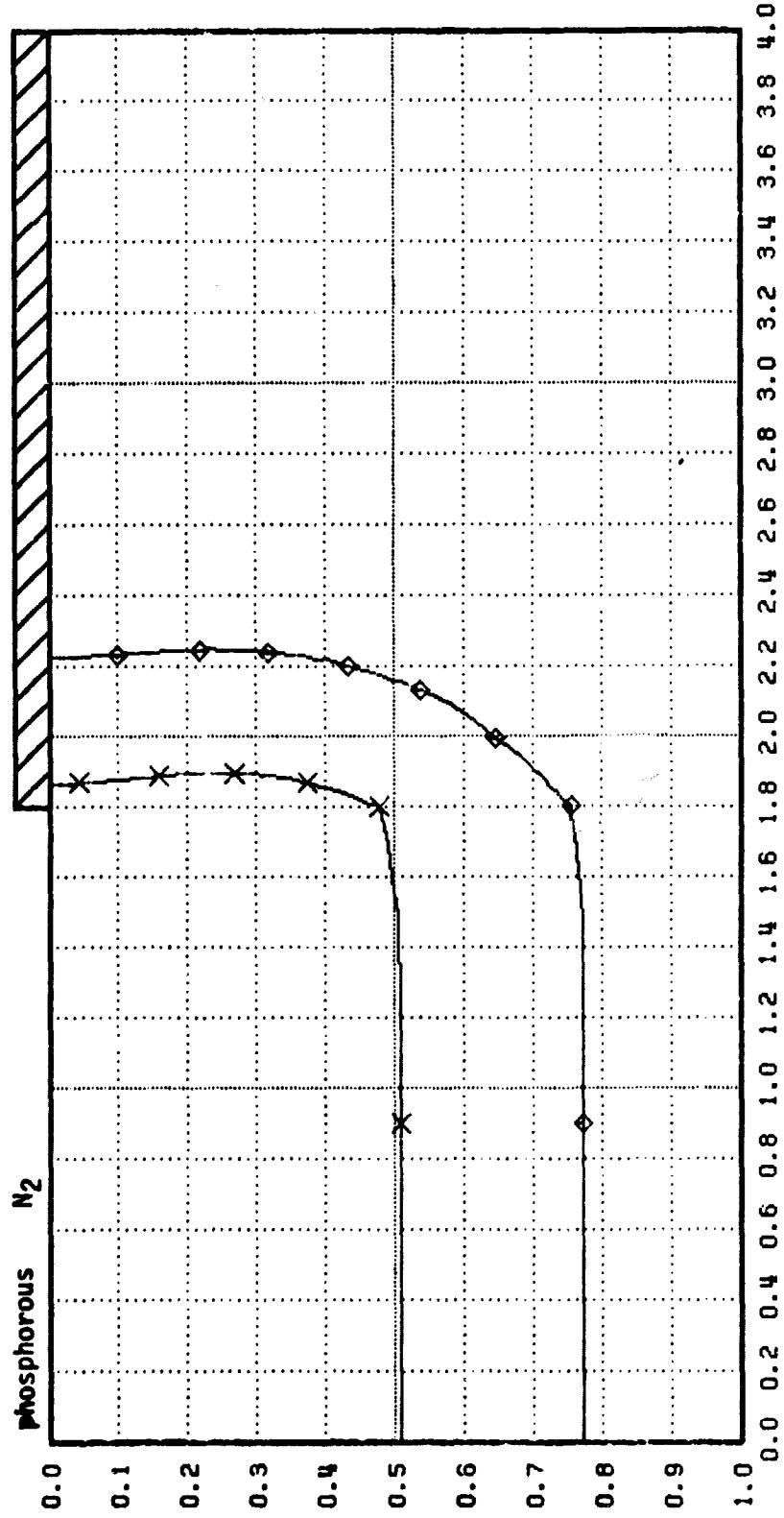
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λ^2
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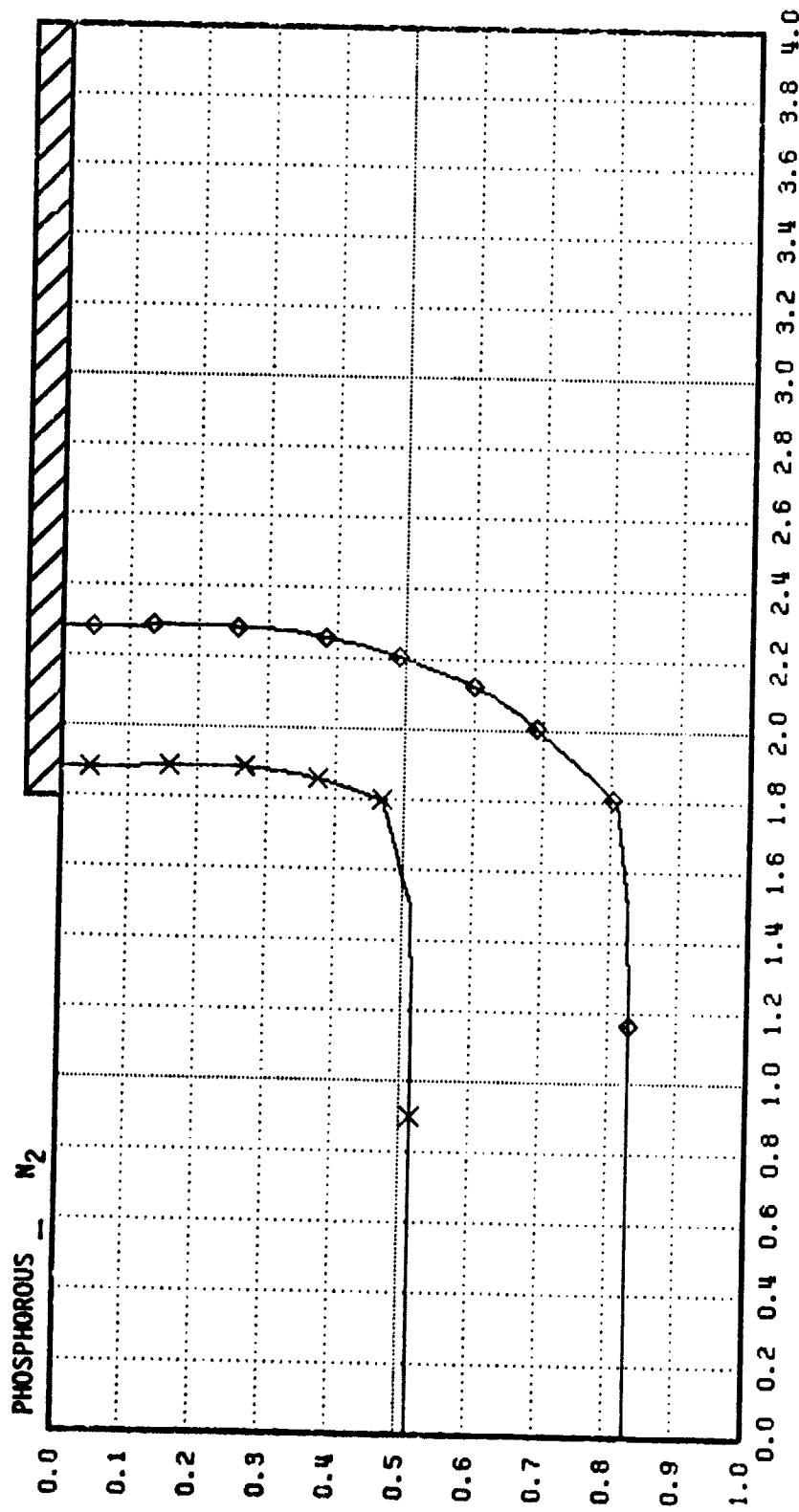


λ^2
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TIME STEP = 1000.
TIME = 0.60
 λ^2
= 0.0308
= 1000.
= 30
= 0.60

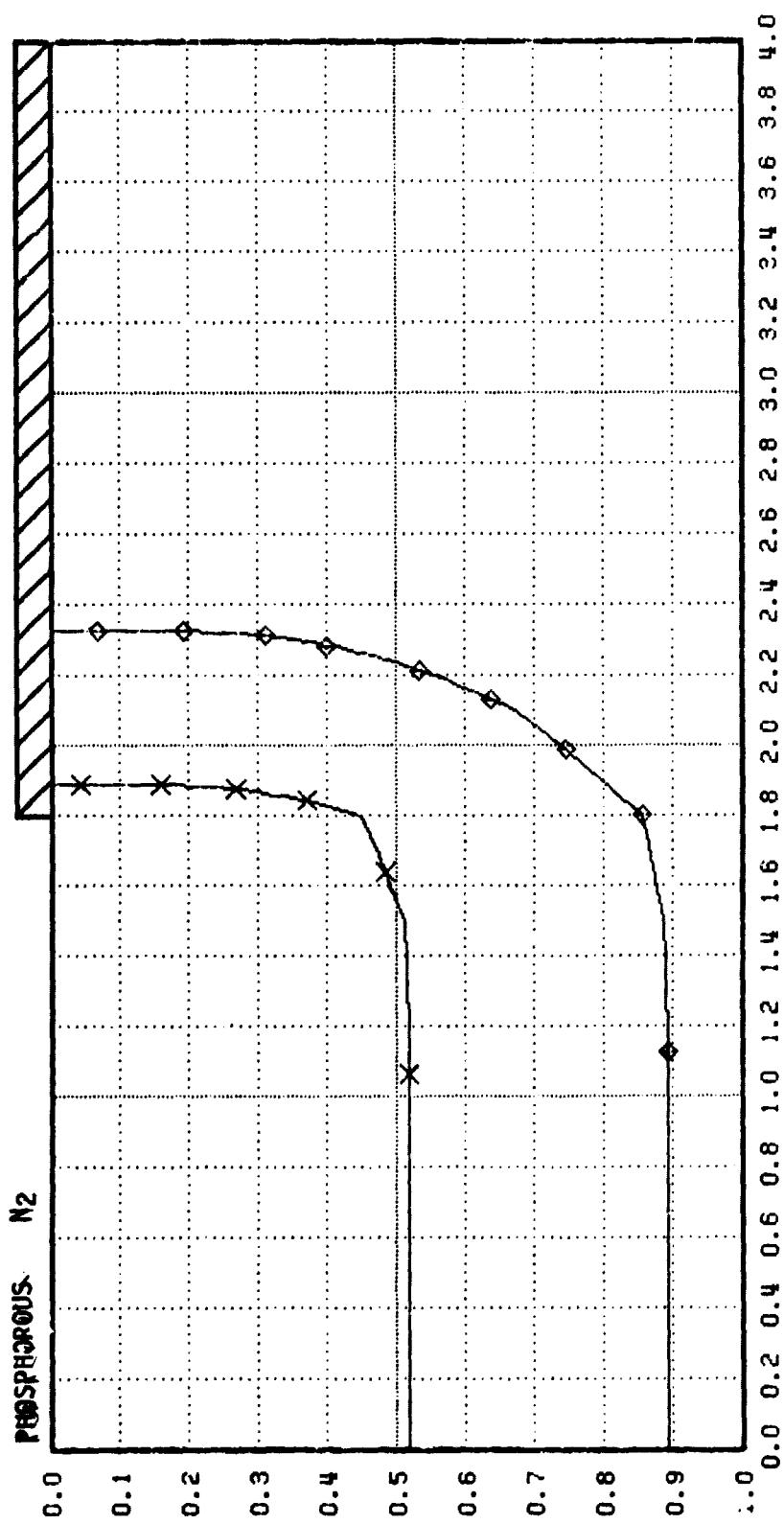


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TIME = 0.80

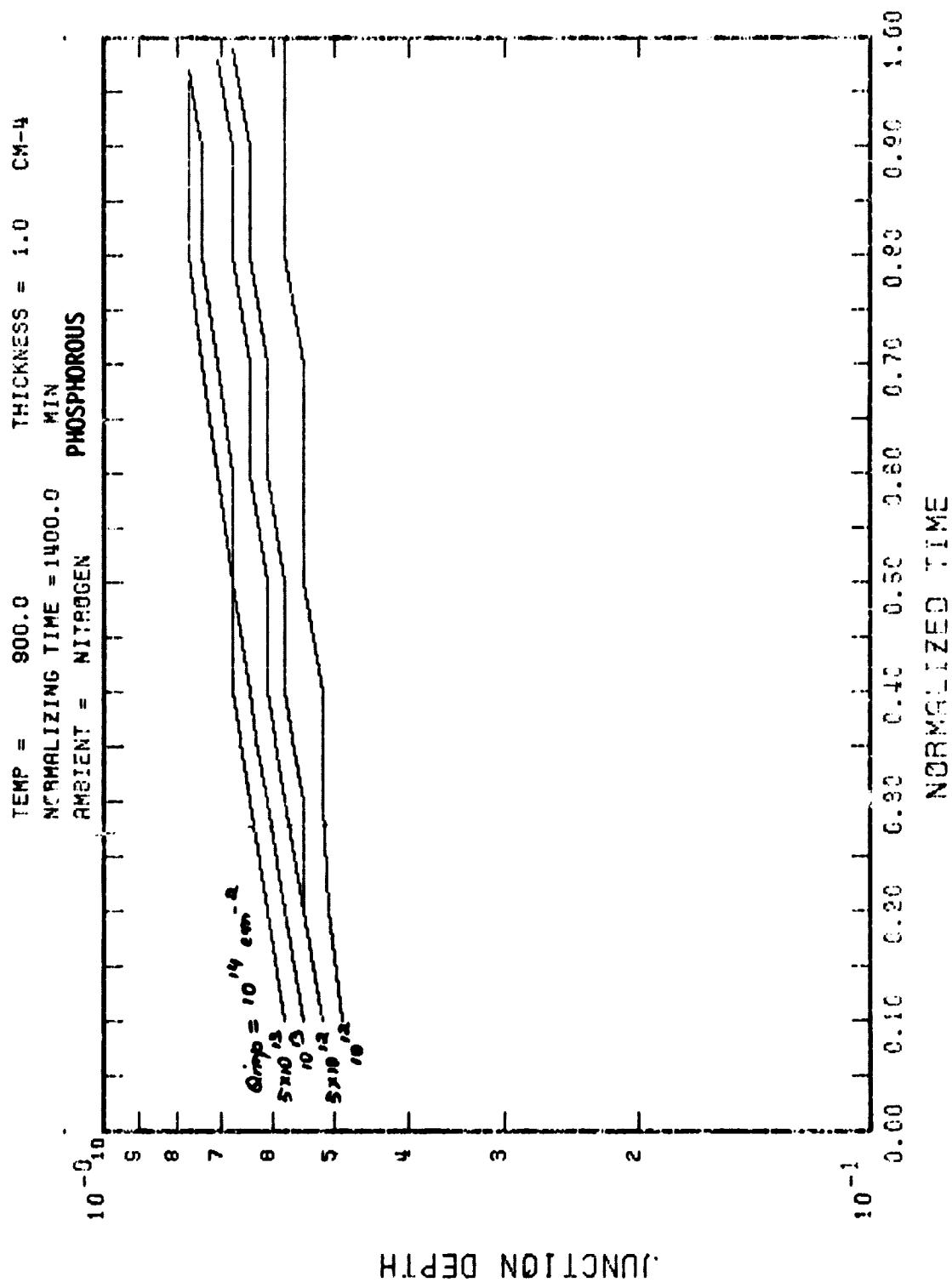


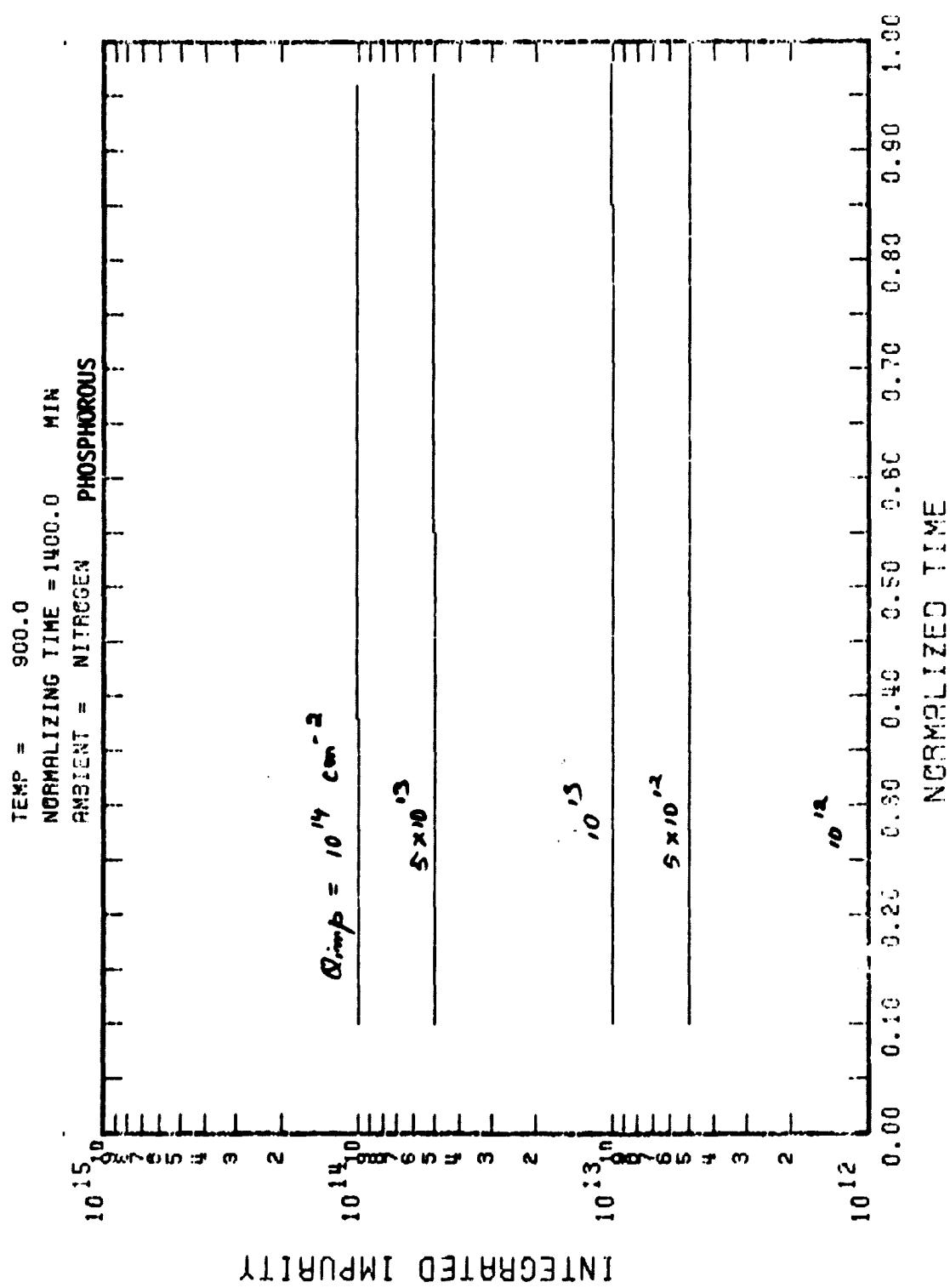
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= 0.0308
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TIME = 1.00



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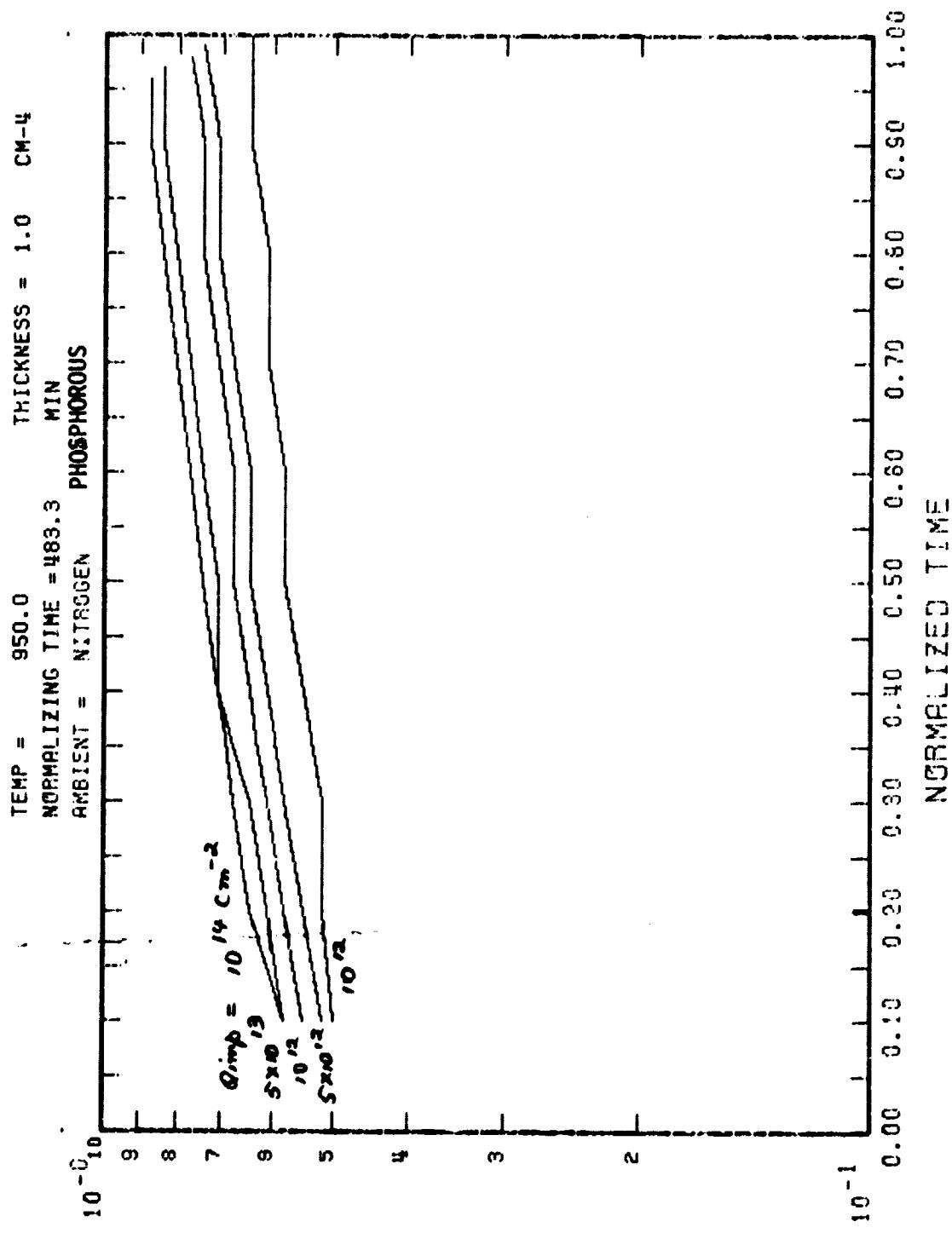
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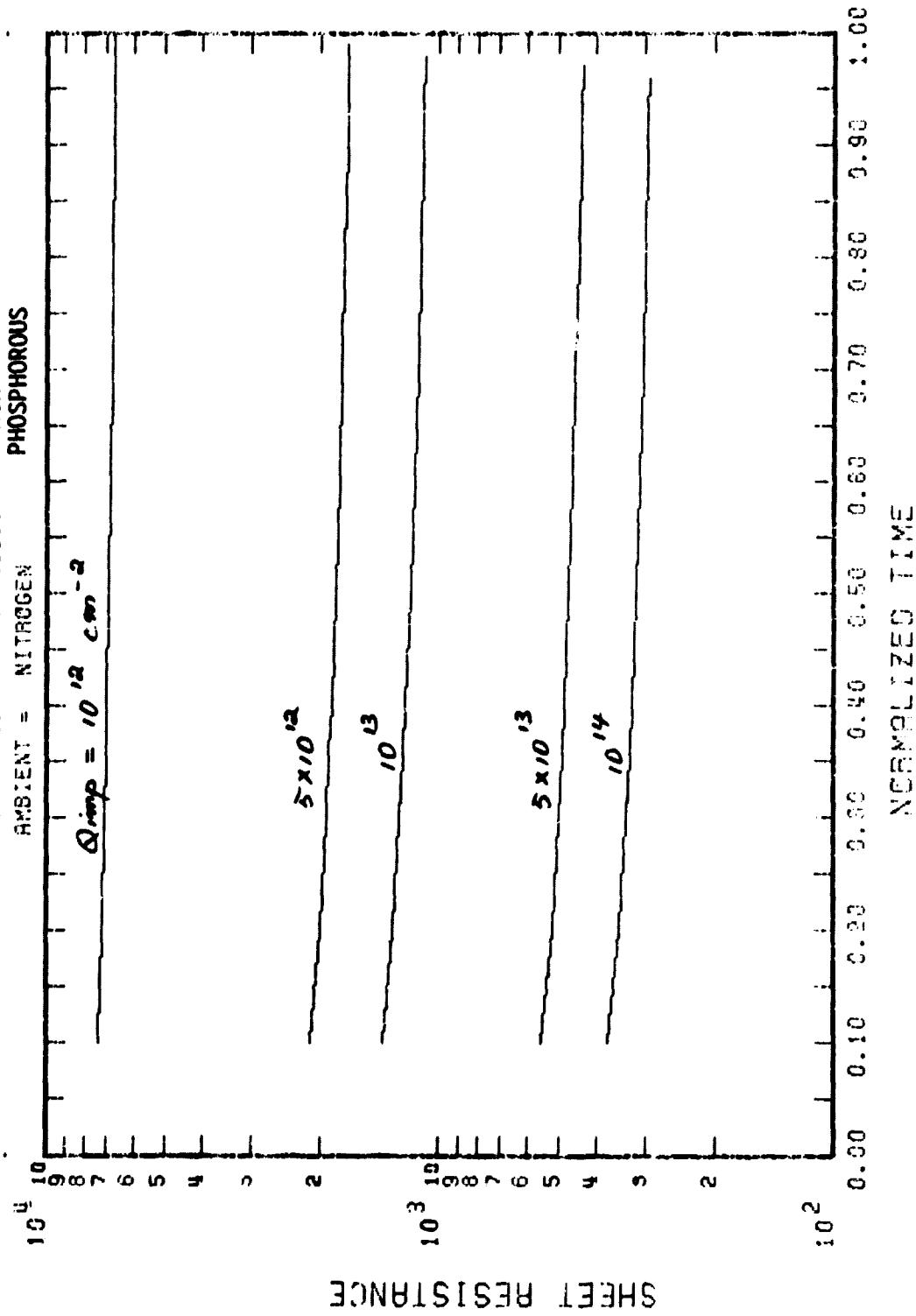


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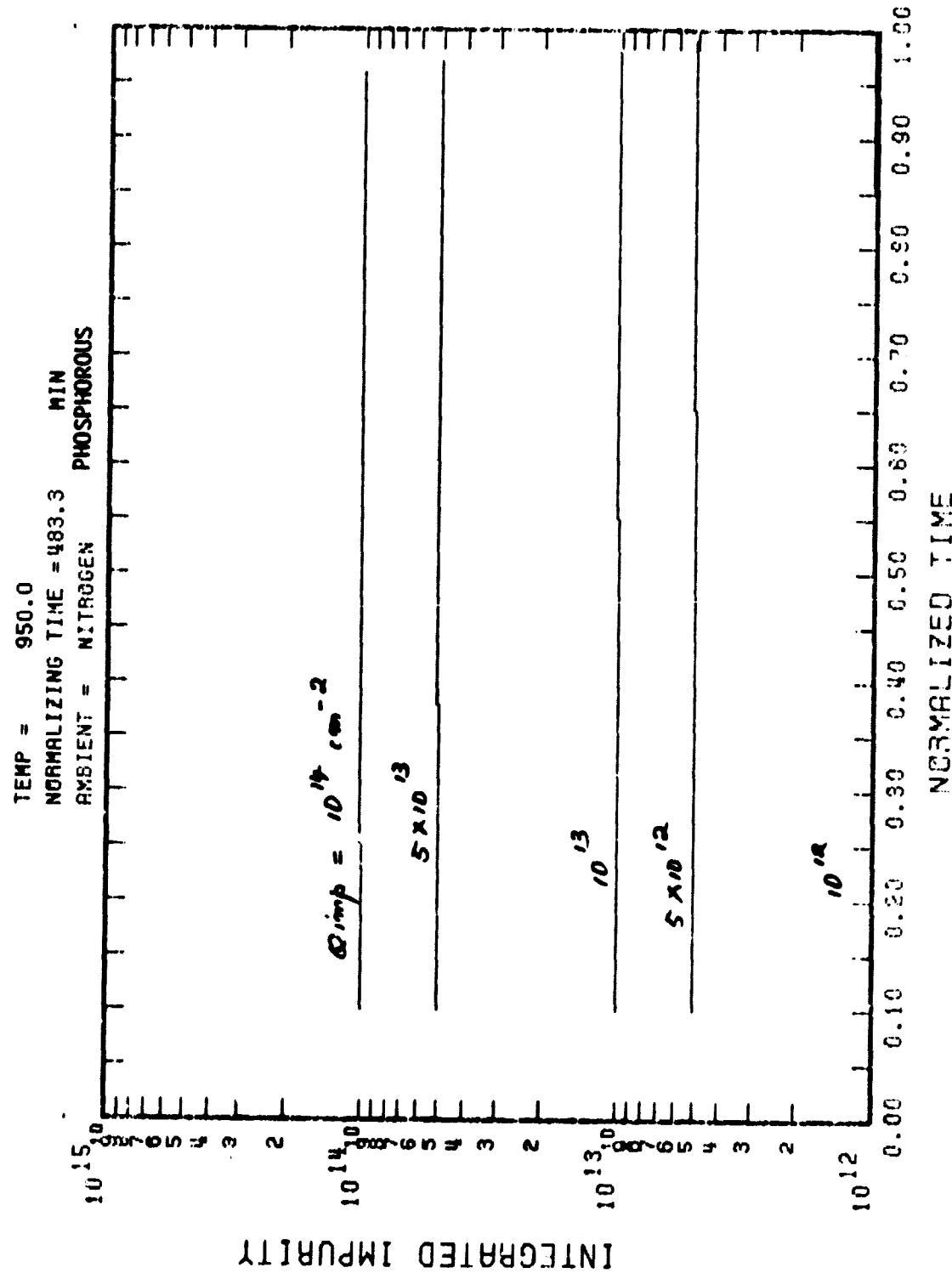


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PHOSPHOROUS



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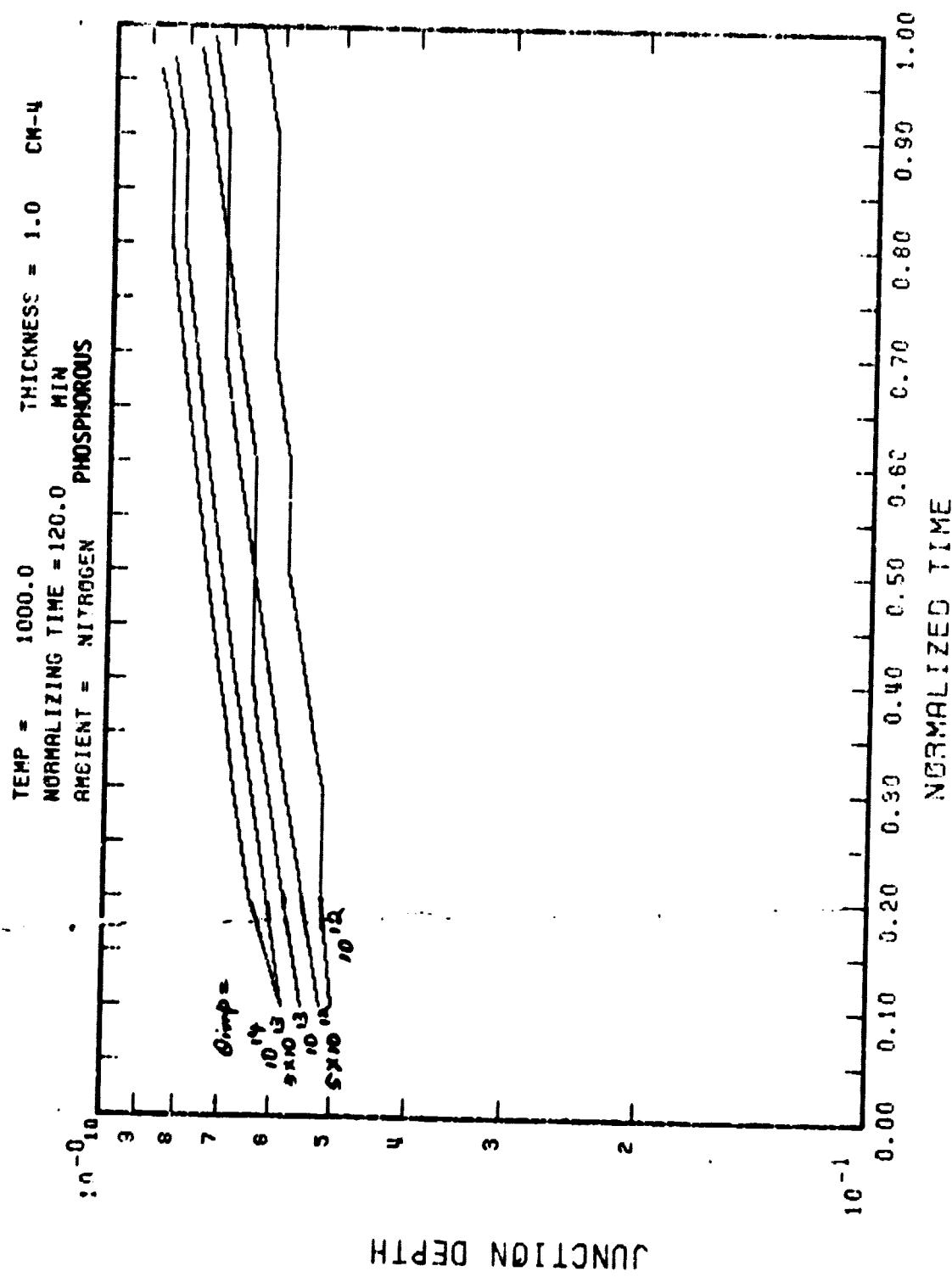
B 12



3

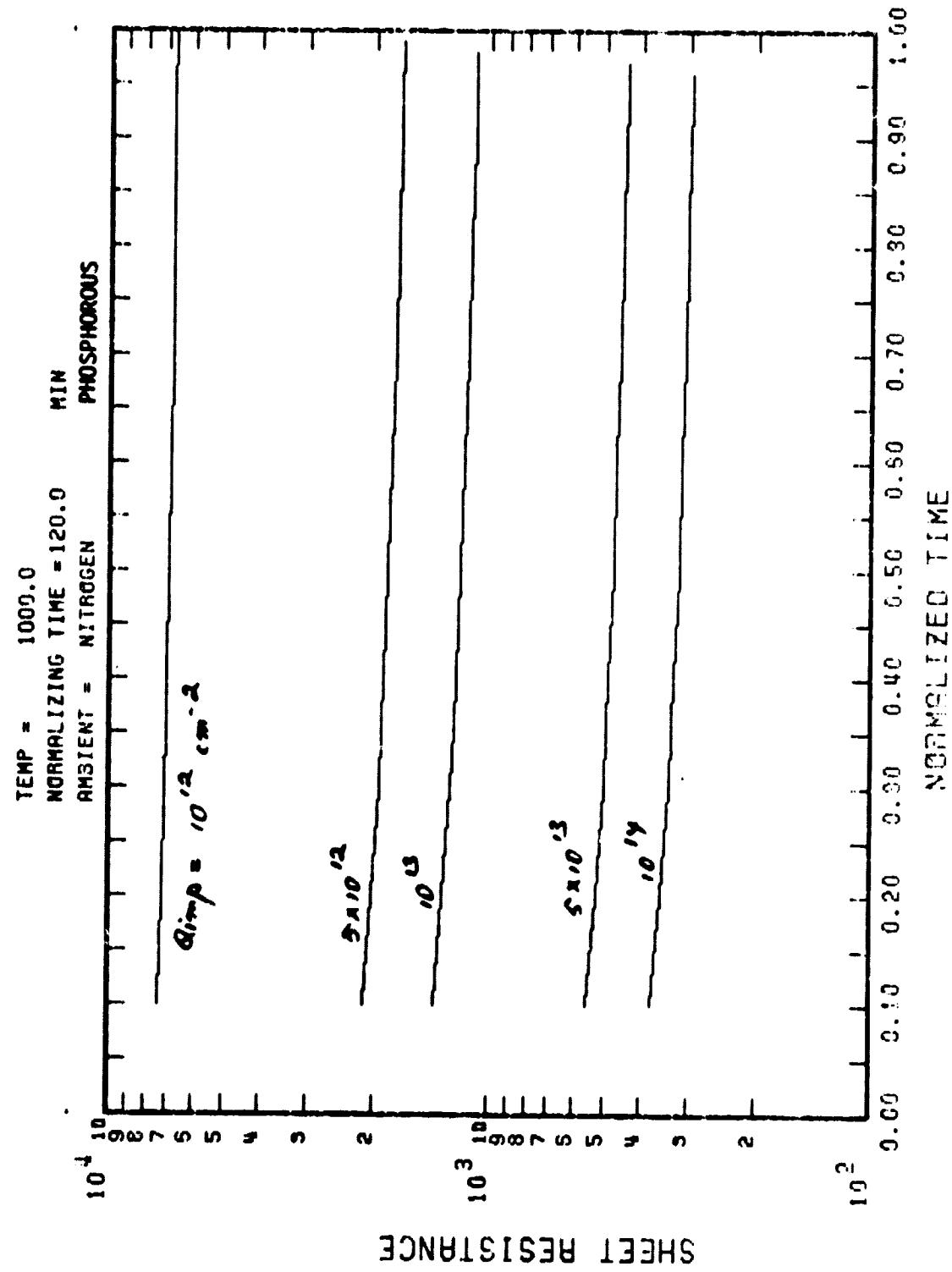
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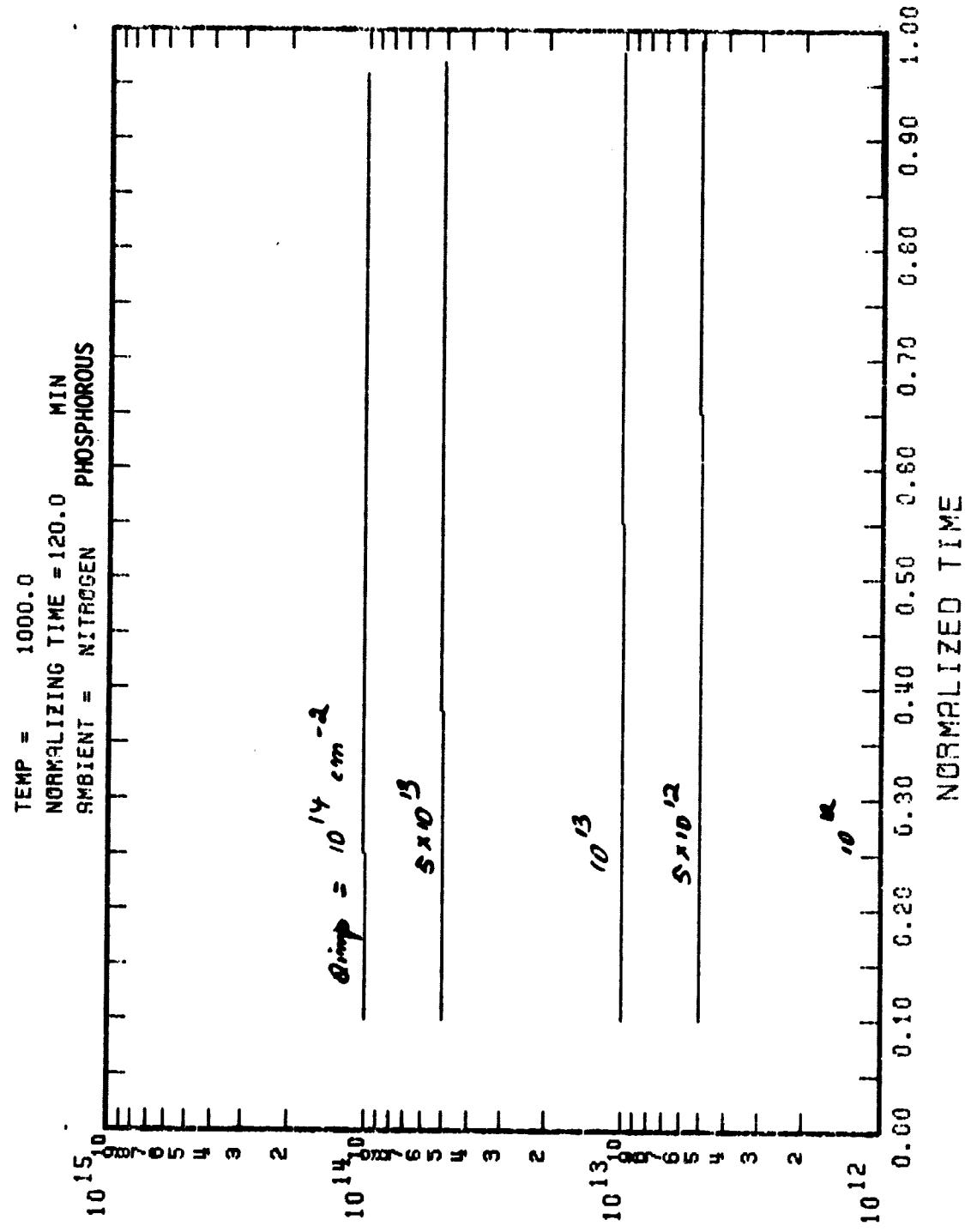
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7

B 14



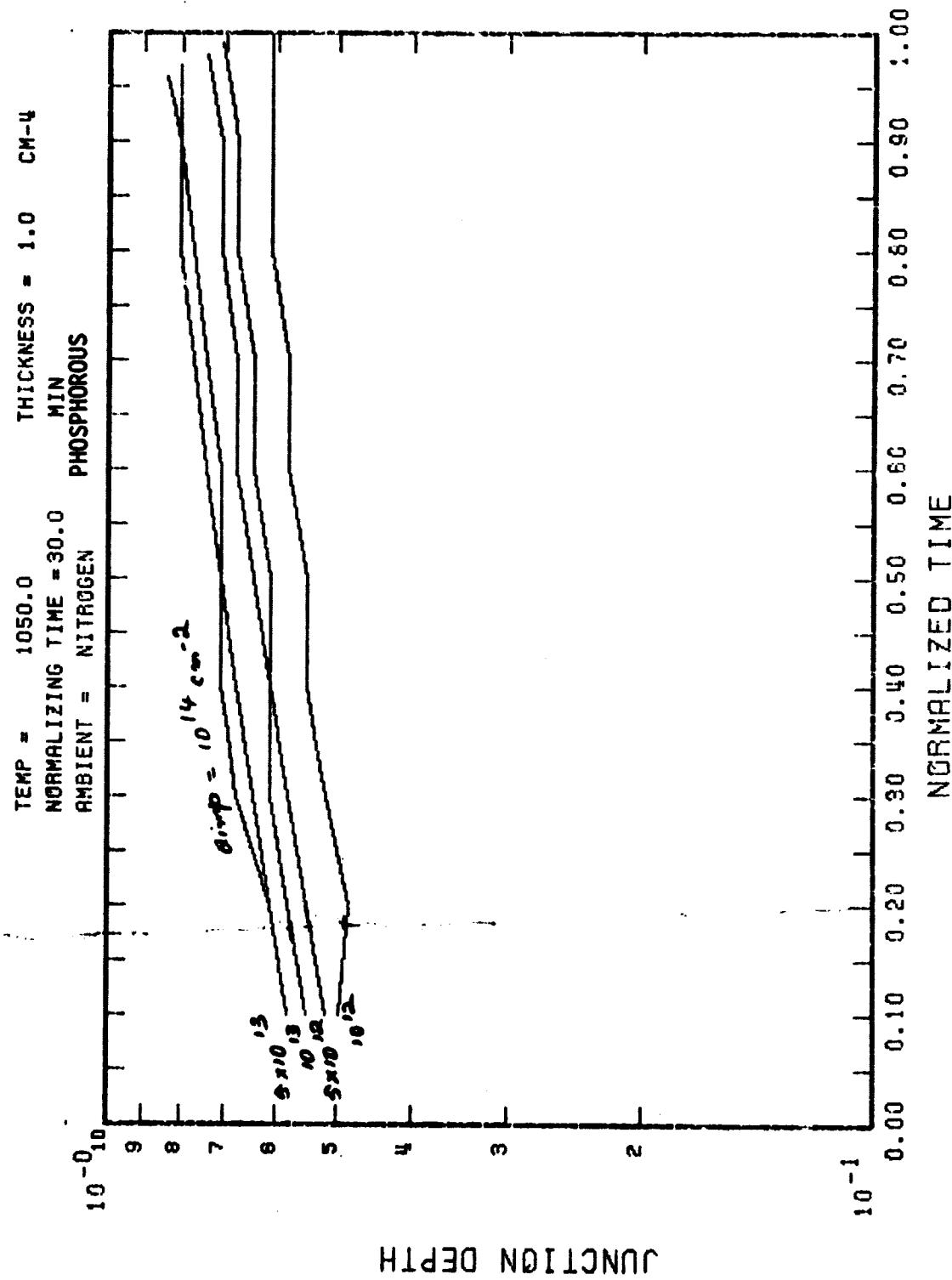


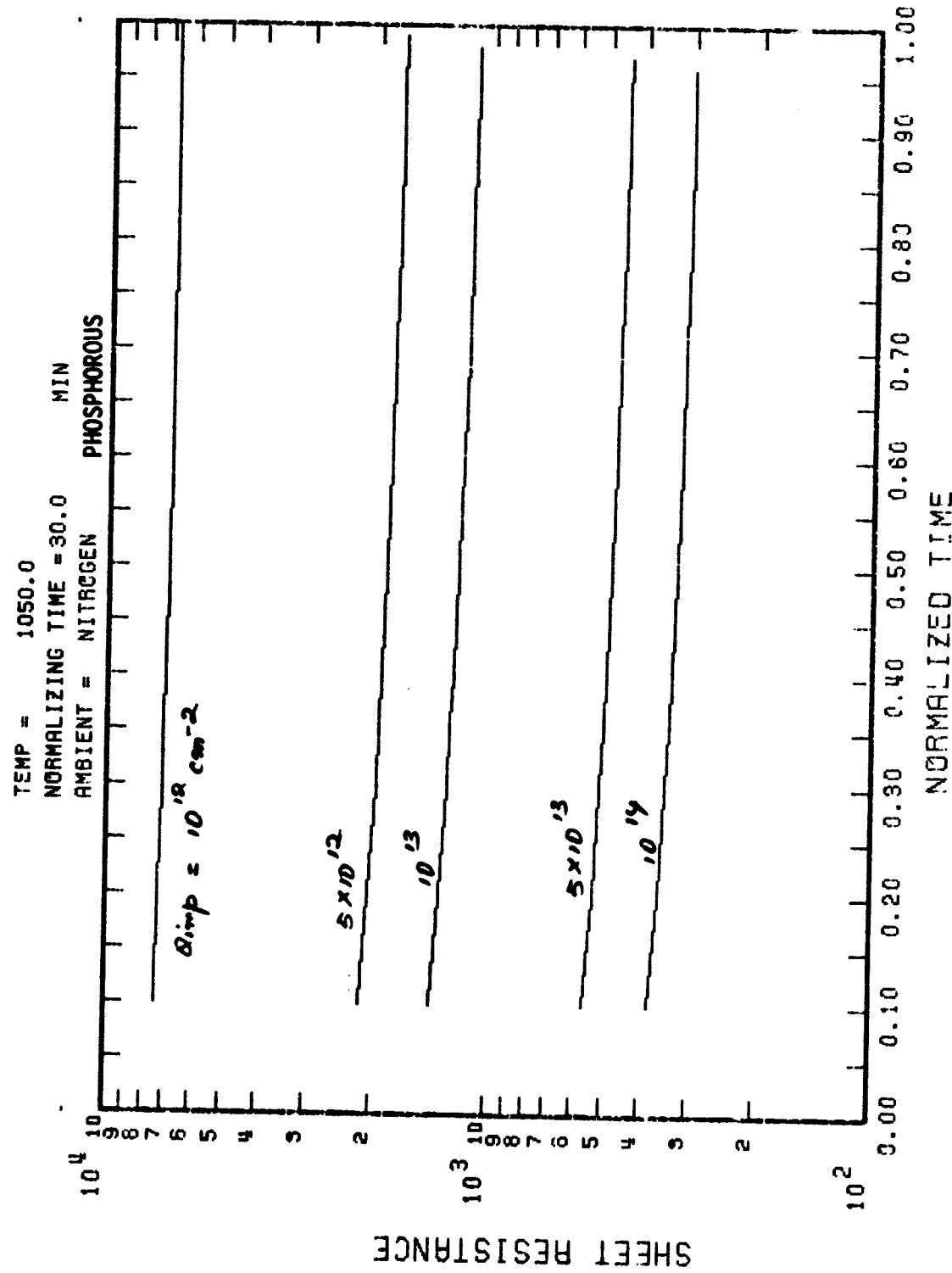
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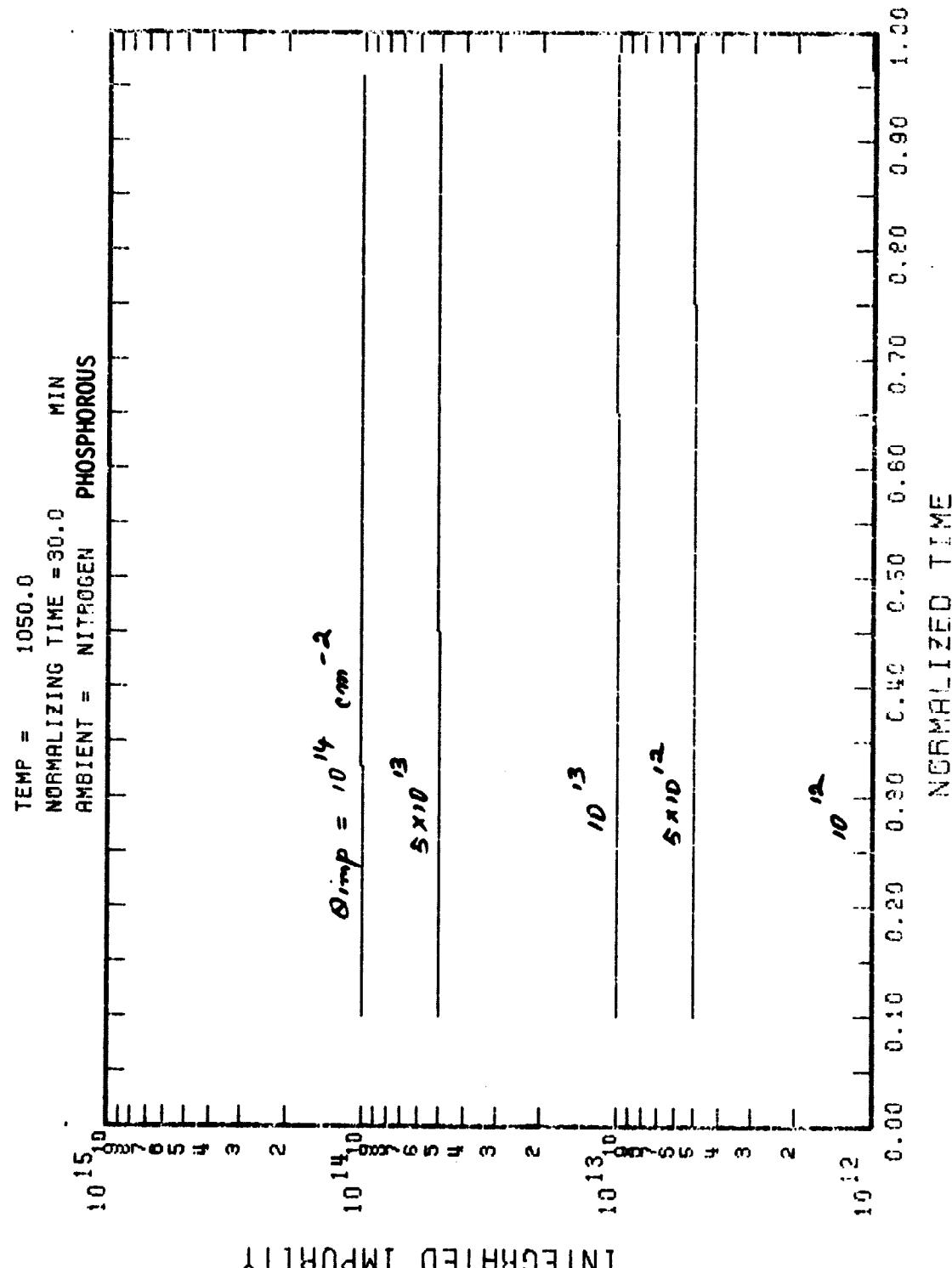


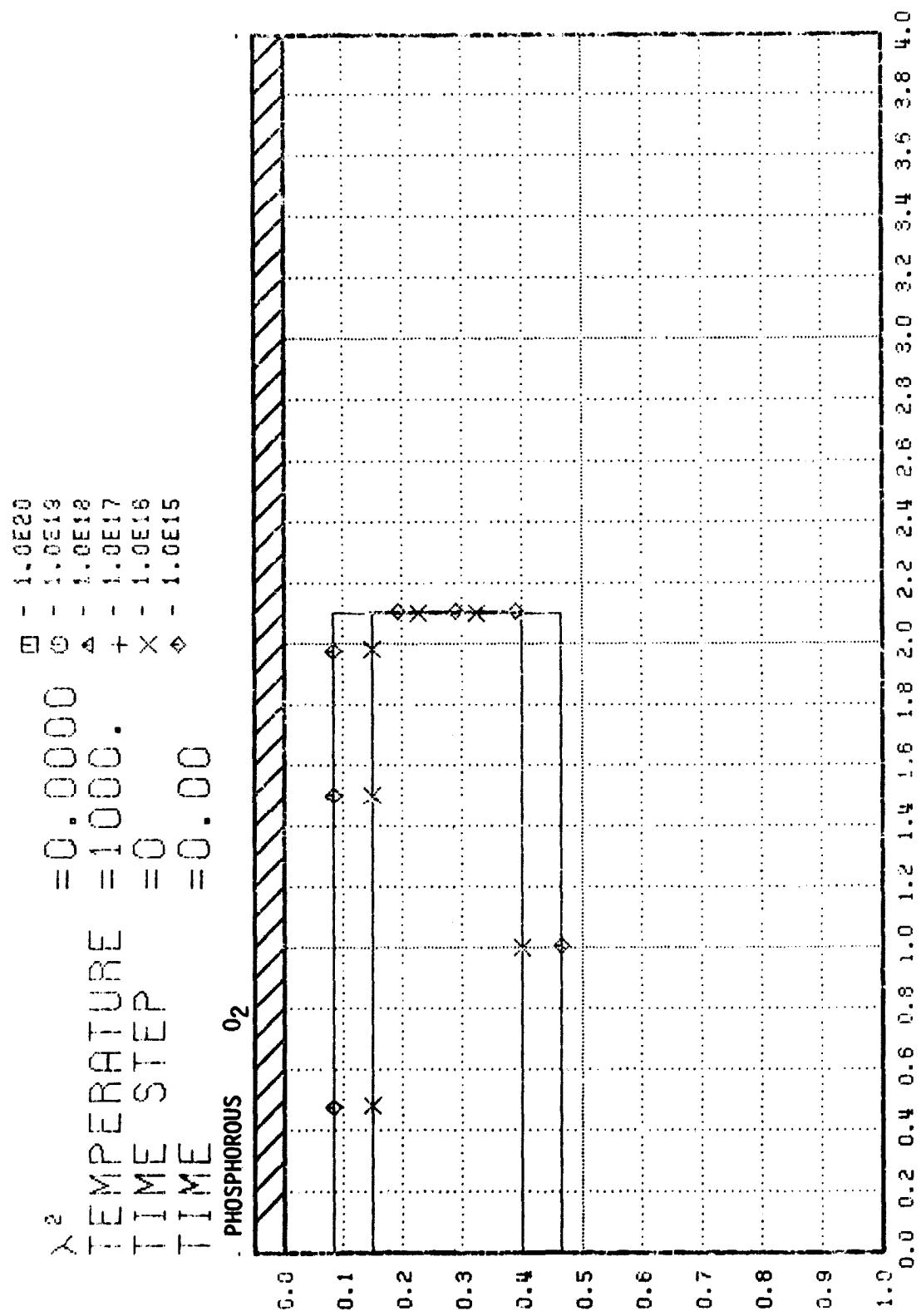


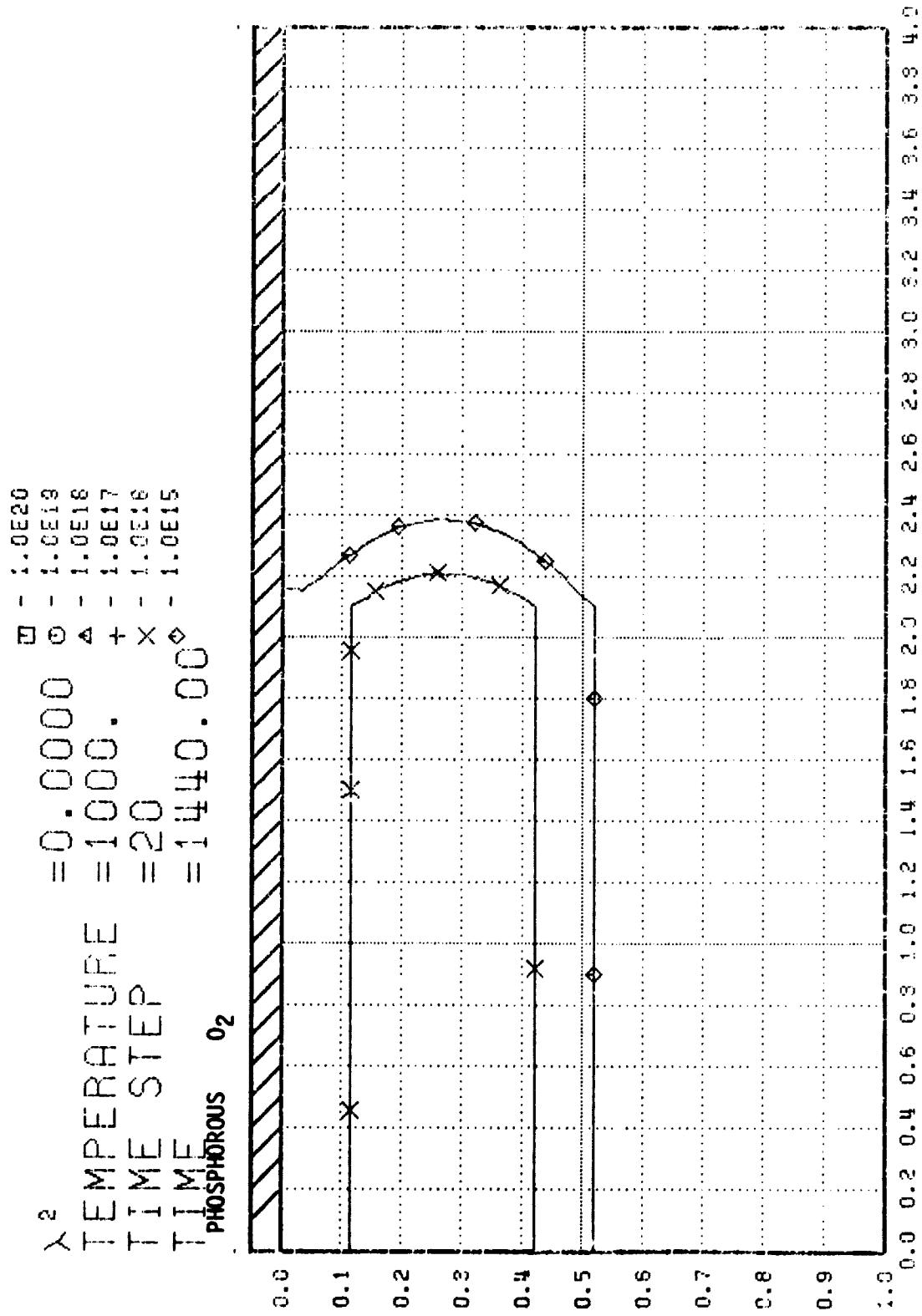
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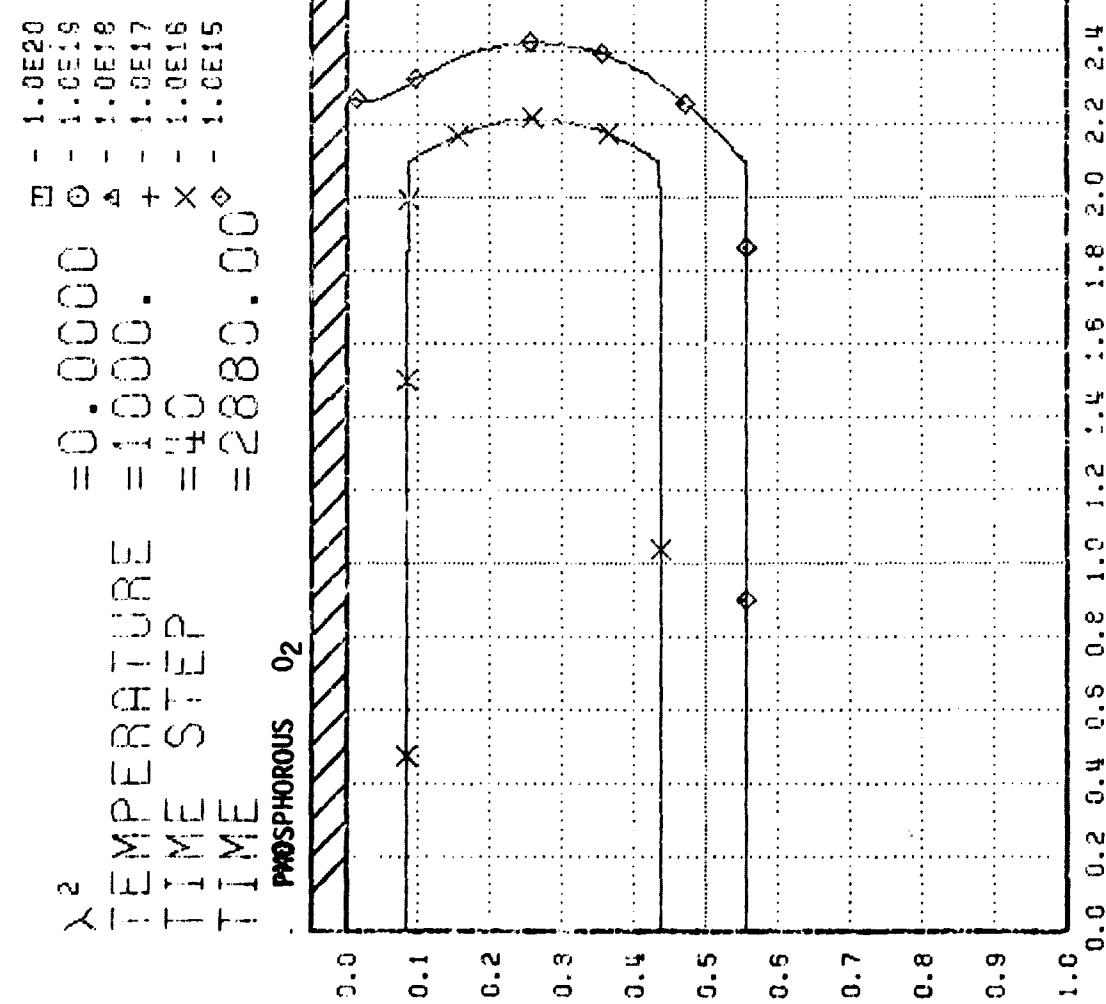
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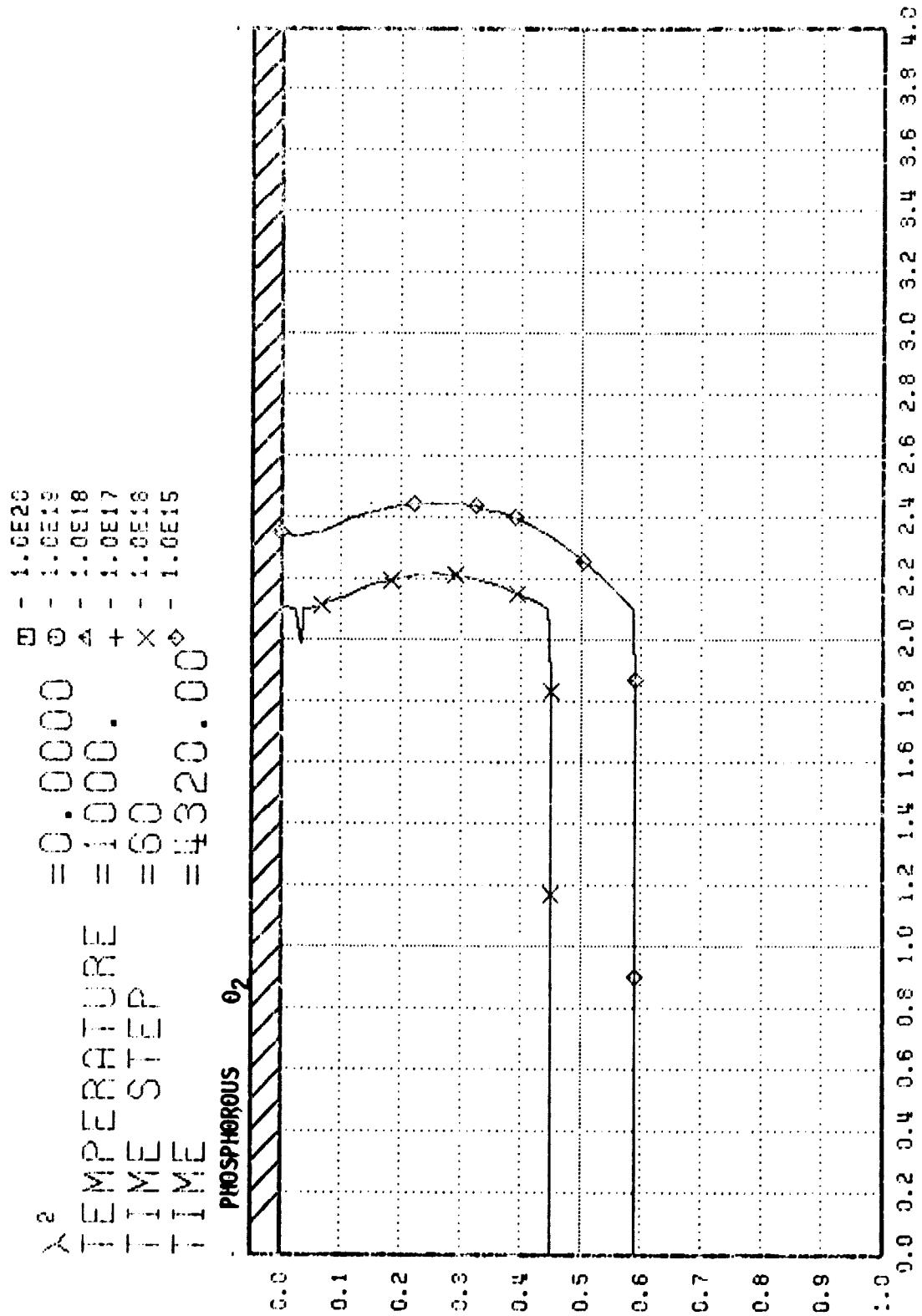


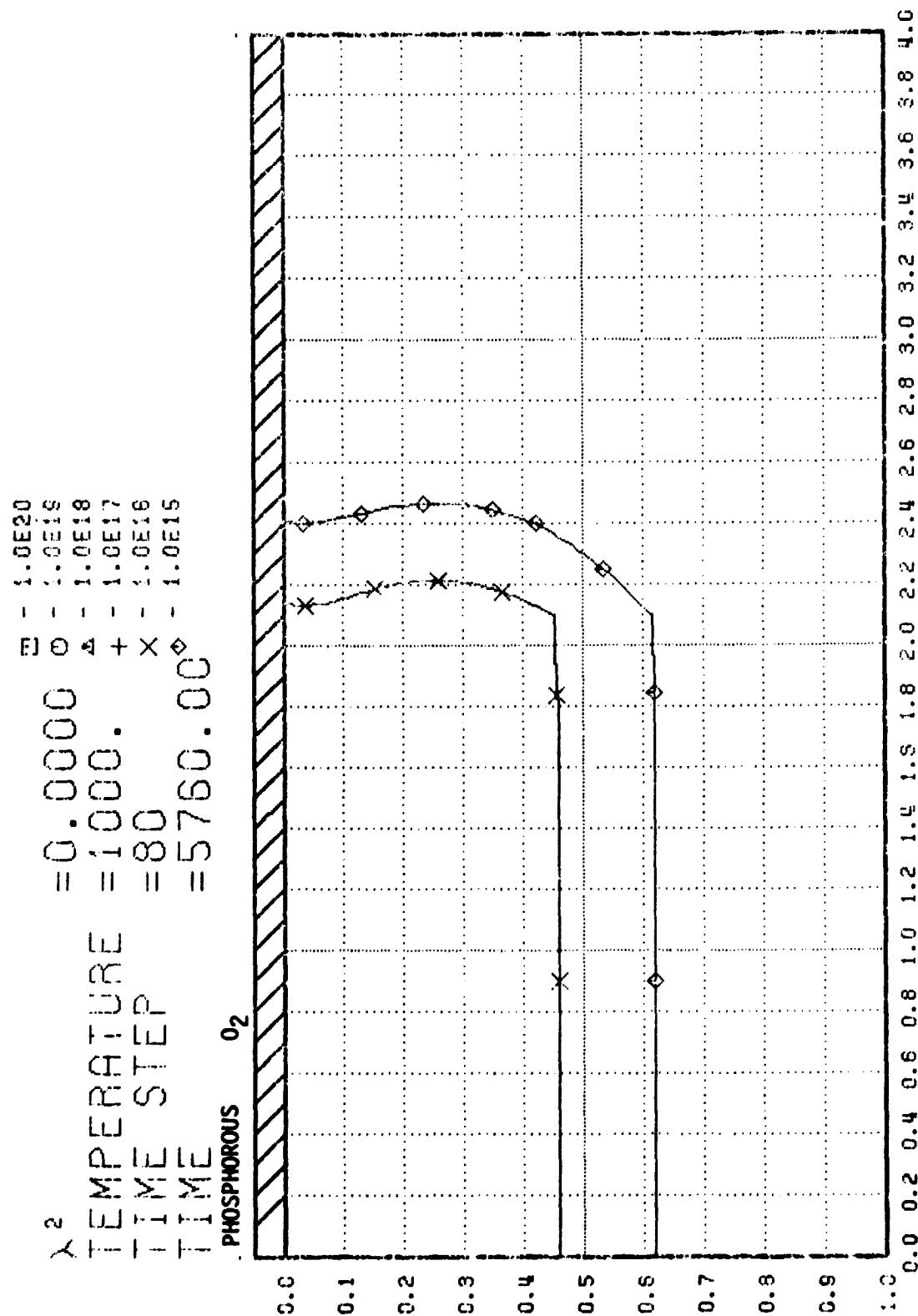
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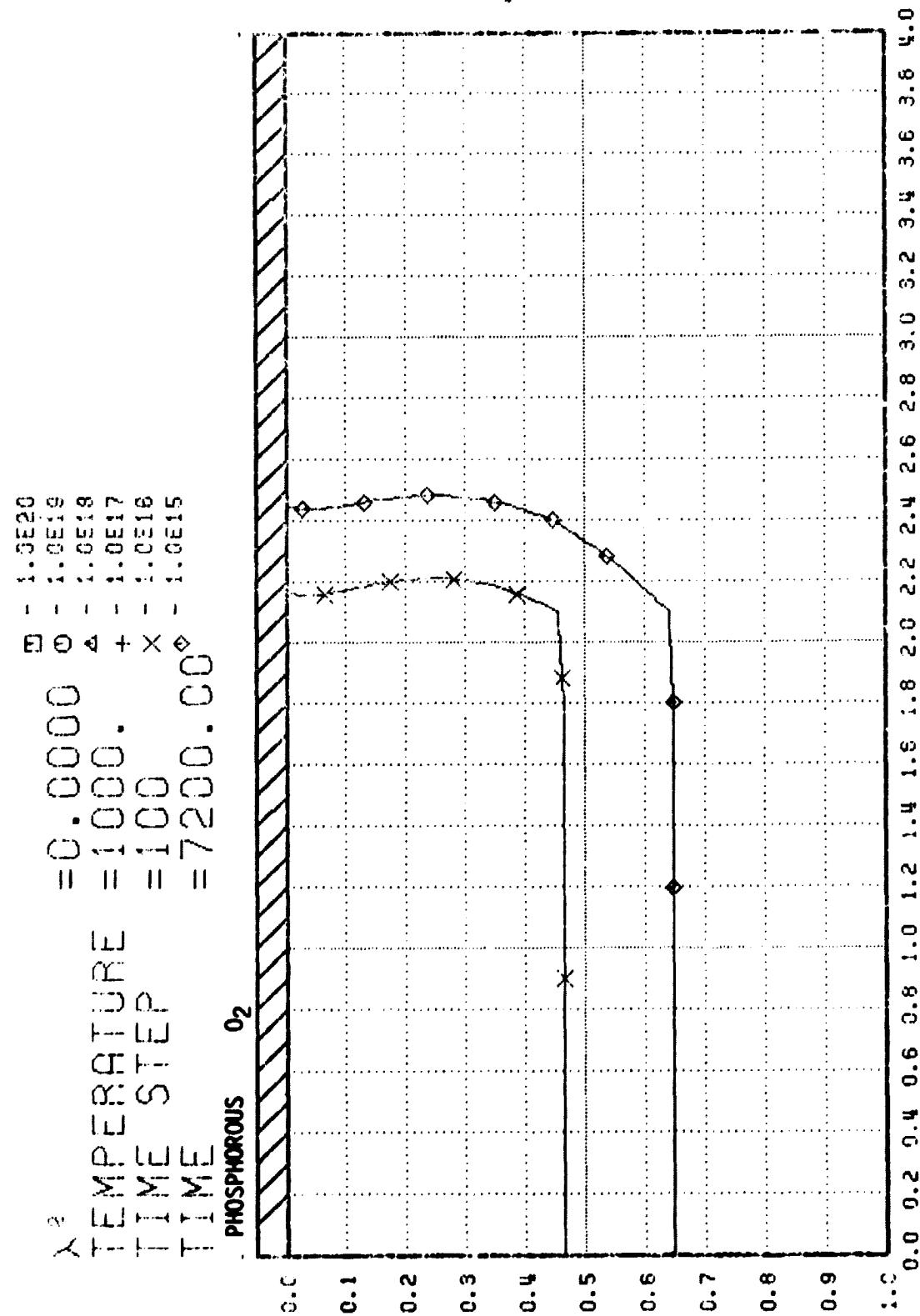


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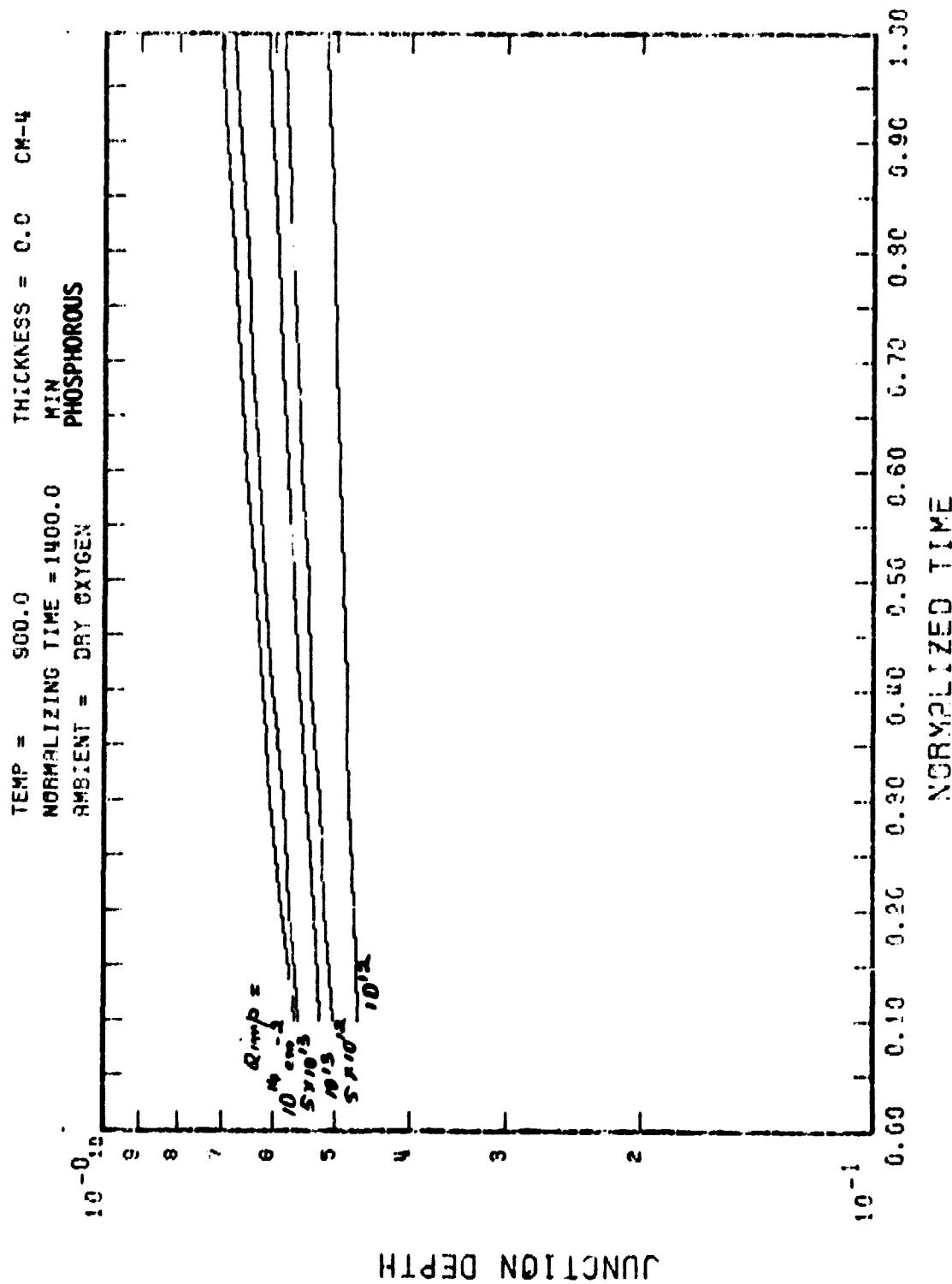


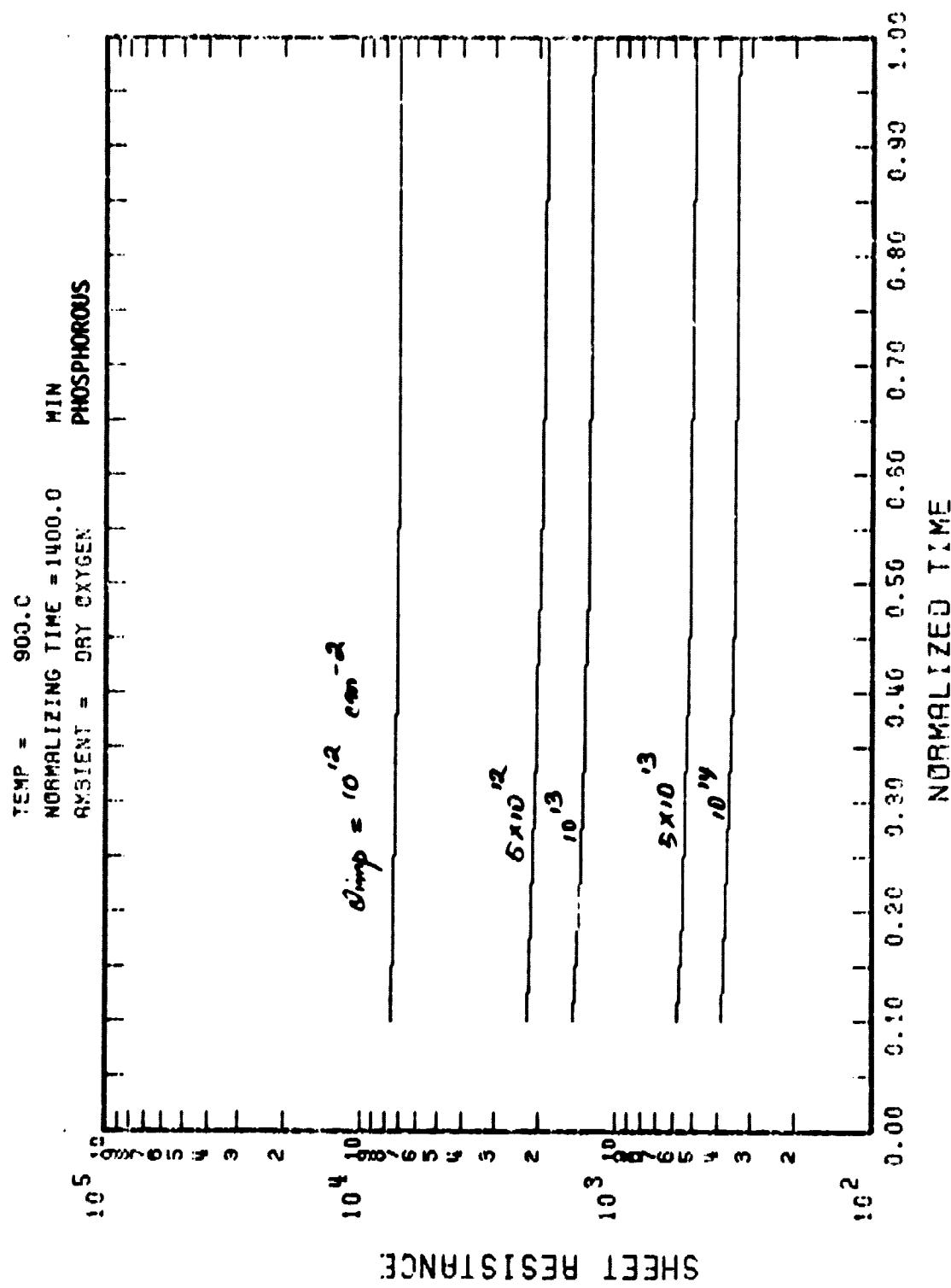




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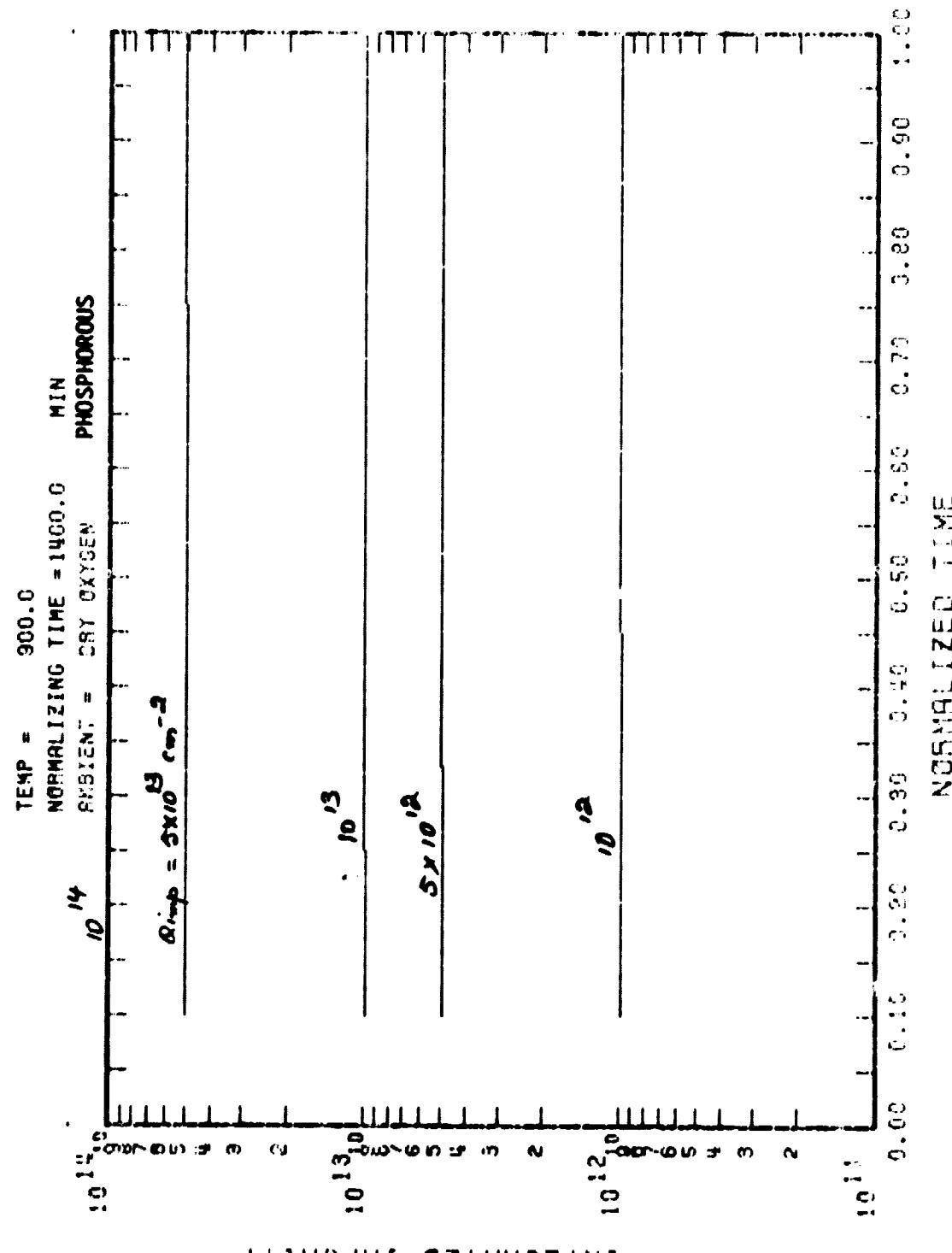


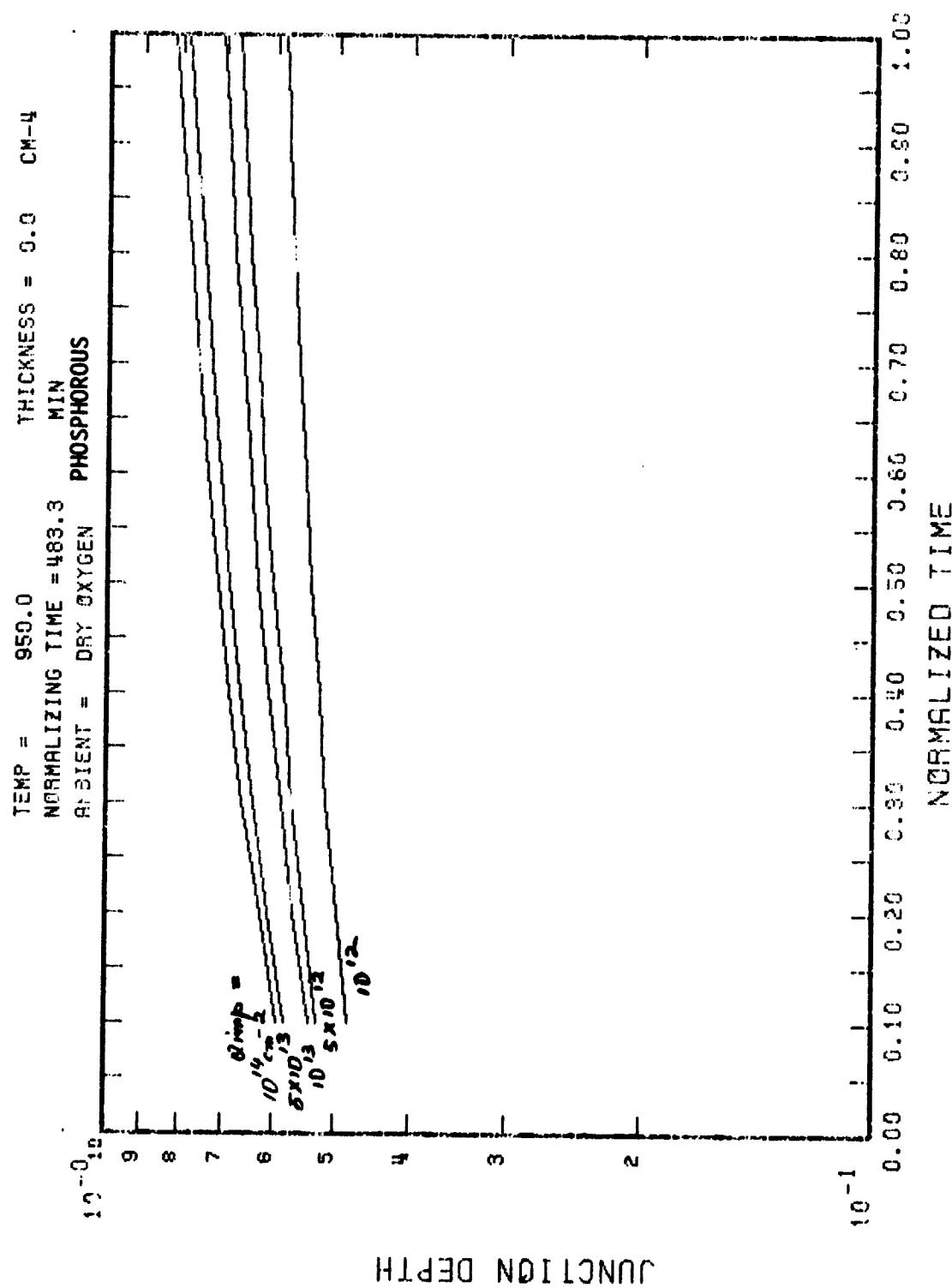


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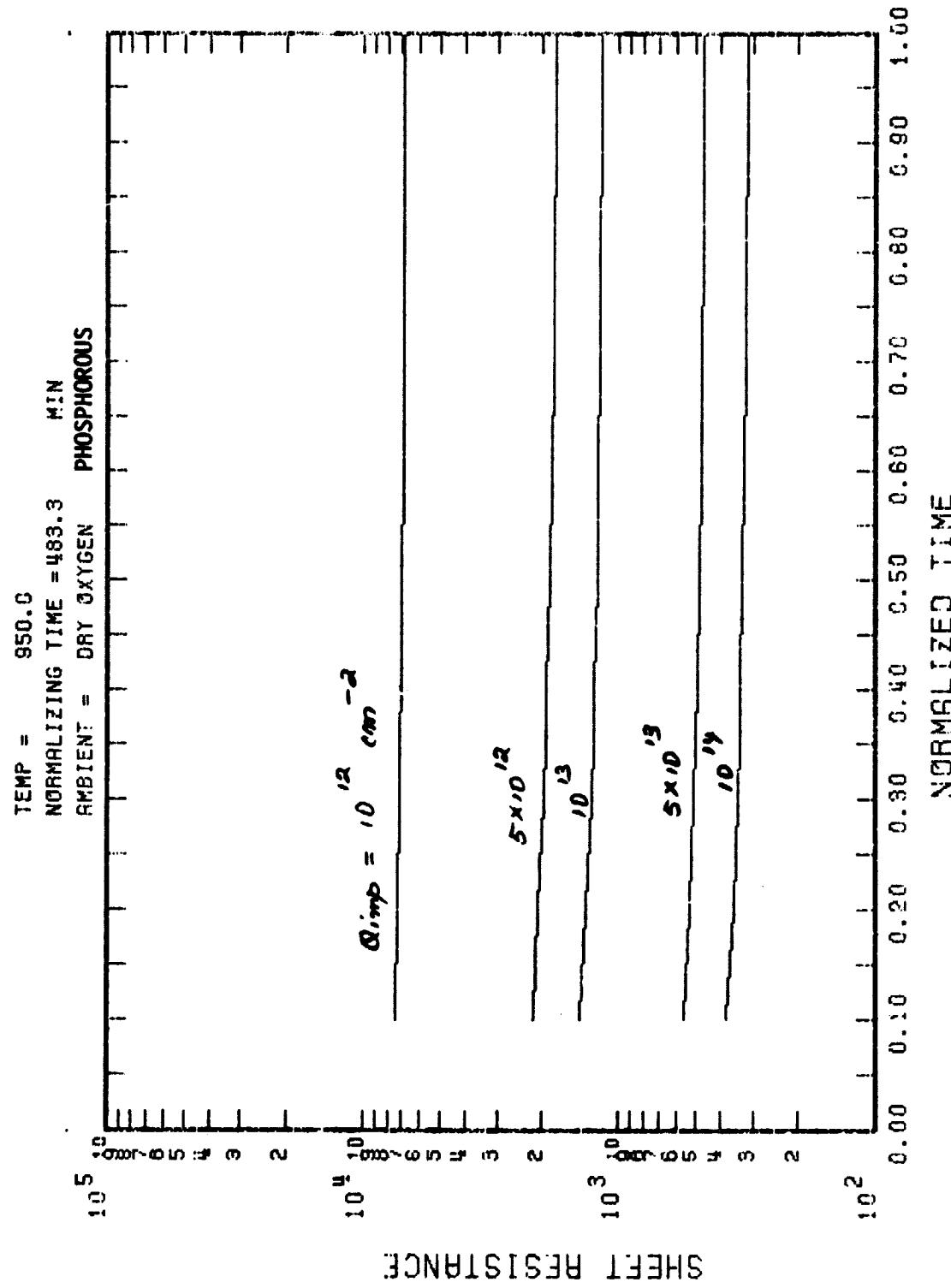
B 27





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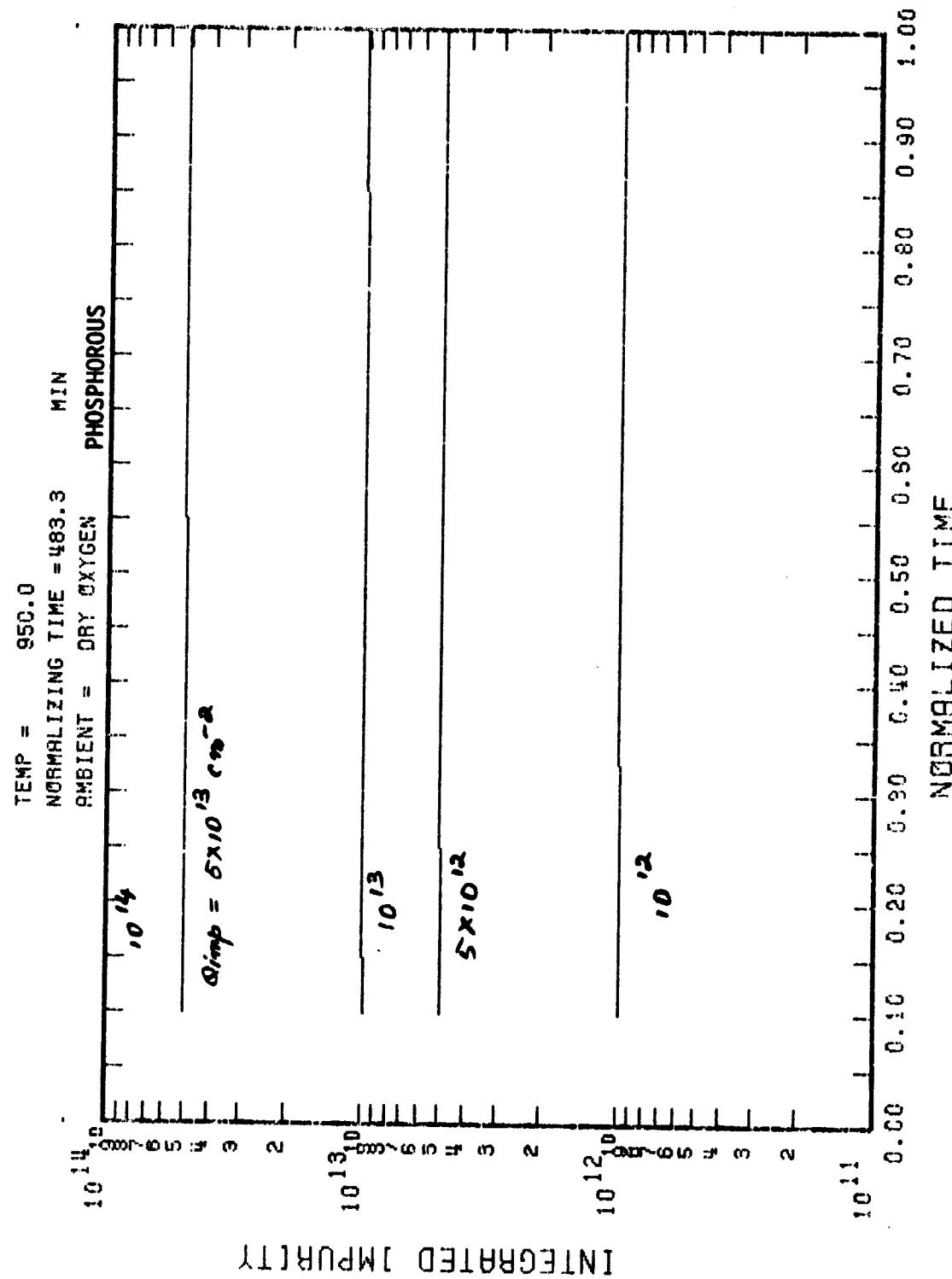
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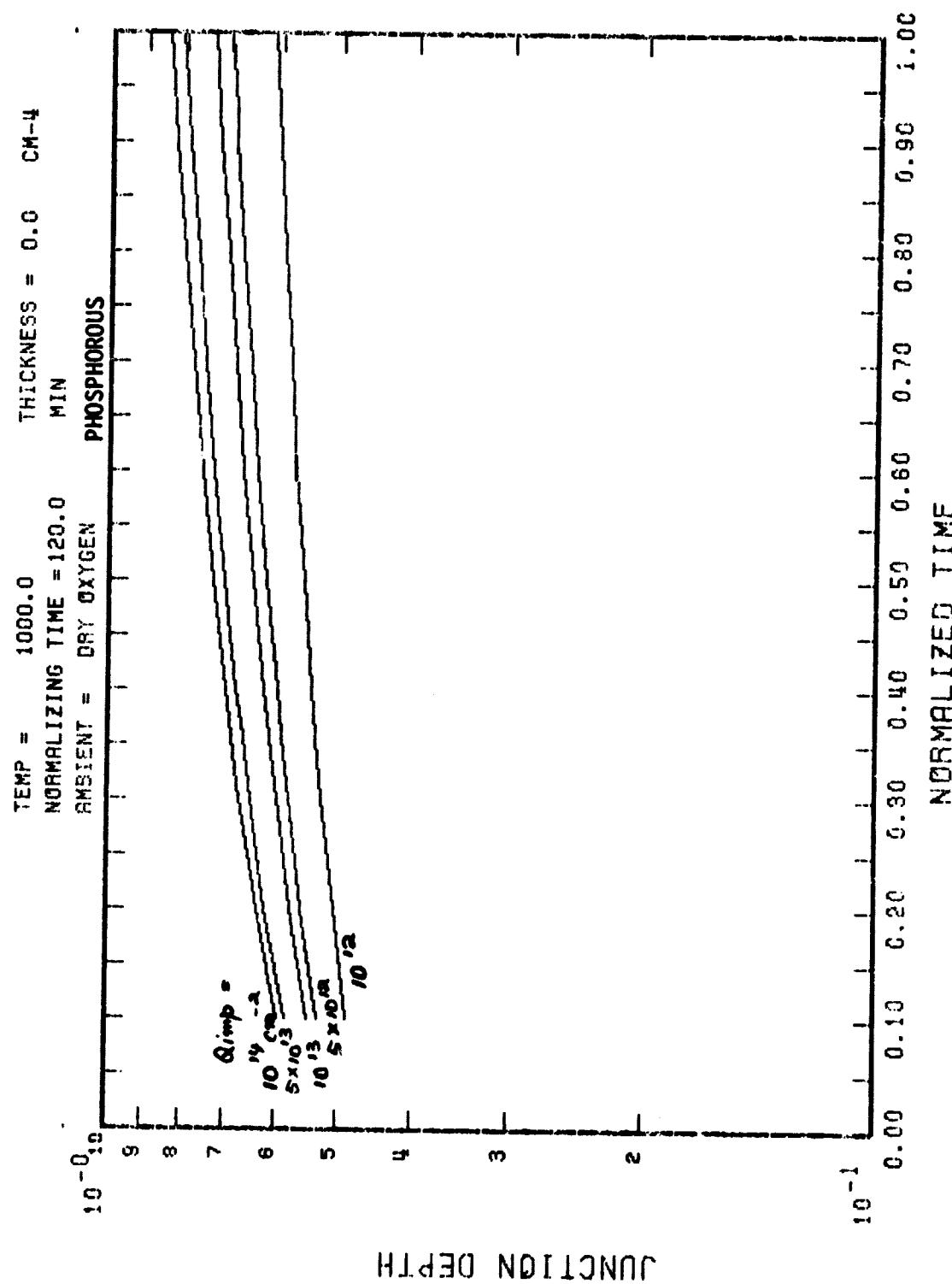


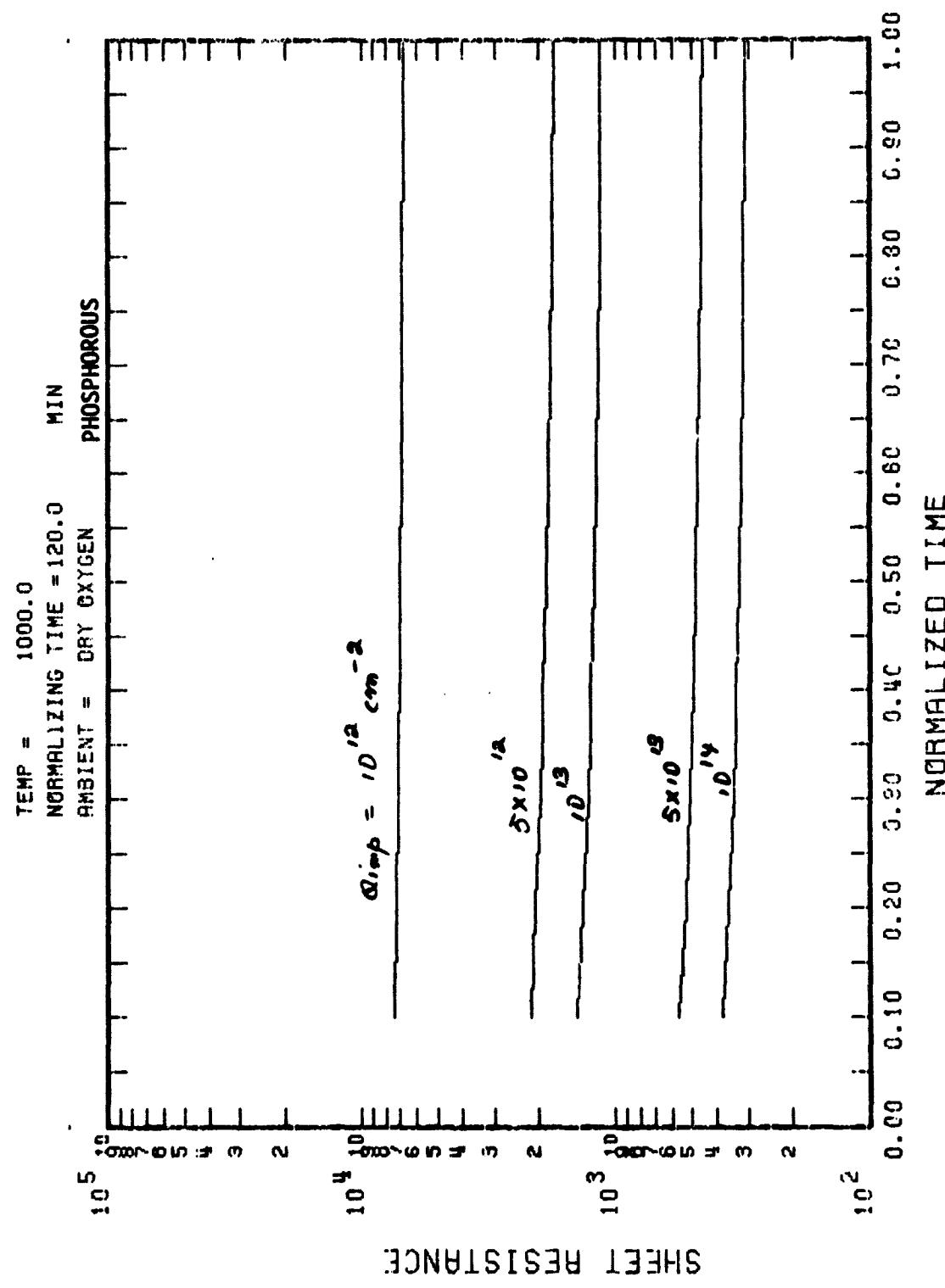
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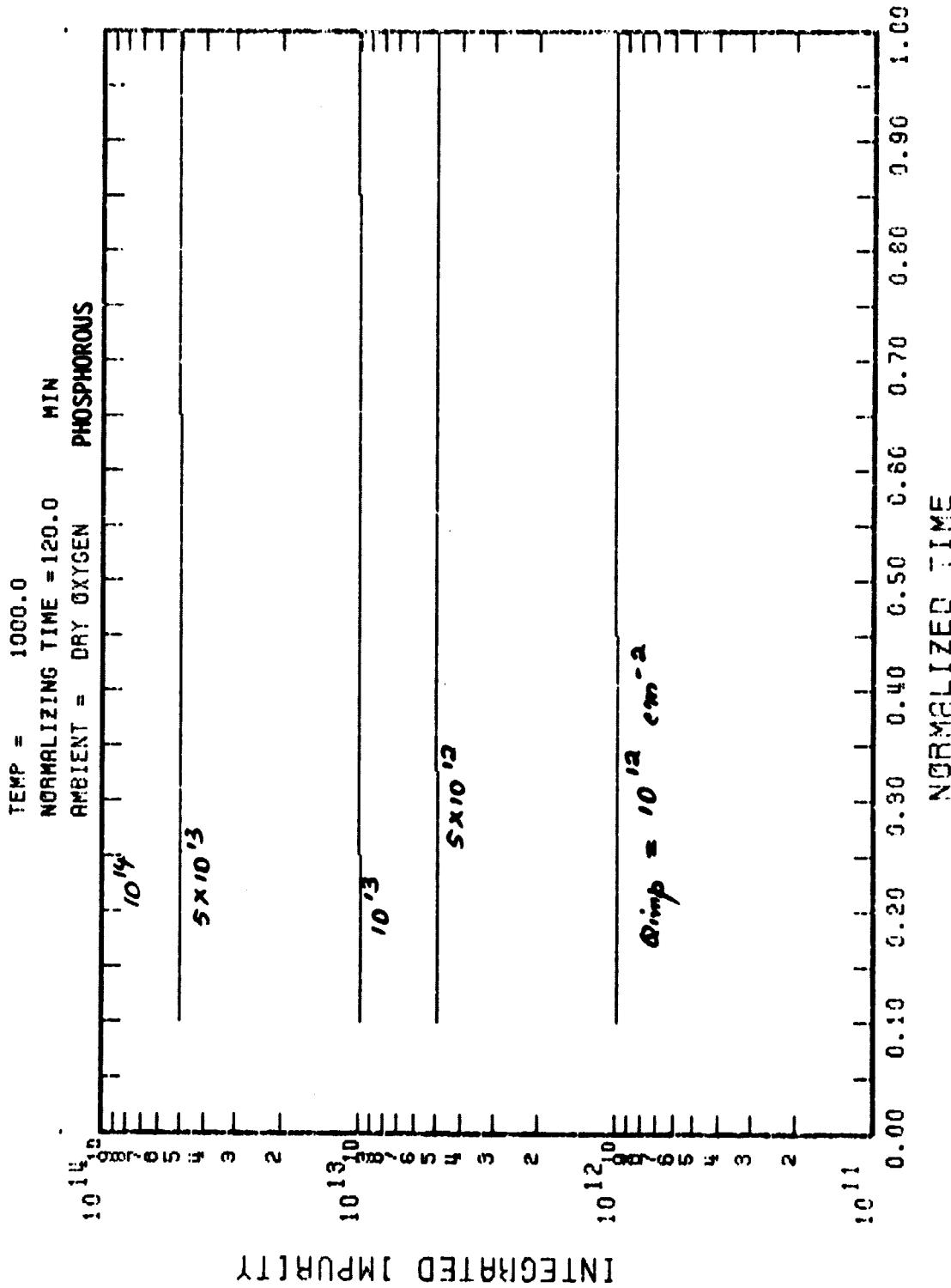


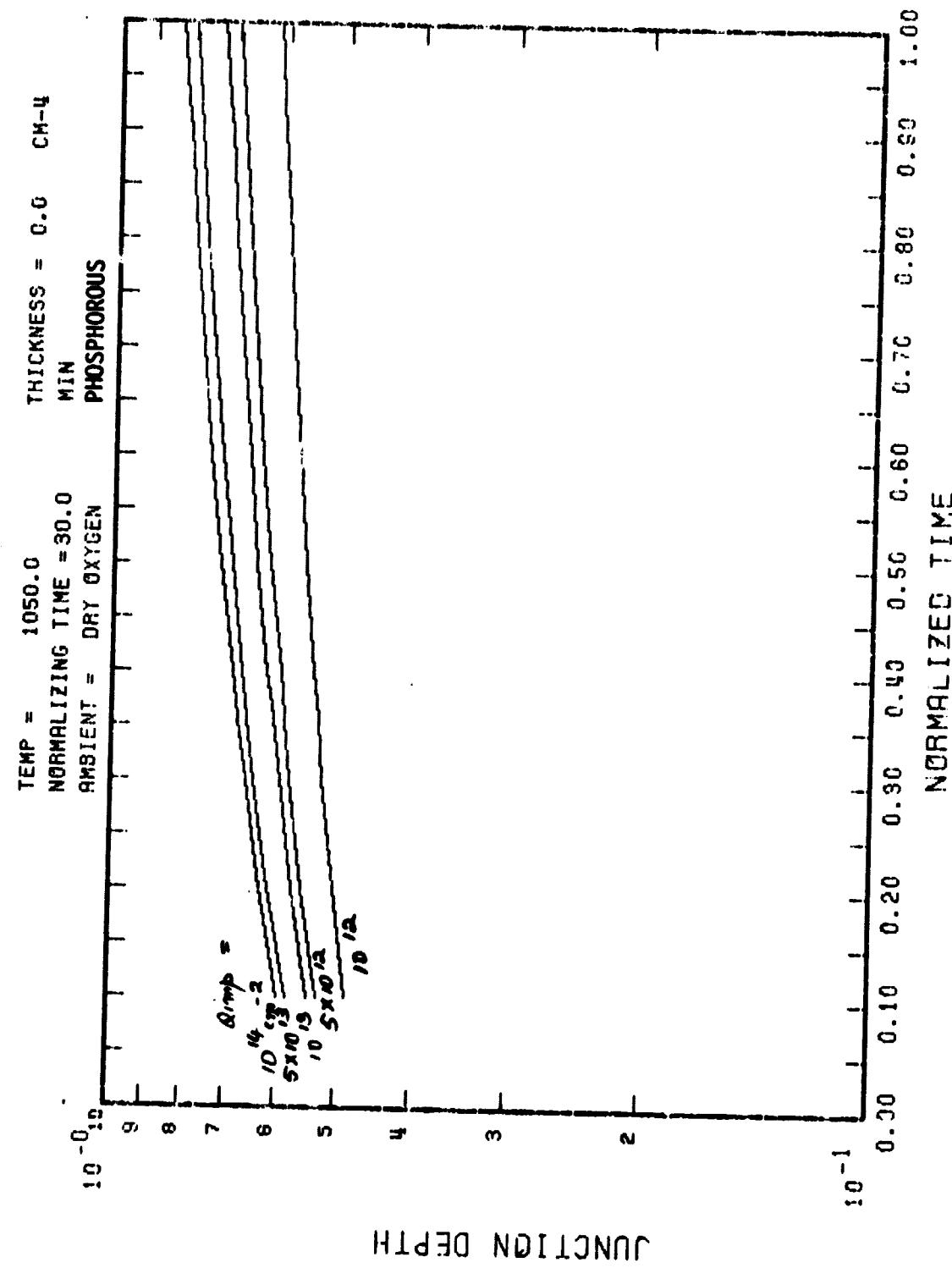


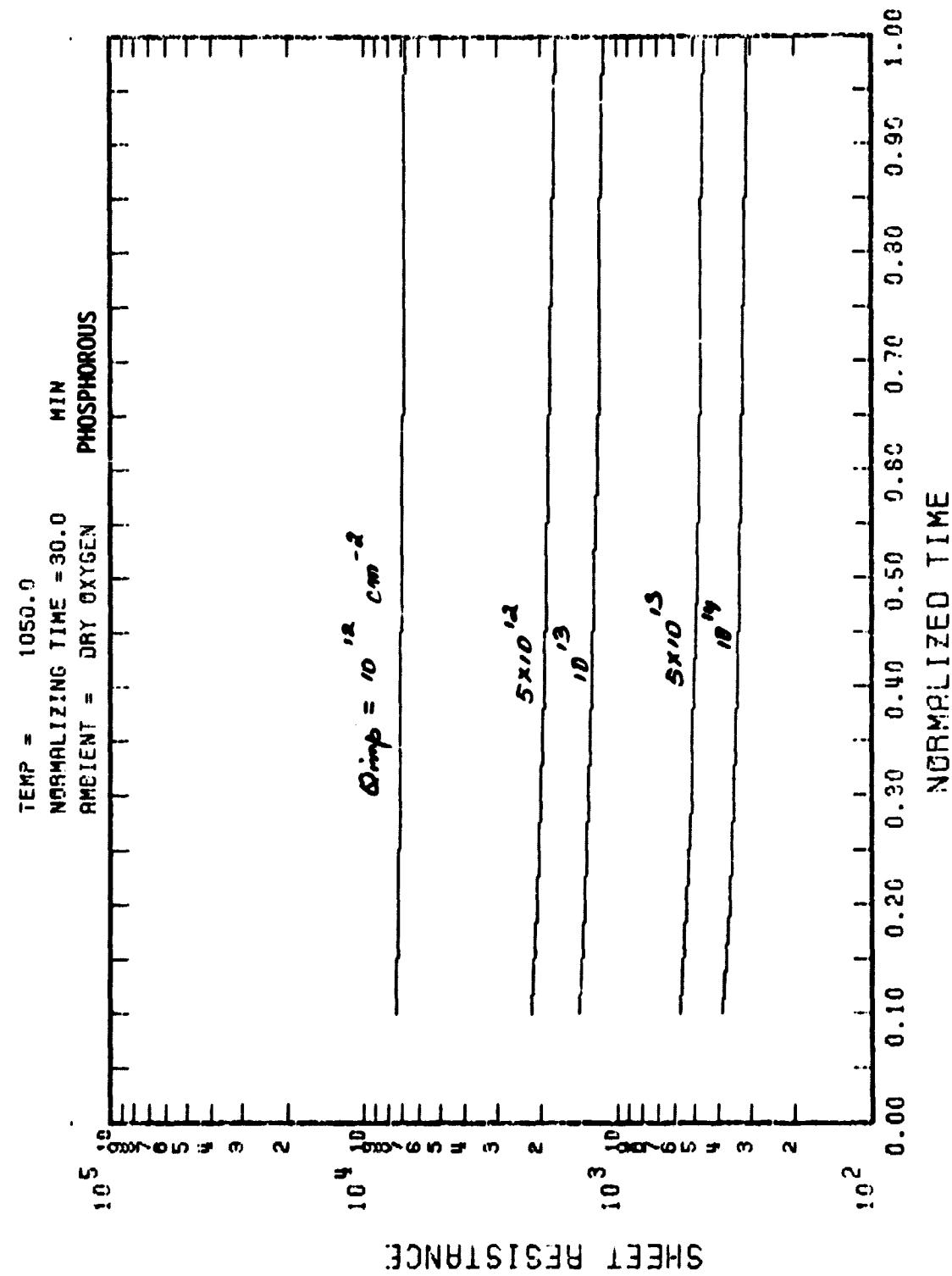


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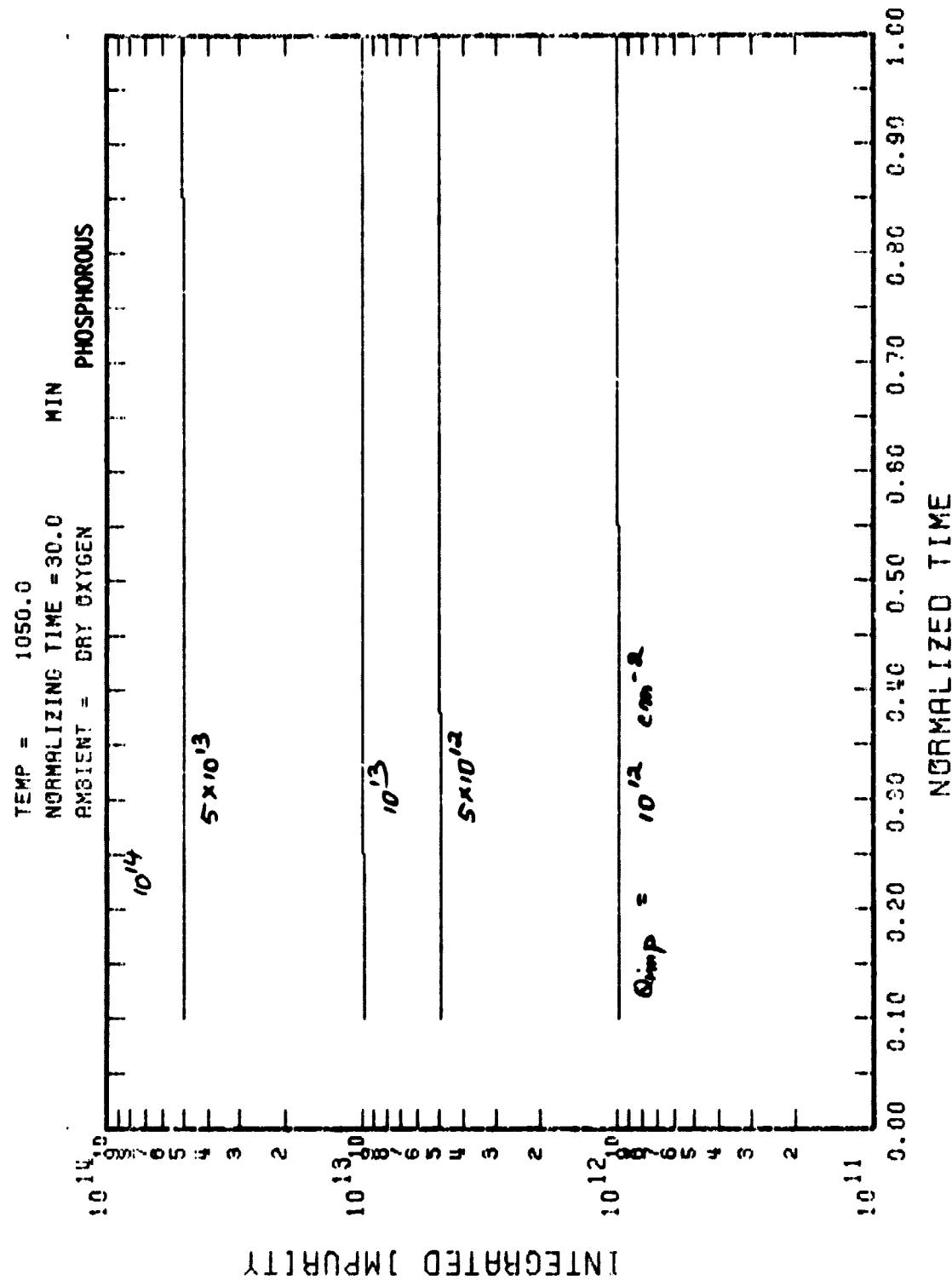


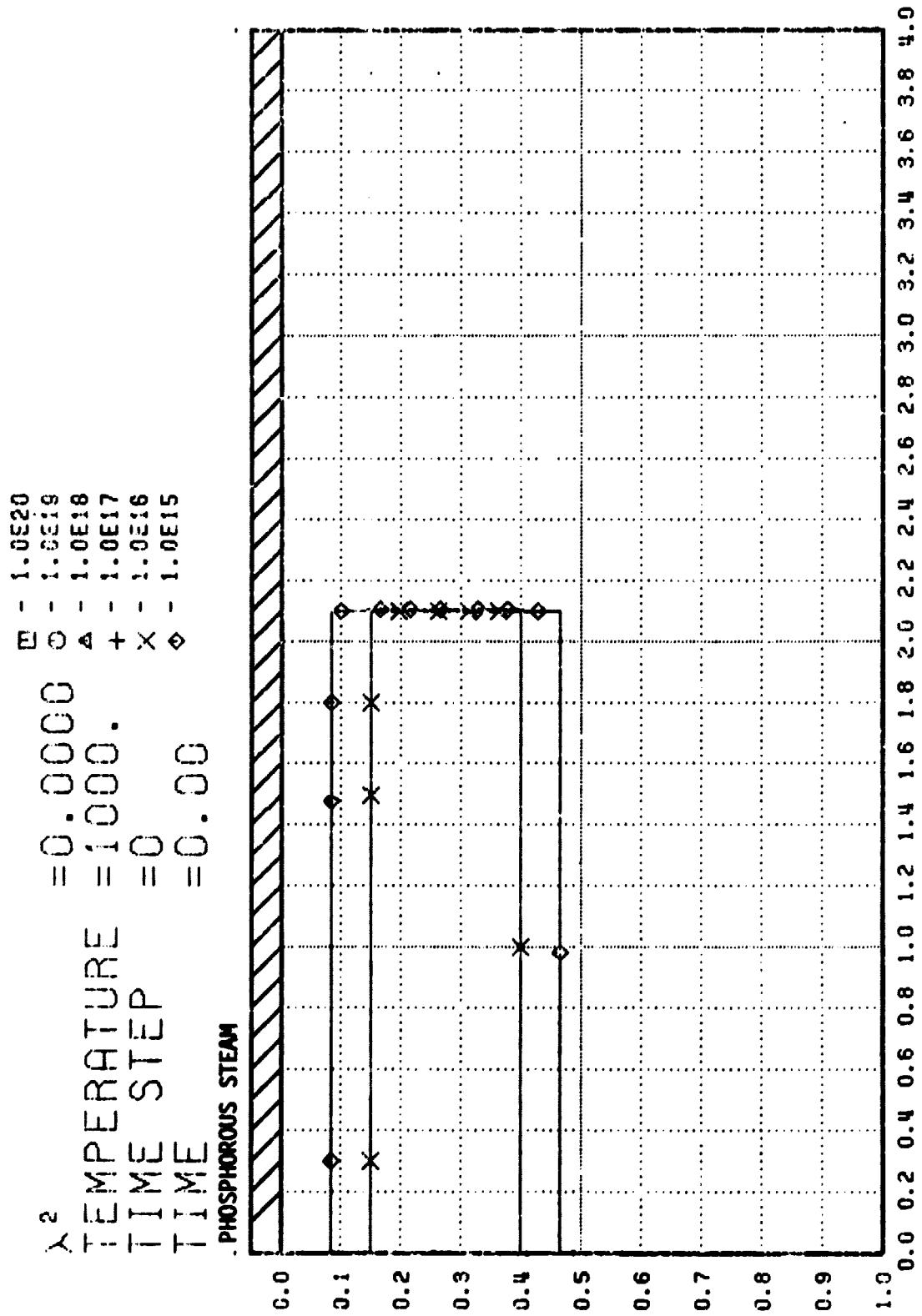


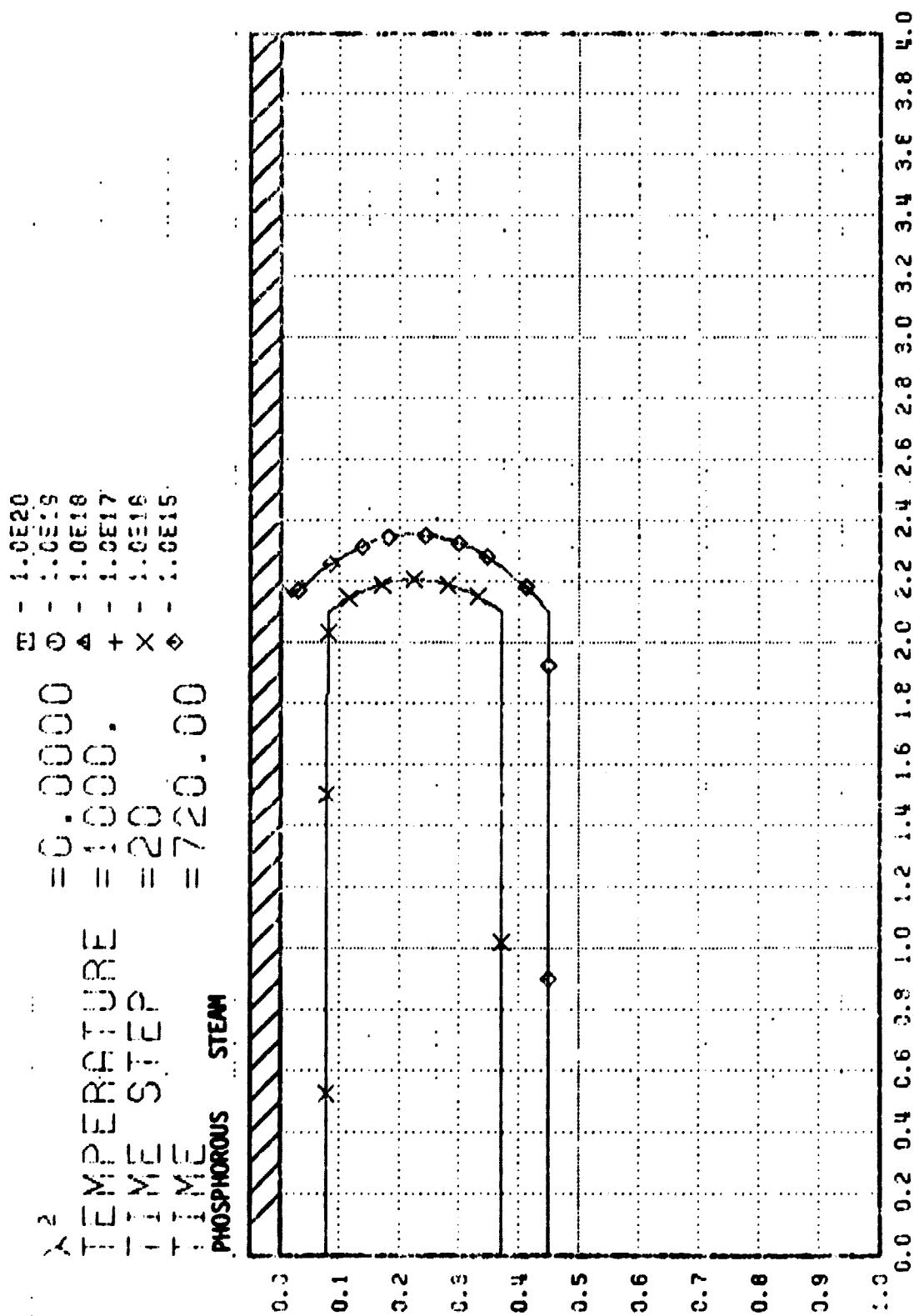
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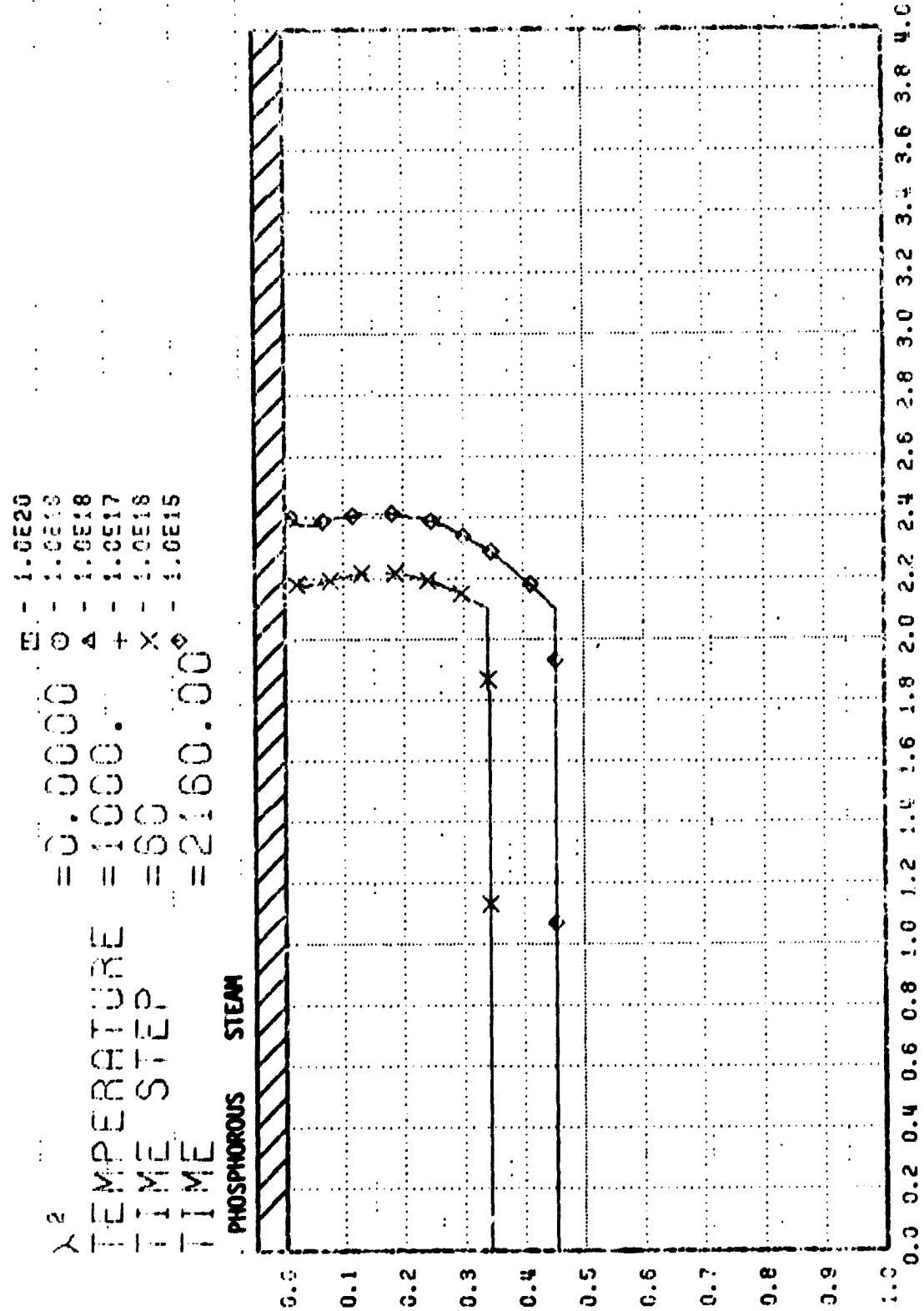






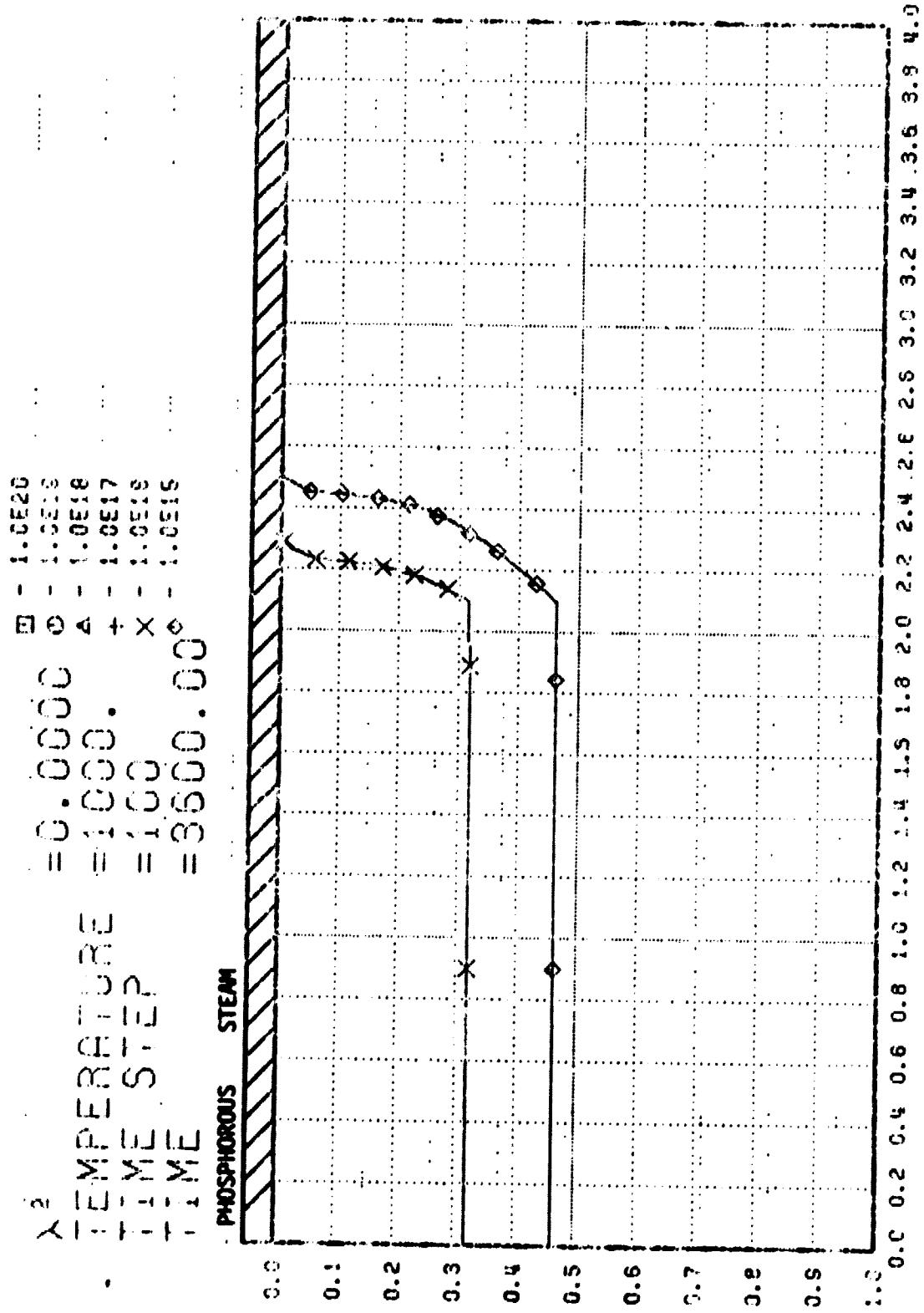
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B 39



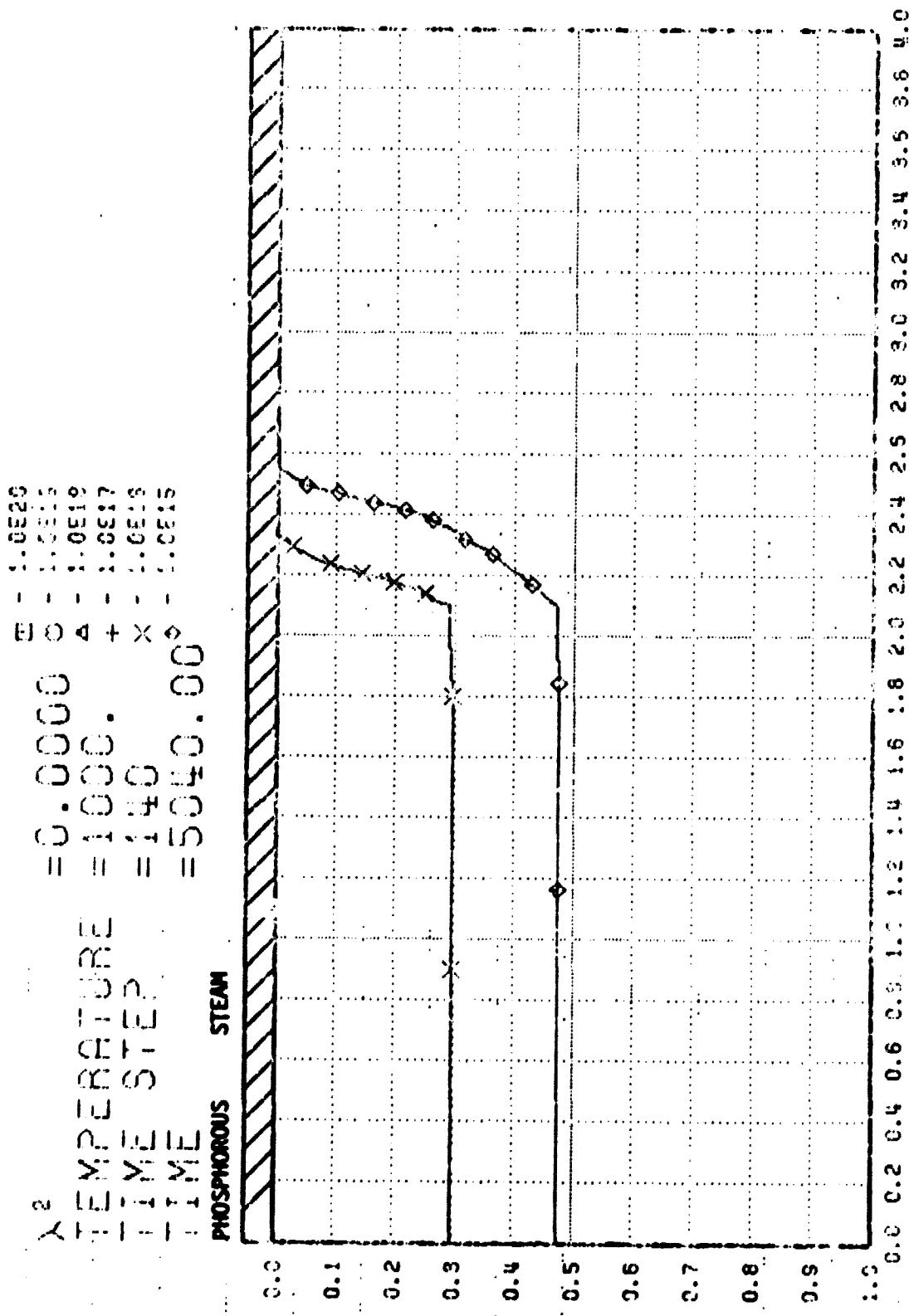
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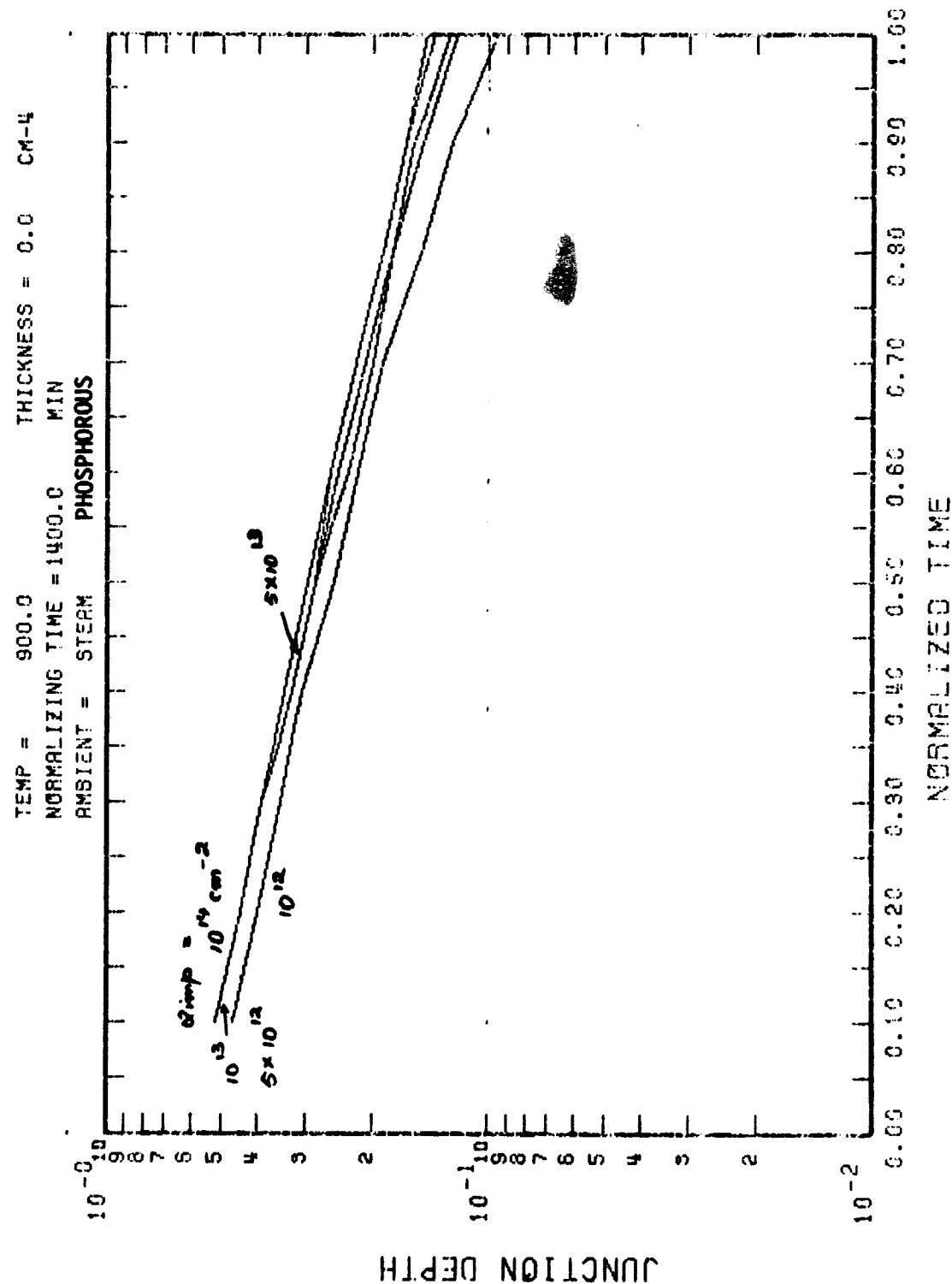
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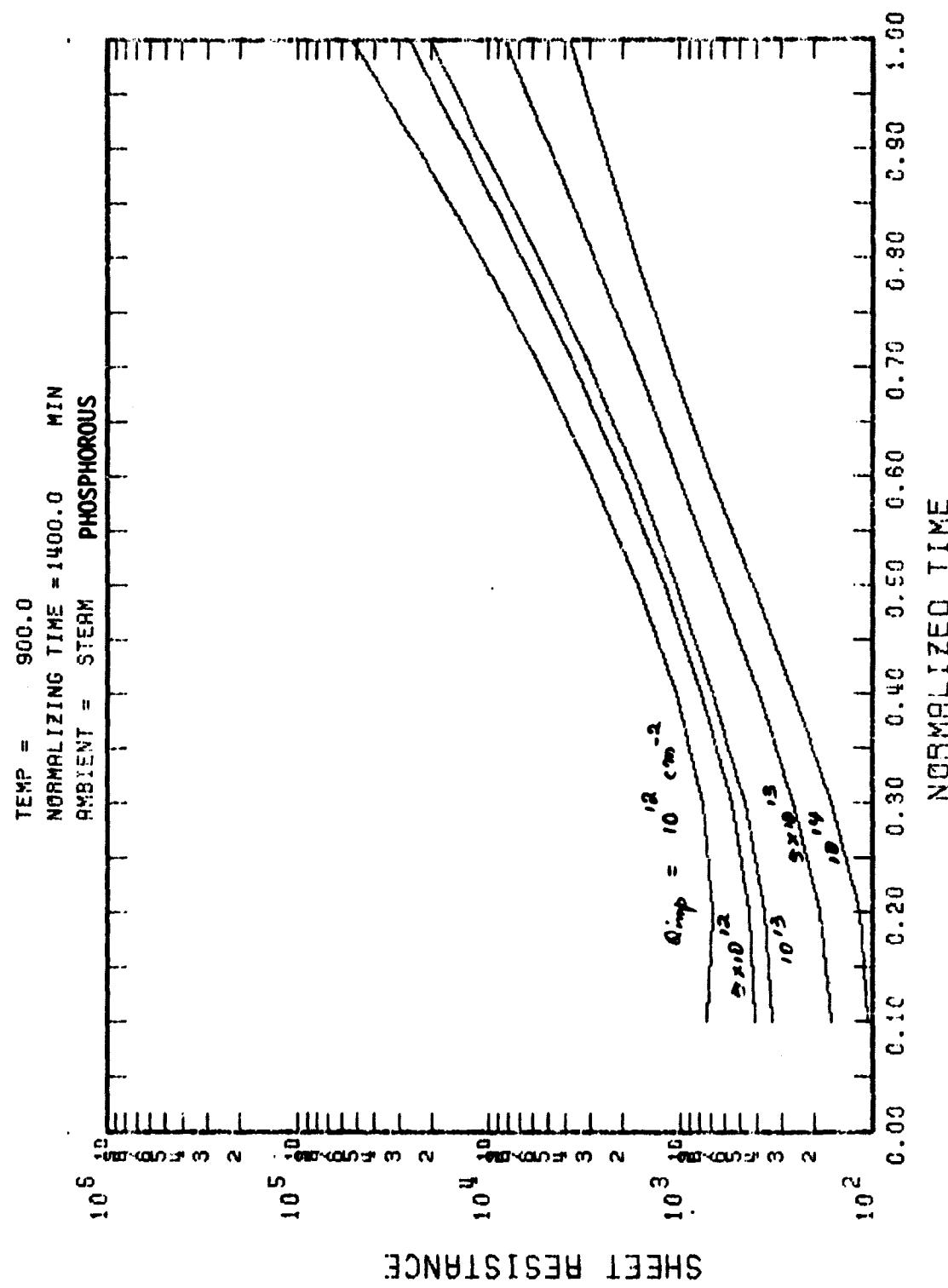


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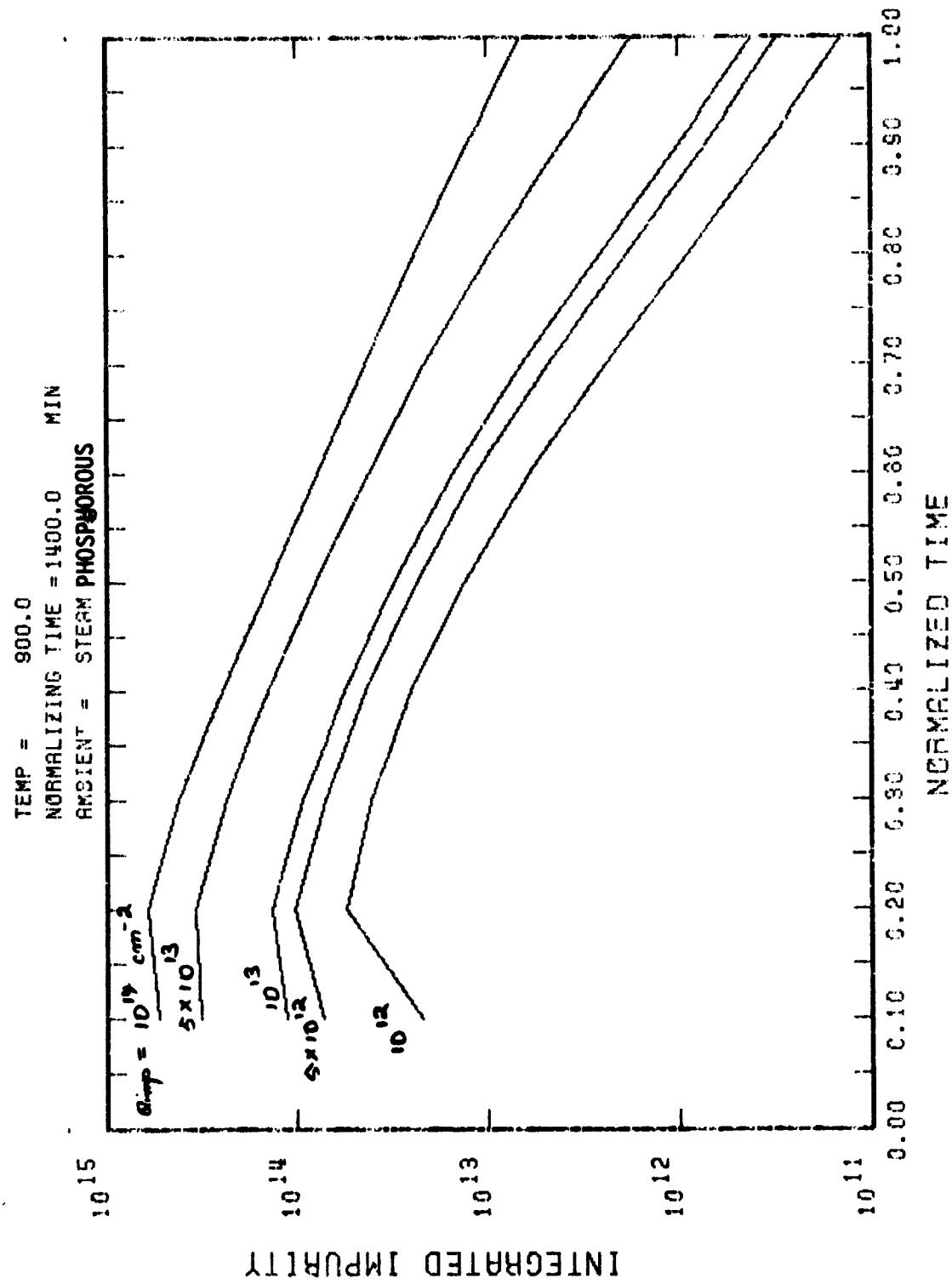
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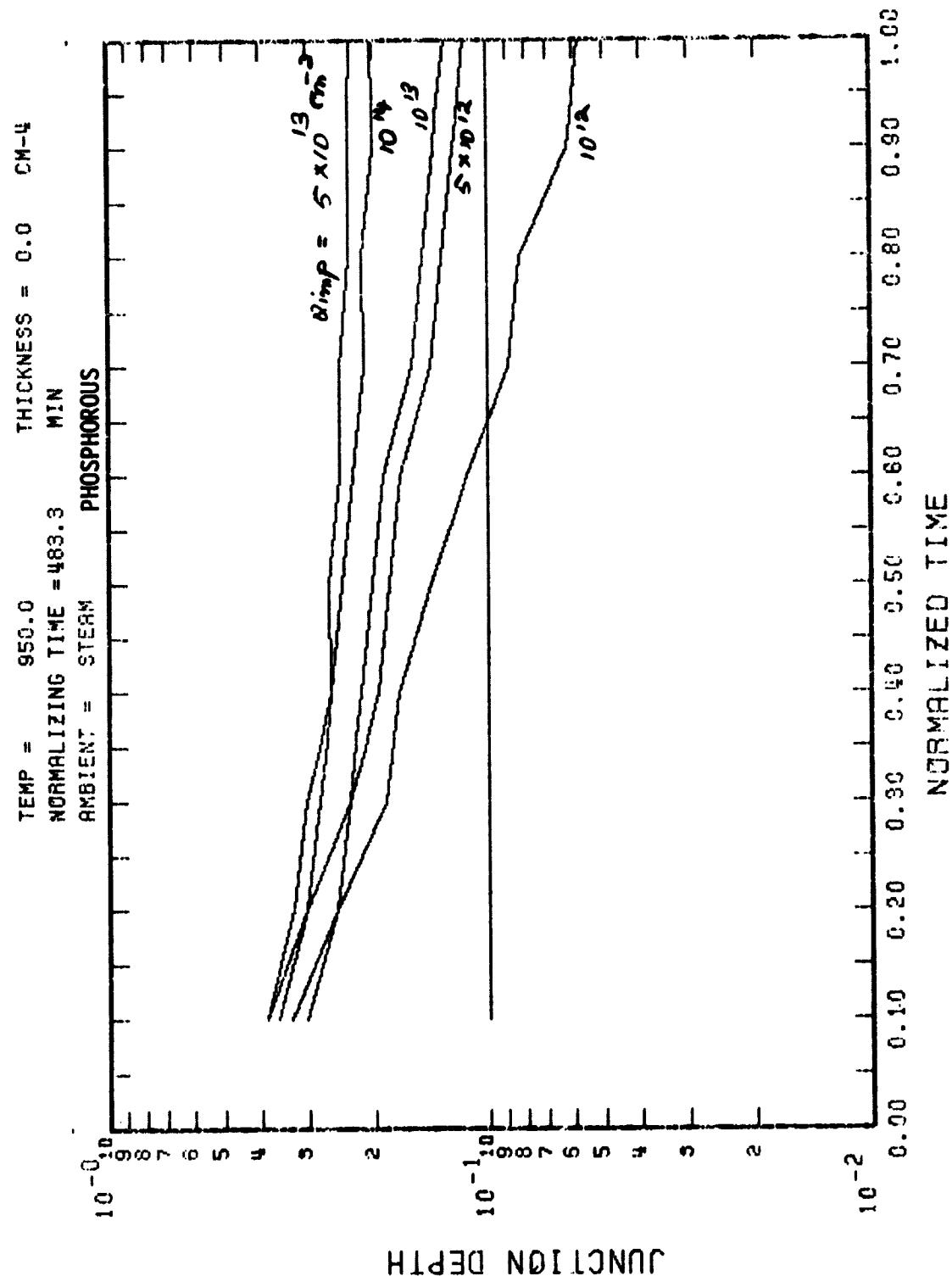
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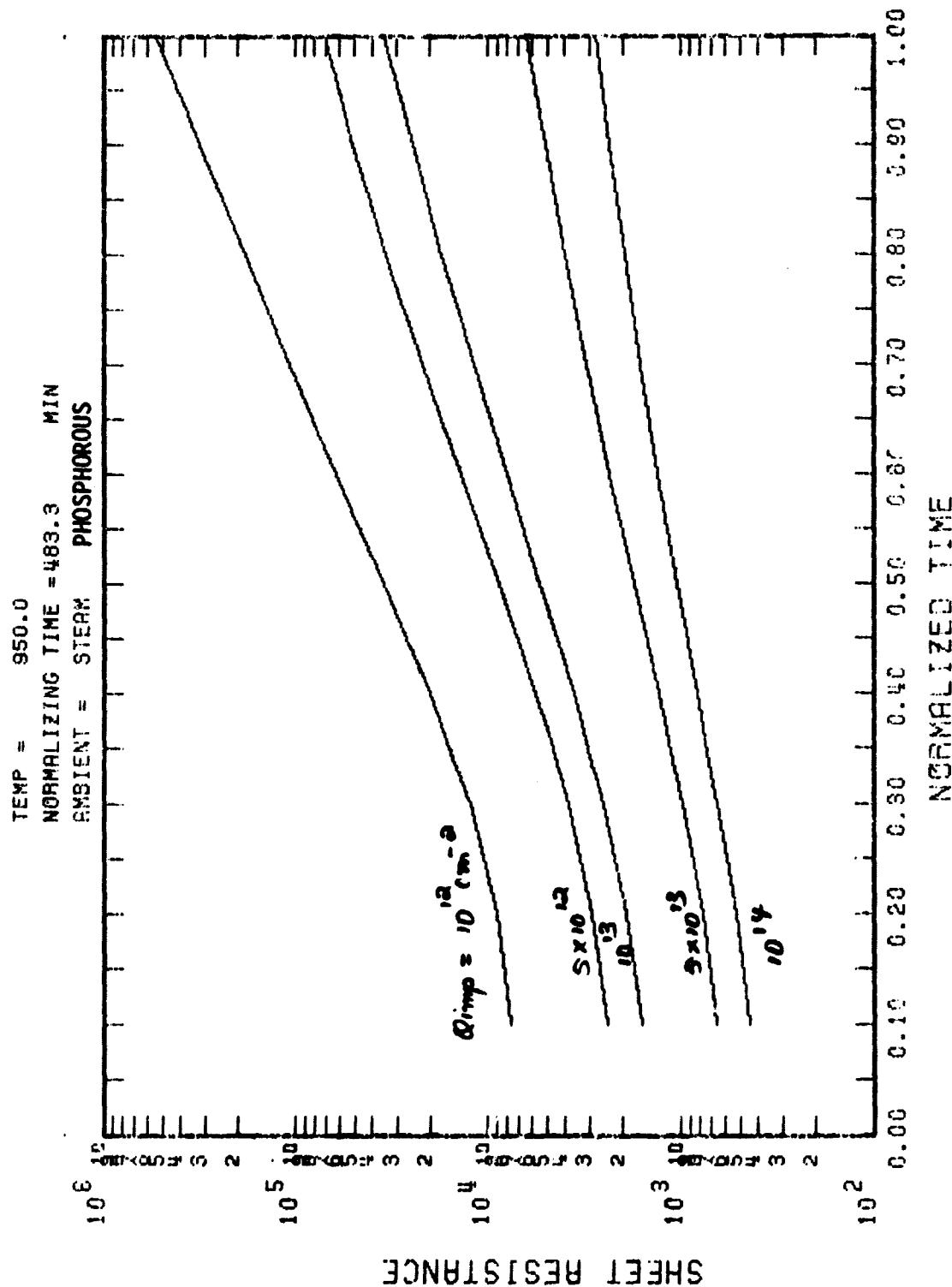
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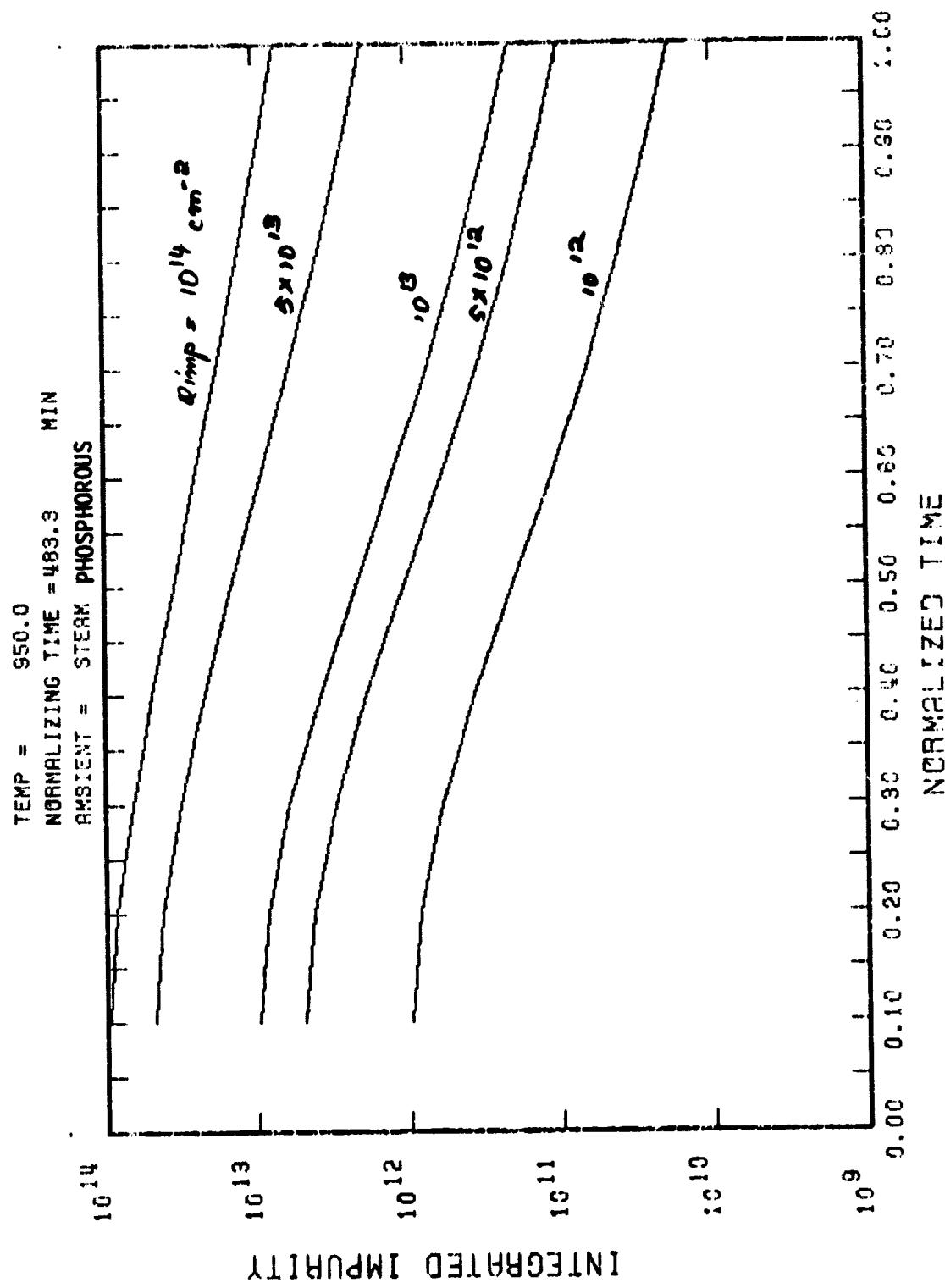
45
B 45





Y7

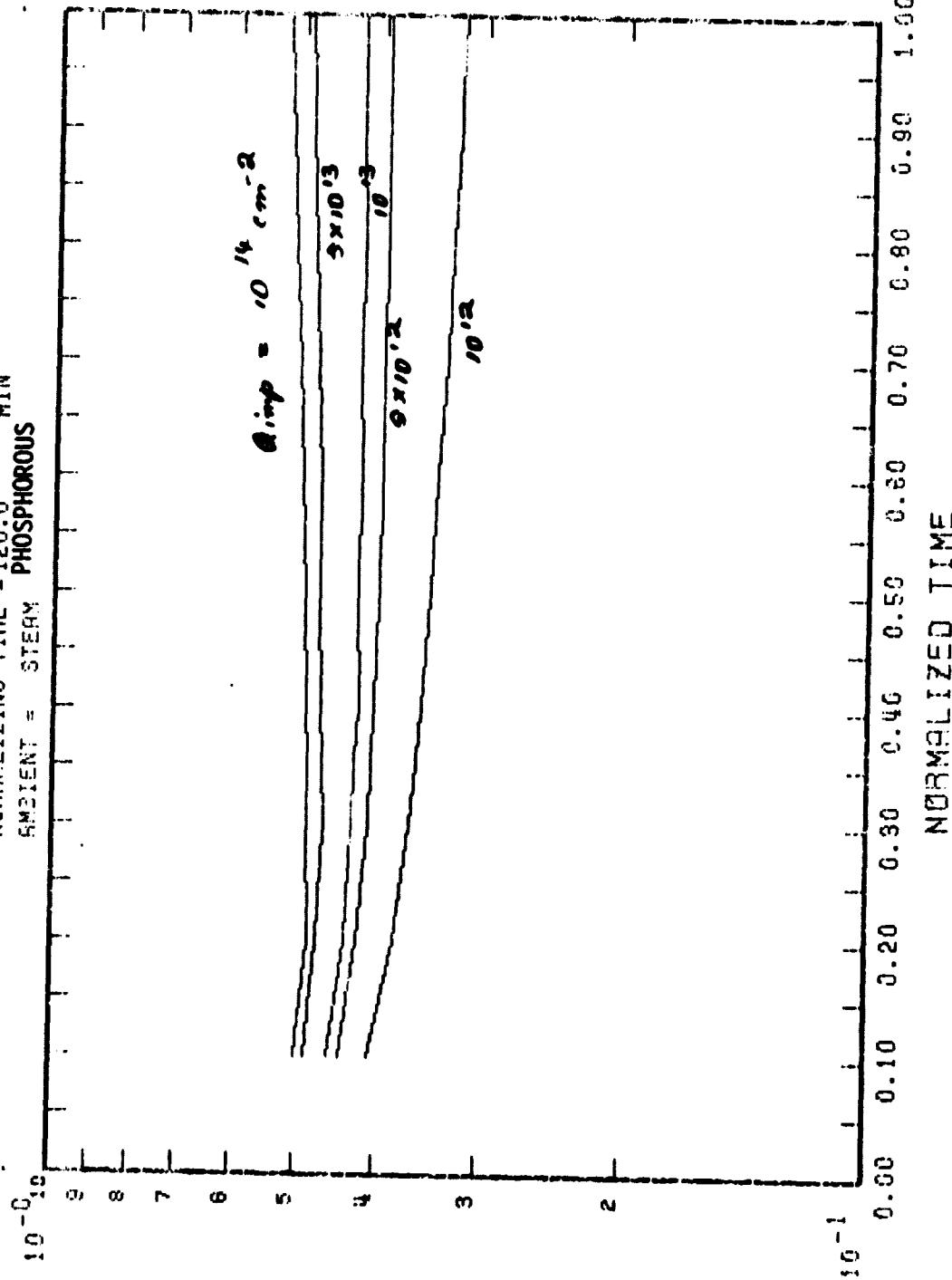
B 47



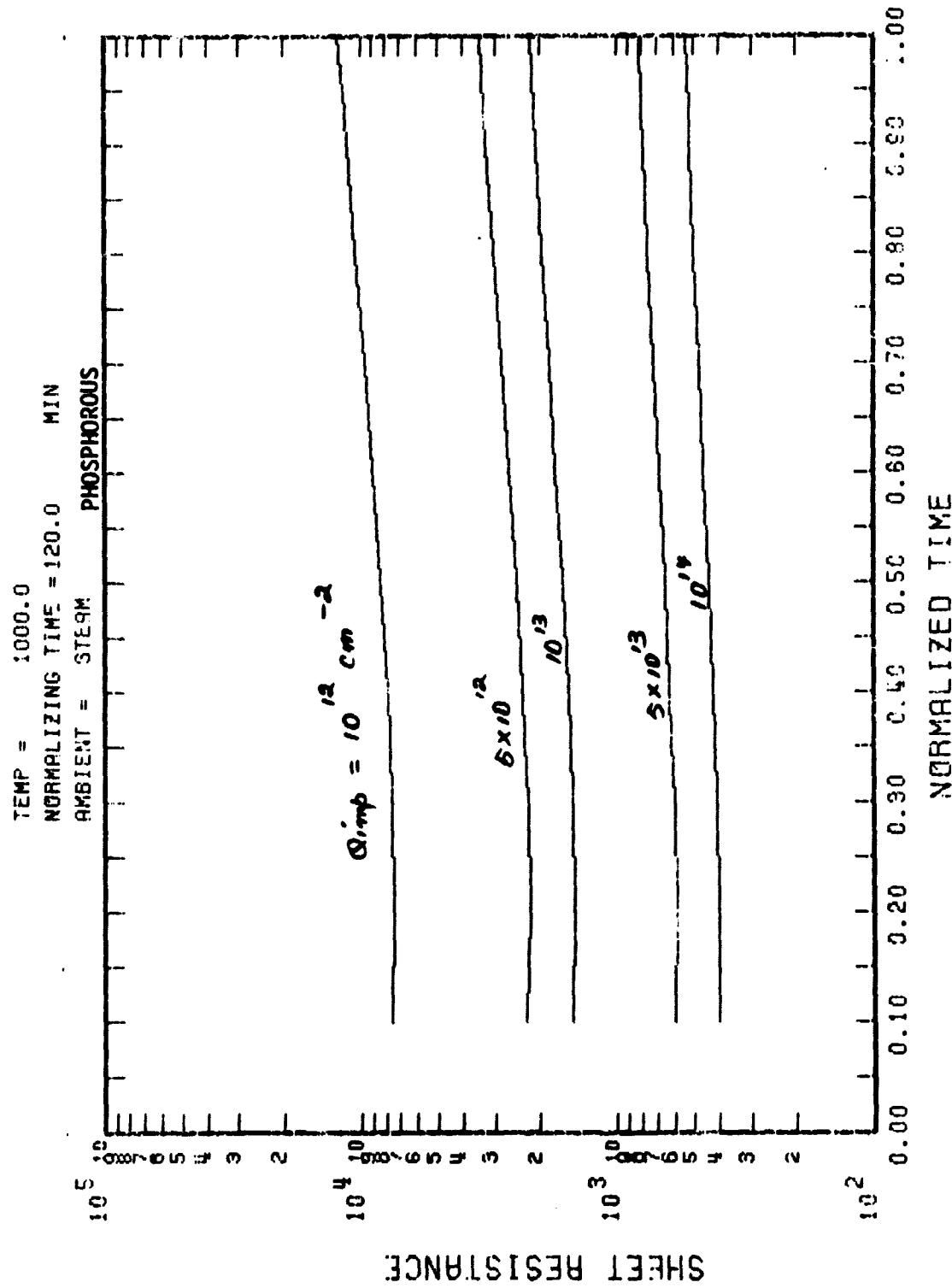
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B 48

TEMP = 1000.0 THICKNESS = 0.6 CM-4
NORMALIZING TIME = 120.0 MIN
AMBIENT = STEAM PHOSPHOROUS

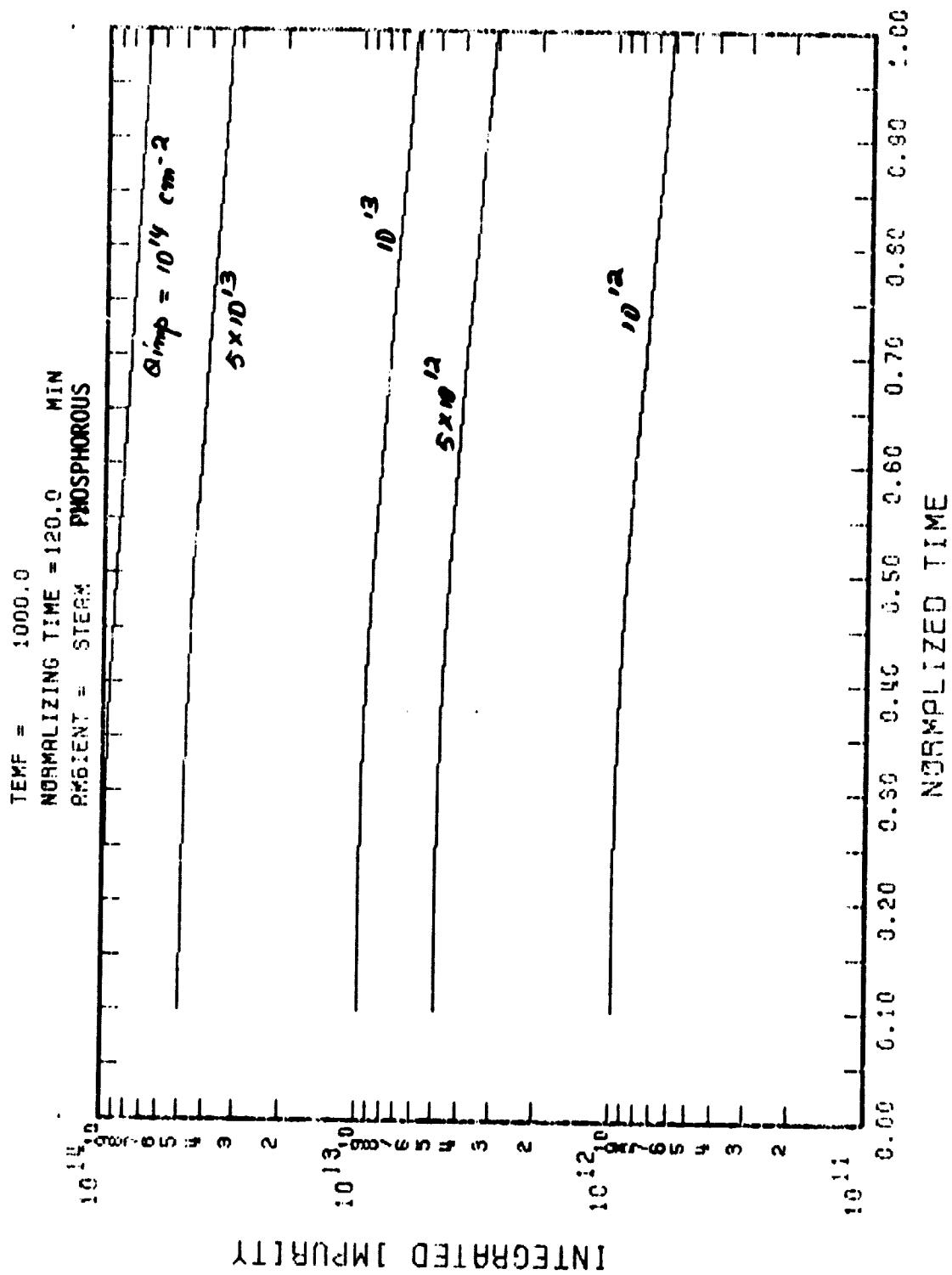


JUNCTION DEPTH



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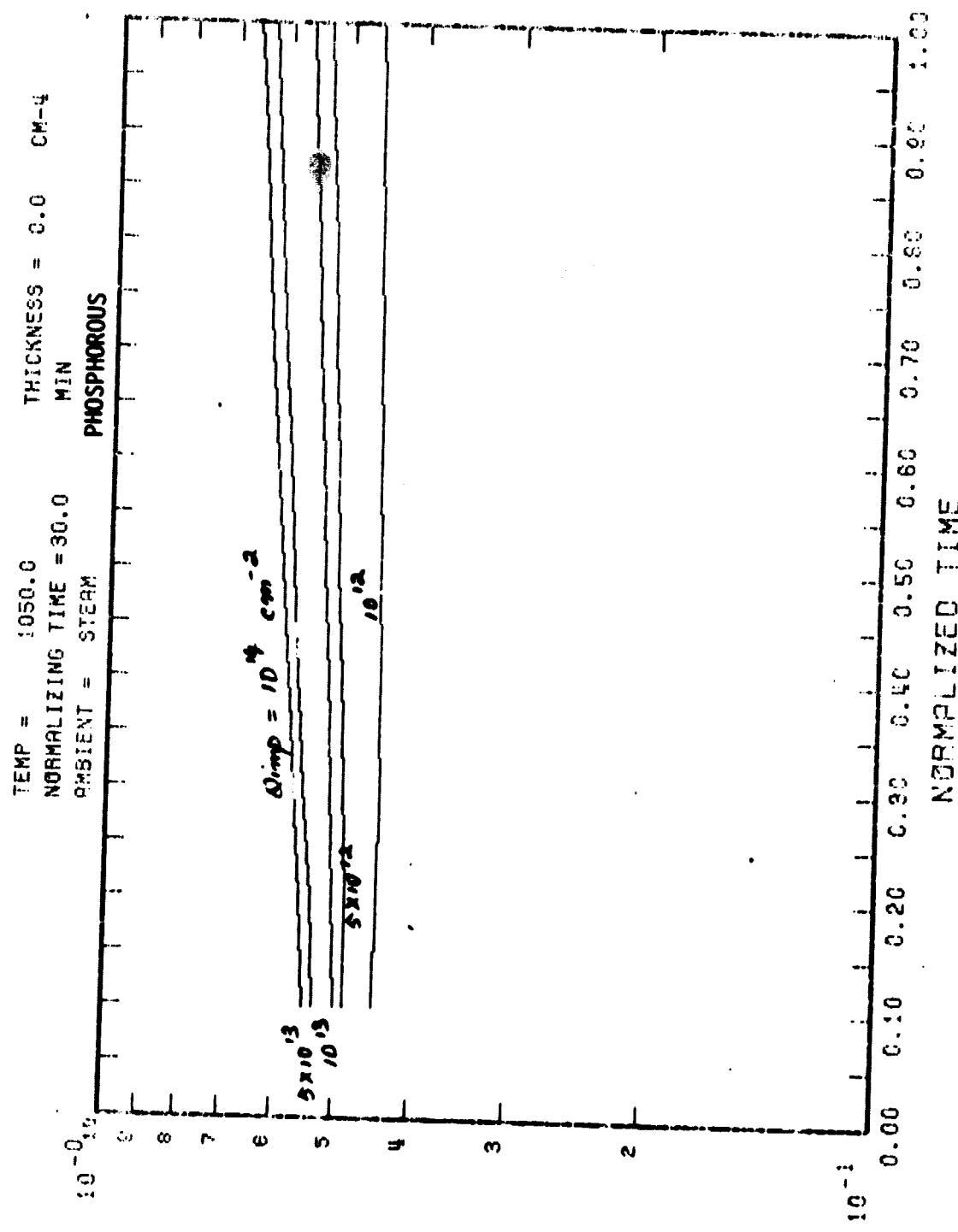
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51

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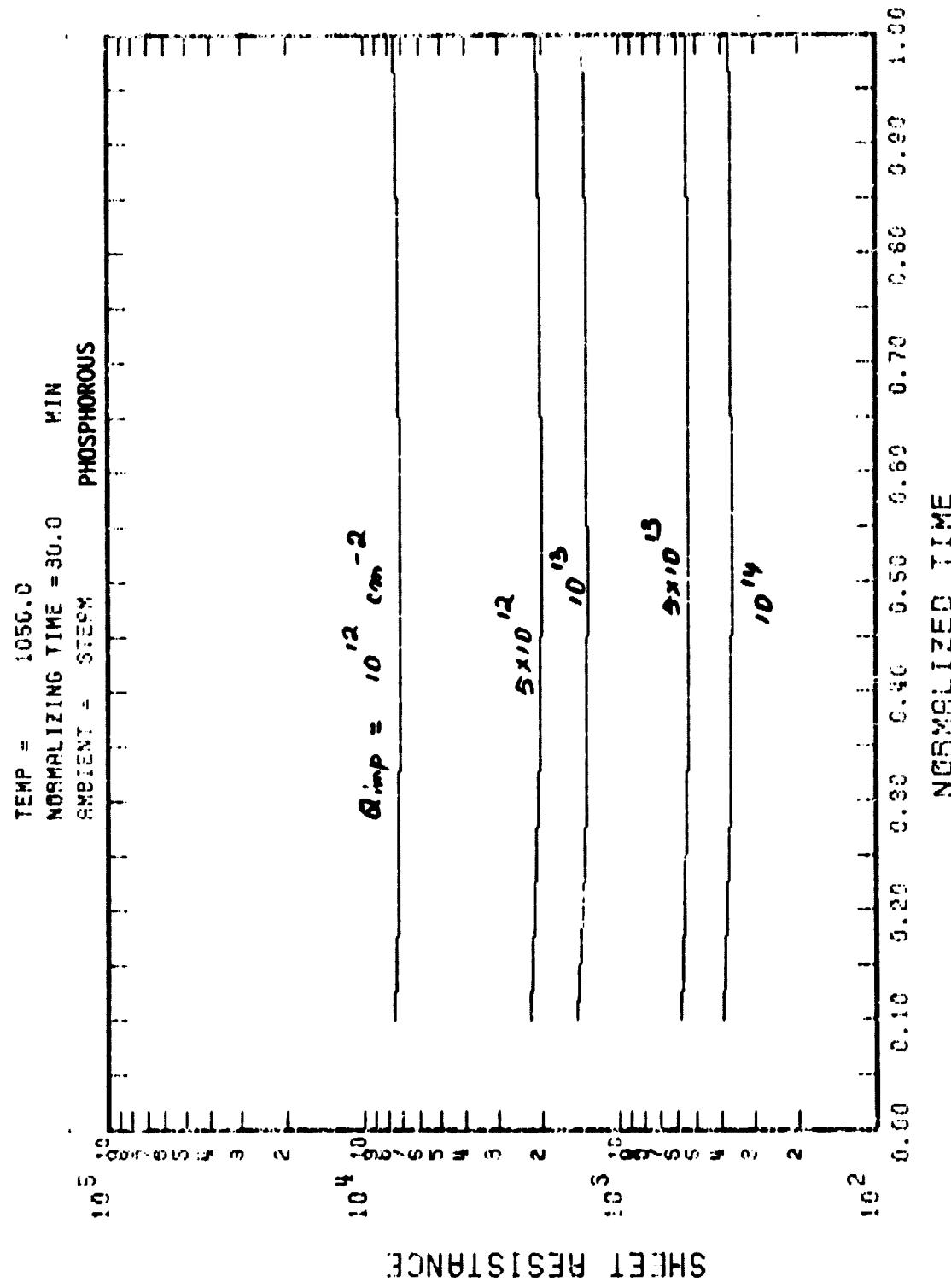
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JUNCTION DEPTH

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B 53

TEMP = 1050.0
NORMALIZING TIME = 30.0 MIN
AMBIENT = STEAM

PHOSPHOROUS

$d_{imp} = 10^{14} \text{ cm}^{-2}$

10^{14}

10^{13}

10^{12}

10^{11}

10^{10}

10^9

10^8

10^7

10^6

10^5

10^4

10^3

10^2

10^1

0.00 0.10 0.20 0.30 0.40 0.50 0.60 0.70 0.80 0.90 1.00 1.10 1.20 1.30

0.00 0.10 0.20 0.30 0.40 0.50 0.60 0.70 0.80 0.90 1.00 1.10 1.20 1.30

0.00 0.10 0.20 0.30 0.40 0.50 0.60 0.70 0.80 0.90 1.00 1.10 1.20 1.30

INTEGRATED IMPURITY

INTEGRATED MPURITY

```

1 C *** SHRFJN PLOT PROGRAM ***
2 C
3 C *** DATA DEPK ***
4 C
5 C *** 1ST CARD
6 C   NPIT = # OF DATA SETS FOR DIFF VALUES OF IMPLNT, DOSES)
7 C   NSTP1 TO NSTPS = # OF TIME STEPS FOR A VALUE OF NPITMAX. 5 VALUES)
8 C   FIELD 8110
9 C *** 2ND CARD, 4TH AND 6TH CARD
10 C   X & Y AND Z AXES LABELS RESPECTIVELY
11 C   1ST, 2ND AND 3RD PLOTS ARE RS, X,J AND Q VS TIME PLOTS REPP.
12 C   JCOD = PUT A FOR NO GRID
13 C   FIELD 2(5A6),2110
14 C *** 3RD CARD
15 C   JGRID = # OF DIV. IN Y AXIS
16 C   IGRID = # OF DIV. IN X AXIS
17 C   NYSTP = SUBGRID DIV. IN Y AXIS
18 C   1 GIVES 1 SUBGD.
19 C   NXSTP = SUBGRID DIV. IN X AXIS
20 C   2 GIVES 1 SUBGD.
21 C   YMINV = MIN VAL IN Y AXIS
22 C   YMAXV = MAX VAL IN Y AXIS
23 C   XMINV = MIN VAL IN X AXIS
24 C   XMAXV = MAX VAL IN X AXIS
25 C   FIELD 4(10,4E10.5)
26 C   DIMENSION RS(10,1C0),XJ(10,100),Q(10,100),TIME(10,100)
27 C   DIMENSION X(10,100)
28 C   DIMENSION IX(5),IV(5),IL(2),XO(10,100)
29 C *** READ IN DATA
30 C   READ 100,NPIT,NSTP1,NSTP2,NSTP3,NSTP4,NSTPS
31 C   DO 10 I=1,NPIT
32 C   IF(I,FQ,1) NSTP=NSTP1
33 C   IF(I,FQ,2) NSTP=NSTP2
34 C   IF(I,FQ,3) NSTP=NSTP3
35 C   IF(I,FQ,4) NSTP=NSTP4
36 C   IF(I,FQ,5) NSTP=NSTP5
37 C   DO 10 J=1,NSTP
38 C   READ(14,104) JMAX,IAMBNT
39 C   READ(14,101) TEMP,XMAX,DELT,DFLY,VDIST
40 C   READ(14,101) RS(1,J),X(1,J),XJ(1,J),Q(1,J),TIME(1,J),XO(1,J)
41 C   IF(IAMBNT,EQ,1) I1(1)=DRY OR
42 C   IF(IAMBNT,EQ,1) I1(2)=YGEN
43 C   IF(IAMBNT,EQ,2) I1(1)=STEAM
44 C   IF(IAMBNT,EQ,2) I1(2)=
45 C   IF(IAMBNT,EQ,3) I1(1)=NITROG
46 C   IF(IAMBNT,EQ,3) I1(2)=EN
47 C
48 C   101 FORMAT(1H0,1D15.9)
49 C   102 FORMAT(2(5A6),2110)
50 C   103 FORMAT(4(10,4E10.5))
51 C   104 FORMAT(1H0,8110)
52 C   105 FORMAT(2A6)
53 C   400 FORMAT(1H0,10X,'XMIN = ',5X,'XMAX = ',5X,'YMIN = ',5X,'YMAX = ',5X)
54 C   //1H0,3X,4(F10.5,14))
55 C
56 C   DATA HGT,XMAX,YMAX/0.0875,7.05/
57 C   THMAX=TMAX/600
58 C   IC=10
59 C *** INITIATE THE PLOT
60 C   DO 11 N=1,3
61 C   READ 102,(IX(1),I1(1),I1(2),(IV(1),I1(1),I1(2)),JCOD
62 C   READ 1C3, JGRID, JCHD, NYSTP, NXSTP, YMINV, YMAXV, XMINV, XMAXV
63 C   PRINT 400,XMINV,XMAXV,YMINV,YMAXV
64 C   IF(JCOD,NE,0) JCHD=2
65 C   IF(JCOD,LE,0) JCHD=3
66 C   CALL PLOTS(10,0,1C0)
67 C   CALL PLOT(1,5,1,C,-3)
68 C *** DRAW BORDER
69 C   CALL PLOT(0,0,YMAXZ,-1)
70 C   CALL PLOT(XMAX,YMAXZ,-1)
71 C   CALL PLOT(XMAX,0,YMAXZ,-1)
72 C   CALL PLOT(0,0,0,YMAXZ,-1)
73 C *** DRAW GRID
74 C   VDIV=YMAX/F1(DATL,IC)
75 C   JK=1
76 C   DO 12 J=1,IC,NYSTP
77 C   DO 13 I=1,1C,NXSTP
78 C   VSPC=ALOG10(IFLOAT(JJK))>VDIV
79 C

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80      CALL PLOT(0.0,VSPP,3)
81      CALL PLOT(0.12,VSPP,2,0)
82      CALL PLOT(XMAX=0.12,VSPP,1,0)
83      13 CALL PLOT(XMAX,VSPP,2,0)
84      12 JK=JK+10
85      IGRID1=IGRID0XSTP
86      IGRID2=IGRID1-1
87      XDIV=XMAX/FLOAT(IGRID1)
88      DO 14 J=1,IGRID2
89      XSPC=FLOAT(J)*XDIV
90      CALL PLOT(XSPC,0.0,3)
91      CALL PLOT(XSPC,0.12,2,0)
92      CALL PLOT(XSPC,XMAX=0.12,1,0)
93      14 CALL PLOT(XSPC,VSPP,2,0)
94      C *** AXES NUMBERS
95      VAL1YMINV
96      JK=1
97      JGRD1=YGRD0+1
98      DO 16 J=1,JGRD1
99      C,NYSTP
100     IF(1.0E-12,JGRD1,AND,J,NE:1) GO TO 17
101     VSPP=ALOG10(FLOAT(J)*JK)/XDIV
102     VSPP1=VSPP
103     IF(J,0.1) GO TO 100
104     VAL1YFLOAT1
105     CALL NUMBER(-0.10,VSPP1,.0R,VAL,0.,-1)
106     GO TO 17
107 200 VAL2=ALOG10(VAL1)
108     CALL NUMBER(-0.66,VSPP1,0.10,10.,0.,-1)
109     CALL NUMBER(-0.38,VSPP1,0.09,0.1,VAL2,0.,-1)
110     17 CONTINUE
111     VAL1=VAL1+1N.
112     JK=JK+10
113     XDIV=XMAX/FLOAT(IGRID1)
114     IGRID3=IGRID0+1
115     DO 18 J=1,IGRID3
116     XSPC=(J-1)*XDIVXSTP
117     XSPC1=XSPC-0.2
118     VAL1XVAL1+1
119     C *** PUT LABELS
120     CALL NUMBER(XSPC1,-0.20,0.1,VAL,0.0,2)
121     CALL SYMBOL(-0.8,1.0,0.1313,Y,90.,30)
122     CALL SYMBOL(2.00,0.0,0.1313,IX,0.,30)
123     CALL SYMBOL(2.0,0.5,0.1HAT,TEMP,0.,0.,7)
124     CALL NUMBER(3.0,0.5,0.1HAT,TEMP,0.,1)
125     CALL SYMBOL(2.0,0.5,0.1HAT,'NORMALIZING TEMP ='
126     * 0.0,32) MINUS
127     CALL NUMBER(3.0,0.5,0.1HAT,THMAX,0.,1)
128     CALL SYMBOL(2.0,0.5,0.1HAT,'AMBIENT = ',0.,10)
129     CALL SYMBOL(3.0,0.5,0.1HAT,IL,0.,12)
130     IF(N,0.2) CALL SYMBOL(4.0,0.5,0.1HAT,'THICKNESS = '
131     * 0.0,23) CM=4"
132     IF(N,0.2) CALL NUMBER(5.0,0.5,0.1HAT,YDIST,0.,1)
133     C *** DRAW CURVES
134     YLOG=YMAX/XMAX
135     XVID=XMAX/XMAX
136     YMVRD1/YTHINV
137     DO 22 J=1,NPLT
138     CALL PLOT(0.0,0.0,0.,3)
139     IF(1.0E-11,NSTP=NSTP1
140     IF(1.0E-21,NSTP=NSTP2
141     IF(1.0E-31,NSTP=NSTP3
142     IF(1.0E-41,NSTP=NSTP4
143     IF(1.0E-51,NSTP=NSTP5
144     DO 21 J=1,NSTP
145     IF(J,0.1) L=3
146     IF(J,NE,1) L=2
147     IF((AMBNT,NE,3), TIME(1,J)=TIME(1,J)/TIME(NPLT,NSTP)
148     XMOVE=TIME(1,J)*EV1
149     IF(N,0.3) GO TO 201
150     IF(N,0.2) GO TO 202
151     YMOVE=YLOG*ALOG10(RS(1,J)*YMVR)
152     GO TO 21
153     YMOVE=YLOG*ALOG10(B(1,J)*YMVR)
154     GO TO 21
155 202 YMOVE=YLOG*ALOG10(XJ(1,J)*YMVR)
156     21 CALL PLOT(XMOVE,YMOVE,L,0)
157     IF(N,NE,2) GO TO 22
158     CALL PLOT(0.0,0.0,3)
159     GO 23 J=1,NSTP

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```
160      IF(J.EQ.1) L=3
161      IF(J.NE.1) L=2
162      XMOVE=TIME(I,J)*XVI
163      X(I,J)=X(I,J)*(YDIST=0.45*X0(I,J))/1.E-4
164      IF(XI(I,J).LT.1.E-01) XI(I,J)=1.E-01
165      YMOVE=YLOG ALOG10(XI(I,J))*YHVR
166      23 CALL PLOT(XMOVE,YMOVE,L,0)
167      22 CONTINUE
168      CALL PLOT(0.,0.,999)
169      11 CONTINUE
170      STOP
171      END
```

```
1 CCRON=SN52(1),PARAH
2      SUBROUTINE PARAM(r,t)
3      C.....AFTER THAI AND MORIN AND HAITA.
4      C.....IMPLICIT DOUBLE PRECISION (A-H,O-Z)
5      C(I=1,515
6      2  FG=1.21*7.1E-10*SGRT(P1)*(T)**(-.5)
7      EG=EG/(8.62E-5*(T))
8      CIOLD=C1
9      C1=3.87E16*((T)**(1.5))*EXP(-EG/2.)
10     R=CIOLD/C1
11     IF(R.LT.0.995.AND.R.GT.1.005) GO TO 2
12     RETURN
13     END
14
15  C.....
```

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MICRON5052(1).G

```

1      DOUBLE PRECISION FUNCTION G(CN,J,J)
2      IMPLICIT DOUBLE PRECISION(A-H,O-Z)
3      C*****IRWIN'S CONDUCTIVITY FORMULAS.
4      C
5      IF(JJ.EQ.1) GO TO 3
6      IF(CN.GT.0.0) A=1.0
7      IF(CN.GT.0.0) B=7.2D-17
8      IF(CN.GT.1.0D+16) A=0.65
9      IF(CN.GT.1.0D+16) B=3.3D-11
10     IF(CN.GT.2.4D+18) A=0.832
11     IF(CN.GT.2.4D+18) B=1.47D-14
12     IF(CN.GT.1.5D+19) A=0.966
13     IF(CN.GT.1.5D+19) B=4.0D-17
14     GO TO 5
15
16     3   IF(CN.GT.0.0) A=1.0
17     IF(CN.GT.0.0) B=2.0D-16
18     IF(CN.GT.3.5D15) A=0.837
19     IF(CN.GT.3.5D15) B=6.97D-14
20     IF(CN.GT.1.0D17) A=0.543
21     IF(CN.GT.1.0D17) B=6.93D-9
22     IF(CN.GT.9.5D18) A=0.94
23     IF(CN.GT.9.5D18) B=2.0D-16
24     IF(CN.GT.6. D19) A=0.744
25     IF(CN.GT.6. D19) B=1.43D-12
26     IF(CN.GT.2.35D20) A=0.456
27     IF(CN.GT.2.35D20) B=1.04D-6
28
29     5   G = B*(CN**A)
30     RETURN
END

```

```

1 1CRON=SNS2(1),OXDATA
2      SUBROUTINE OXDATA(AMANT,ORINT,T,R,C,M,KB)
3
4      SURROUTINE FOR OXIDATION PARAMETERS AND SEGREGATION Cn-EFF!
5
6
7      IMPLICIT DOUBLE PRECISION(A-H,O-Z)
8      INTEGER AMANT,ORINT
9      DOUBLE PRECISION KB,M,M1,M3
10
11      IF(AMANT.EQ.1) GO TO 12
12      R=4.40277D-10*DEXP(-7945.74/T)
13      IF(ORINT.EQ.1) C=4.9458D-1*DEXP(-22184.07/T)
14      IF(ORINT.EQ.2) C=9.13546D-1*DEXP(-21835.313/T)
15      IF(ORINT.EQ.3) C=1.4000*DEXP(-22394.038/T)
16      GO TO 14
17
18      12 CONTINUE
19      R=1.58507D-9*DEXP(-13916.6449/T)
20      IF(ORINT.EQ.1) C=2.0093D-1*DEXP(-24118.9R/T)
21      IF(ORINT.EQ.2) C=4.33277D-1*DEXP(-24551.98/T)
22      IF(ORINT.EQ.3) C=7.09845D-1*DEXP(-24957.028/T)
23
24      14 CONTINUE
25      M1=33.3*DEXP(-0.57/(KR*T))
26      M3=20.0*DEXP(-0.57/(KR*T))
27      IF(ORINT.EQ.1) M=M1
28      IF(ORINT.EQ.2) M=(M1+M3)/2.0
29      IF(ORINT.EQ.3) M=M3
30      RETURN
31      END

```

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41CRON=S052(1),FRONT          C7
1      SUBROUTINE FRONT(I,MAXI,JMAXI,LN,K,TEMP,DFI,DELT,JSTEP,
2          * KTYPE,KOTI,XDIST)
3
4      C     SUR. FOR CALCULATING CONTOUR FRONT MOVEMENT DATA AND
5      C     READING AND WRITING THE SAME ON FILE
6
7      C     IMPLICIT DOUBLE PRECISION(A-H,O-Z)
8      DIMENSION XFRONT(1), YFRONT(1)
9      DATA IDOL,IBLNK,ISTAR/IHS,IM ,INH/
10     IF(KTYPE.NE.1) GO TO 100
11
12     C     READ FILE
13
14     DO 60 KK=1,JSTEP
15        READ (9,390) MARK
16        IF (MARK.NE.IDOL) GO TO 50
17        READ(9,430) TEMP,DFI,DELT
18        READ(9,390) MARK
19        50   READ (9,430) (DUM,L=1,6)
20        READ (9,430) (DUM,L=1,6)
21        READ(9,420) IMAXI,JMAXI,K,LM
22        CONTINUE
23        RETURN
24    800  CONTINUE
25        DO 260 LL=1,6
26        CONVAL=10.0*FLOAT(70-LL+1)
27        XF=CONDEP(I,MAXI,JMAXI,10,-JMAXI,0,0,CONVAL)
28        YF=CONDEP(I,MAXI,JMAXI,-2,0,0,0,CONVAL)
29        IF (XF.EQ.0.0) GO TO 260
30        XFRONT(LL)=(XF-FLOAT(K))*(XDIST/FLOAT(JMAXI-1))
31        CONTINUE
32        IF (YF.EQ.0.0) GO TO 260
33        YFRONT(LL)=(FLOAT(JMAXI)-YF)/FLOAT(JMAXI-1)
34        CONTINUE
35
36     C     STORE CONTOUR FRONT MOVEMENT DATA IF IFILF = 1
37
38     MARK=IDOL
39     IF (KOTI.GT.1) MARK=IBLNK
40     WRITE (9,390) MARK
41     IF (KOTI.GT.1) GO TO 270
42     WRITE(9,430) TEMP,DFI,DELT
43     MARK=IBLNK
44     WRITE(9,390) MARK
45     270  WRITE (9,430) (XFRONT(LL),LL=1,6)
46     WRITE (9,430) (YFRONT(LL),LL=1,6)
47     WRITE(9,420) IMAXI,JMAXI,K,LM
48     390  FORMAT (1HO.16)
49     400  FORMAT (1H .3F10.1)
50     420  FORMAT (1H .415)
51     430  FORMAT (1H .6(E14.9,2X))
52     RETURN
53     END

```

```

1 C *** PLOT PROGRAM FOR THE CONTOUR FRONT MOVEMENT ***
2
3 C READ IN FROM DATA DECK
4 C JSTEP= # OF TIME STEPS TO BE READ IN
5 C
6 C TEMP = SIMULATION TEMPERATURE
7 C 'DFI' = 1 AND 'DLT'
8 C 'DLT' = TIME STEP
9 C
10 DOUBLE PRECISION XFRONT(800,6),YFRONT(800,6)
11 DOUBLE PRECISION TEMP,DFI,DLT
12 DIMENSION TAU(800)
13 DIMENSION IX(3),IY(3),IA(6)
14 DATA IDOL,18LNK,14TAU,1HS,1H,1HO,
15 DATA IA/6HCONCEN,AHTRATIO,6HN,FRON,6HT MOVE,6HMNT P,6HLAT ;
16 DATA IX/6HIN X D,6HIRFCI,6HN /
17 DATA IY/6HIN Y D,6HIRFCI,6HN /
18 390 FORMAT(1HO,6F)
19 420 FORMAT(1H,6E14.9,2X)
20 430 FORMAT(1H,6E14.9,2X)
21 C *** READ DATA FROM DECK
22 READ 200, JSTEP
23 200 FORMAT(8I10)
24 TIME=0.
25 DO 1 KK=1,JSTEP
26 READ(8,390) MARK
27 IF(MARK.NE.IDOL) GO TO 5
28 READ(8,430) TEMP,DFI,DLT
29 READ(8,390) MARK
30 READ(8,430) (XFRONT(KK,LL),LL=1,6)
31 READ(8,430) (YFRONT(KK,LL),LL=1,6)
32 READ(8,420) IMAX1,JMAX1,LH
33 TIME=TIME+DLT
34 TAU(KK)=TIME
35 1 CONTINUE
36 DATA HGT,XMAX,YMAX/0.075,7.0,5.0/
37 C *** INITIATE THE PLOT
38 DO 80 N=1,2
39 CALL PLOTS(10.0,10.0)
40 CALL PLOT(1.5,1.5,-3)
41 C *** DRAW BORDER
42 CALL PLOT(0.0,YMAX,2,-1)
43 CALL PLOT(XMAX,YMAX,2,-1)
44 CALL PLOT(XMAX,0.0,2,-1)
45 CALL PLOT(0.0,0.0,2,-1)
46 C *** SCALE GRID
47 TTAU=TAU(JSTEP)+1HO.
48 IDIV=INT(TTAU)
49 IS=IDIV/25*25*25
50 TAUH=FLOAT(IS)/100.
51 C
52 YY1=XFRONT(1,6)
53 IF(N.EQ.2) YY1=YFRONT(1,6)
54 DO 2 1=2,JSTEP
55 YY2=XFRONT(1,6)
56 IF(N.EQ.2) YY2=YFRONT(1,6)
57 YYYY=AHMAX((YY1,YY2))
58 2 YY1=YYYY
59 YAP=YYYY*100.
60 IYD=INT(YAP)
61 IT=IYD/25*25*25
62 YDHAX=FLOAT(IT)/100.
63 C *** DRAW GRID
64 DX=XMAX/20.
65 DO 10 I=1,19
66 X=FLOAT(I)*DX
67 CALL PLOT(X,0,13)
68 CALL PLOT(X,YMAX,2,1)
69 10 CONTINUE
70 DY=YMAX/20.
71 DO 20 J=1,19
72 Y=FLOAT(J)*DY
73 CALL PLOT(0.0,Y,3)
74 CALL PLOT(XMAX,Y,2,1)
75 20 CONTINUE
76 C *** ERASE LABLE AREA
77 DO 30 I=3,14
78 XX=(I-1)*DX
79 CALL PLOT(XX,17.0,Y,3)

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80      30 CALL PLOT(XX,19.56DY,12)
81      DO 40 I=19,20
82          YY=(I-1)*DY
83          CALL PLOT(DX,YY,3)
84          40 CALL PLOT(14.*DX,YY,12)
85      C *** PUT SYMBOL
86          CALL SYMBOL(0.5,4.7,0.1313,1A,0.0,33)
87          IF(N.EQ.2) IX=LY
88          CALL SYMBOL(1.6,4.45,0.1313,IX,0.0,14)
89      C *** AXES NUMBERS
90          Y=-0.2
91          DO 50 I=-1,-1+2.00DX-125
92              XFLOAT(I)=I*2.00DX-125
93              VAL=XFLOAT(I)*TAUM/100
94          50 CALL NUMBER(X,Y,HGT,VAL,0.0,2)
95          X=0.5
96          DO 60 J=1,21
97              Y=XFLOAT(J-1)*DY-.663
98              VAL=XFLOAT(J-1)*YDMAX/200
99          60 CALL NUMBER(X,Y,HGT,VAL,0.0,2)
100             CALL SYMBOL(-.75,.5,.1313,'DISTANCE',90.,0)
101             CALL SYMBOL(2.1,-.5,.1313,'NORMALIZED TIME = TAU',0.,21)
102             DO 70 LL=1,6
103                 CALL PLOT(0.0,0.0,3)
104                 XMOVE=0.
105                 CALL PLOT(TAU,XMOVE,2,0)
106                 DO 70 ML=1,JSTEP
107                     TAUP=TAU(ML)*XMAX/TAUM
108                     XMOVE=XFRONT(ML,LL)*YMAX/YDMAX
109                     IF(N.EQ.2) YMOVE=YFRONT(ML,LL)*YMAX/YDMAX
110                     IF(TAU.GT.0.0.AND.YMOVE.EQ.0.0.AND.N.EQ.2) GO TO 70
111                     IF(N.EQ.2) XMOVE=YMOVE
112                     IF(XMOVE.LT.0.) XMOVE=0.0
113                     CALL PLOT(TAUP,XMOVE,2,0)
114
115             70 CONTINUE
116             CALL PLOT(0.,0.,999)
117             80 CONTINUE
118             STOP
119             END

```

```
11CRON05nS2(1).SHFILE
1      SUBROUTINE SHFILE(TIME,DELT,DELY,TEMP,THAX,R5,YJ1,YJUNC,A
2          * ,JMAXI,YDIST,X0,IAMANT)
3
4      C   SUB WRITES SETT RFISTANCE, JUNCTION DEPTH AND INTIGRATED
5      C   IMPURITY ON UNIT 11
6
7      IMPLICIT DOUBLE PRECISION(A-H,O-Z)
8      WRITE(13,200) JMAXI,IAMANT
9
10     200 FORMAT(1H0,8I10)
11     WRITE(13,100) TEMP,THAX,DELT,DELY,YDIST
12     WRITE(13,100) R5,YJ1,YJUNC,A,TIME,X0
13     100 FORMAT(1H0,6E15.9)
14     RETURN
15
16     END
```

```

MICRON=SOS2(),OUTPUT
1      SUBROUTINE OUTPUT(X,Y,IMAX1,JMAX1,K,L,M,JJ,TIME,YDIST,
2      *ID,ITIME,X0,PTIME,DTIME,IAMBNT)
3
4      C   TRANSIENT DATA PRINT OUT
5
6      IMPLICIT DOUBLE PRECISION(A-H,O-Z)
7      COMMON /CON/CB1(65:64)
8      DIMENSION X(1),Y(1),IN(15),X0(1)
9      IMAX=IMAX1-1
10     IMAX2=IMAX1+1
11     PRINT 106, 1D, ITIME
12     PRINT 100, LM, TIME, PTIME, DTIME, K, X(K), IMAX1, X(IMAX1)
13     PRINT 101, (N,N=2,IMAX1,2)
14     PRINT 102, (X(1),I=2,IMAX1,2)
15     PRINT 105
16     W1=YDIST-0.45*X0(5)
17     DO 2 J=JMAX1,1,-1
18     Q=YDIST-Y(J)
19     IF(IAMBNT.NE.3) Q=(JMAX1-J)*41./FLOAT(JMAX1-1))
20     2    PRINT 103, Q,(CB1(I,J),I=2,IMAX1,2)
21     PRINT 108, (X0(I),I=2,IMAX1,2)
22     IF(IAMBNT.NE.3) PB(1)=INT(109, W1
23     109 FORMAT(1H0,10X,10SI, FILM = 0.0, E10.5)
24     108 FORMAT(1H0,10X,10SI, OXIDE THICKNESS IN CM = 1H0,13X,11(1PF10.3))
25     PRINT 104, JJ
26     100 FORMAT(1H0,10X,12WTIME STEP = 1H,3X,7HTIME = ,F10.3,
27     *5X,'ELAPSED TIME IN SEC.:1,2X,1PREDEF = ,F10.3,2X,'DRIVE IN = ,
28     * F10.3//,
29     *10X,'OXIDE POSITION'/,
30     *10X,'X(1,12,1) = ,E6.2,2X,'X(1,12,1) = ,E6.2//)
31     101 FORMAT(1H0,3H1 = ,6X,12110)
32     102 FORMAT(1H0,3X,3HX = ,7X,12(1PF10.3))
33     103 FORMAT(1H,2X,'Y= ,1PF7.1,2X,11(1PE10.3))
34     104 FORMAT(1H0,10X,15A4,T98,'TIME',A6)
35     105 FORMAT(1H0)
36     106 FORMAT(1H1,10X,15A4,T98,'TIME',A6)
37     RETURN
38     END

```

PRT SOS2,PLOT=CONTOUR,,SUBION,,TRINAG,,ABC,,XYZ,,PLOT,,CONDEP,,MAIN

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11ICRON=5052(1),PLOT=CONTOUR
12      SUBROUTINE PLTCON(A,CONVAL,NC,IK,JK)
13
14      C   ISOCONCENTRATION PLOT SUBPROGRAM /
15
16      DIMENSION A(64,64),X(1000,3),Y(1000,3),NV(1000)
17      DIMENSION CS(2,3),CT(2,2,4),OT(2,4),OS(2,3)
18      DATA ZERO/1.0E-20/
19      DATA ((CS(I,J),J=1,3),I=1,2)/0.5,-1.0,0.5,-0.5,0.0,0.5/
20      DATA ((OT(I,J),J=1,4),I=1,2)/1.0,0.0,-1.0,0.0,-1.0,0.0,0.0,0.0/
21      DATA ((OS(I,J),J=1,3),I=1,2)/0.5,1.0,0.0,0.5,0.0,0.0,0.0,0.0/
22      DATA XMAX,YMAX/B.0,4.0/
23      NCMI=NC-1
24      C   CONTOUR=ALOG10(CONVAL)
25      C   * RESET PEN TO ORIGIN
26      C   * COMPUTE SCALING FACTORS
27      SCALX=XMAX*1.5/(JK*2)
28      SCALY=YMAX/(JK-1)
29      C   * START CONTOUR SEARCH
30      NT=0
31      IL=IK-1
32      JL=JK-1
33      10 DO 50 I=2,IL
34      DO 50 J=1,JL
35      C   * LOCATE SQUARE CROSSINGS
36      II=I-2
37      JJ=J-1
38      B(1)=0.25*( ALOG10(A(I,J))+ALOG10(A(I+1,J))+ALOG10(A(I,J+1))+
39      * ALOG10(A(I+1,J+1)))
40      R(1)=10.0*R(1)
41      R(4)=R(1)
42      C   * LOCATE TRIANGLES
43      20 DO 40 K=1,4
44      NP=1
45      GO TO 21
46      21 R(2)=A(I+1,J)
47      R(3)=A(I,J)
48      GO TO 30
49      22 R(2)=A(I,J)
50      R(3)=A(I,J+1)
51      GO TO 30
52      23 R(2)=A(I,J+1)
53      R(3)=A(I+1,J+1)
54      GO TO 30
55      24 R(2)=A(I+1,J+1)
56      R(3)=A(I+1,J)
57      GO TO 30
58      C   * LOCATE INTERSECTIONS
59      30 DO 35 M=1,3
60      IF (CONVAL.LT.AMIN(B(M),B(M+1)),OR,CONVAL.GT.AMAX(B(M),B(M+1)))
61      * GO TO 35
62      NP=NP+1
63      BB=ALOG10(B(M+1))-ALOG10(B(M))
64      IF (ABS(BB).GT.2F0) GO TO 33
65      GO TO 5
66      33 BB=(CONTUR-ALOG10(B(M)))/BB
67      CONTINUE
68      TX=OS(1,M)*CS(1,M)*D
69      TY=OS(2,M)*CS(2,M)*D
70      X(INT+1,NP)=OT(1,K)*CT(1,1,K)*TX+CT(1,2,K)*TY+II
71      Y(INT+1,NP)=OT(2,K)*CT(2,1,K)*TX+CT(2,2,K)*TY+JJ
72      35 CONTINUE
73      IF (NP.LE.1) GO TO 40
74      NT=NT+1
75      NV(NT)=NP
76      40 CONTINUE
77      50 CONTINUE
78      C   * SCALE POINTS
79      IF (NT.EQ.0) GO TO 80
80      DO 65 K=1,NT
81      NM=NV(K)
82      DO 65 L=1,NM
83      X(K,L)=X(K,L)*SCALX
84      Y(K,L)=Y(K,L)*SCALY
85      65 CONTINUE
86      C   * PLOT CONTOUR

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```
80      DO 71 K=1,NT
81      NH=NV(K)
82      CALL PLOT(X(K,1),Y(K,1),3)
83      IF (MOD(K,10).EQ.0) CALL SYMBOL(X(K,1),Y(K,1),0+1A,NCH1,n,0,-1)
84      DO 71 L=2,NH
85      CALL PLOT(X(K,L),Y(K,L),2)
86      IF (NH.EQ.3) CALL PLOT(X(K,1),Y(K,1),2)
87      C* 71 CONTINUE
88      * MOVE PEN TO ORIGIN
89      80 CALL PLOT(0.0,0.0,3)
90      RETURN
91      END
```

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1      SURROUNTIE ABC(IMAX1,,JMAX1,X,Y,LH,TIME,K,DFI,TEMP,TMAX,KOTI,XO,
2          * YDIST,IAMBNT)
3
4      {** SURROUNTIE WRITES TRANSIENT DATA ON DATA FILE ON UNIT 11 **}
5
6      C*** SURROUNTIE WRITES TRANSIENT DATA ON DATA FILE ON UNIT 11 ***

7      C*****
8      DOUBLE PRECISION CR1,X,Y,TIMI,TEMP,TMAX,DFI,XO,YDIST
9      COMMON /CON/CR1(4N,64)
10     DIMENSION X0(1)
11     DIMENSION Y(1),Y1(1)
12     DATA IDOL,IRLNK/1M$+1M /
13     KOTI=KOTI+1
14     MARK=IDOL
15     IF(KOTI.GT.1) MARK=IRLNK
16     WRITE(11,400) MARK
17     400 FORMAT(1M,1A6)
18     IF(KOTI.GT.1) GO TO 2
19     WRITE(11,100) DFI,TMAX,TEMP,YDIST
20     WRITE(11,200) K,JMAX1,JMAX1,IAMBNT
21     200 FORMAT(1M,1B110)
22     WRITE(11,100) (X(I),I=2,JMAX1)
23     WRITE(11,100) (Y(I),I=1,JMAX1)
24     MARK=IRLNK
25     WRITE(11,400) MARK
26     2 CONTINUE
27     WRITE(11,200) LH
28     WRITE(11,100) TIME
29     DO 1 J=JMAX1,1,-1
30     1 WRITE(11,100) (CR1(I,J),I=2,JMAX1)
31     WRITE(11,100) (X0(I),I=2,JMAX1)
32     100 FORMAT(1M,5E15.9)
33     PRINT 300,KOTI
34     300 FORMAT(1M,10X,9KOTI + ' ',10/1)
35     RETURN
36     END

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C16

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1      SUBROUTINE XYZ(IHMAX,IJMAX,X,Y,LH,TIME,K,DFI,TEMP,TMAX,KOTI,XD,
2      *      YDIST,IAHANT)
3      CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
4      C      SUBROUTINE READS THE TRANSIENT DATA FILE ON UNIT 11
5      C
6      DOUBLE PRECISION FBI,X,Y,TIME,TEMP,TMAX,KDFI,XD,YDIST
7      COMMON /CON/CRI(64,64)
8      DIMENSION XD(11)
9      DIMENSION X(11),Y(11)
10     DATA IDOL,ISBLNK/1M8,1M /
11     DD 3 KLMD/1,KOTI/
12     READ(11,100) MARK
13     IF(IMARK.NE.IDOL) GO TO 5
14     READ(11,100) DFI,TMAX,TEMP,YDIST
15     READ(11,200) K,IHMAX,IJMAX,IAHANT
16
17 100 FORMAT(IH,5E15.9)
18 200 FORMAT(IH,5E10)
19     READ(11,100) (X(I),I=2,IHMAX)
20     READ(11,100) (Y(I),I=1,IJMAX)
21     READ(11,100) MARK
22
23 5 CONTINUE
24     READ(11,200) LM
25     READ(11,100) TIME
26     DO 1 J=JMAX1,1,-1
27 1 READ(11,100) (CB(I,J),I=2,IHMAX)
28     READ(11,100) (XD(I),I=2,IHMAX)
29
30 3 CONTINUE
31 400 FORMAT(1HO,5E15.9)
32     C      APPLY PERIODIC B.C.
33     IMAX2=IMAX1+1
34     IMAX=IMAX1-1
35     DO 7 JB=1,IHMAX1
36 7 CB(I1,J)=CB(I3,J)
37     CB(I1,IMAX2,J)=CB(I1,IMAX,J)
38     RETURN
39     END

```



```

1      FUNCTION CONDEP(M,N,I,J,MIN,MAX,CONVAL)
2      C   • LOCATES CONCENTRATION CONTOURS ALONG EITHER
3      C   • A VERTICAL OR HORIZONTAL GRID LINE. EITHER
4      C   • LINEAR OR LOGRITHMIC INVERSE INTERPOLATION
5      C   • CAN BE USED.
6      C
7      C   • A      - ARRAY BEING CONTOURED (DIMENSIONED
8      C   • (M,N) IN CALLING PROGRAM
9      C
10     C   • I,J    - NON-ZERO VALUE SPECIFIES GRID LINE
11     C   • TO BE CONTOURED. POSITIVE VALUE FOR
12     C   • LINEAR INTERPOLATION, NEGATIVE FOR
13     C   • LOGRITHMIC INTERPOLATION. EITHER
14     C   • I OR J MUST BE ZERO.
15     C   • CONVAL- CONOUR VALUE
16     C
17     C   • MIN,  - MINIMUM AND MAXIMUM SUBSCRIPTS OF
18     C   • MAX   - GRID LINE TO BE CONTOURED. (MAY BE
19     C   • ZERO IF ENTIRE GRID LINE IS TO BE
20     C   • CONTOURED.)
21     C   • CONDEP- POSITION OF CONVAL ON GRID LINE. IF
22     C   • CONVAL IS OUT OF RANGF OF GRIN LINE
23     C   • VALUES CONDEP RETURNS A VALUE OF
24     C   • ZERO.
25     C
26     IMPLICIT DOUBLE PRECISION(A=H,0-Z)
27     COMMON /CON/A(64,64)
28     DO 100 I=1,M
29     DO 100 J=1,N
30     IF(A(I,J).LT.1.D-100) A(I,J)=1.D-100
31     ILOG=1
32     IF (I,NE.0) GO TO 10
33     INC=1
34     IMIN=MIN
35     IMAX=MAX-1
36     IF ( MIN.EQ.0) IMIN=1
37     IF ( MAX.EQ.0) IMAX=M-1
38     IF (J,LT.0) ILOG=-1
39     INC=0
40     JMIN=IABS(J)
41     JMAX=JMIN
42     GO TO 20
43
44     CONTINUE
45     INC=1
46     IMIN=MIN
47     IMAX=MAX-1
48     IF ( MIN.EQ.0) JMIN=1
49     IF ( MAX.EQ.0) JMAX=N-1
50     IF (I,LT.0) ILOG=-1
51     INC=0
52     IMIN=IABS(I)
53     IMAX=IMIN
54     CONDEP=0.0
55     DO 45 II=IMIN,IMAX
56     DO 40 JJ=JMIN,JMAX
57     IF (CONVAL,LT.AMIN(A(II,JJ),A(II+INC,JJ+JINC)))
58     1.DR,CONVAL.GT.,AMAK(A(II,JJ),A(II+INC,JJ+JINC)))
59     2 GO TO 40
60     IF (ILOG,LT.0) GO TO 30
61     CONDEP=((CONVAL-A(II,JJ))/(A(II+INC,JJ+JINC))-A(II,JJ))
62     1+FLOAT(II+INC+JJ+JINC)
63     RETURN
64
65     CONTINUE
66     CONLOG=ALOG10(CONVAL).
67     CONDEP=((CONLOG-DLOG10(A(II,JJ)))/(DLOG10(A(II+INC,JJ+JINC))-
68     DLOG10(A(II,JJ))))+FLOAT(II+INC+JJ+JINC)
69     RETURN
70
71     CONTINUE
72     RETURN
    END

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MICRON-Sn52(1).MAIN
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          PROCSIM II

          SOLUTION OF DIFFUSION PROBLEM FOR SILICON ON SAPPHIRE
          *** NORMALIZED SOLUTION ***

          DATA IS READ FROM DECK IN FOLLOWING SEQUENCE:

FIRST CARD:
LIST - # OF TIME STEPS TO BE SKIPPED WHILE PRINTING
IFILE - PUT 1 TO WRITE ON FILE AND ALSO TO LOCATE
        CONTOUR POSITION, CONTOUR FRONT MOVEMENT DATA IS
        WRITTEN ON UNIT 9 AND CONCENTRATION PROFILE IS
        WRITTEN ON UNIT 11.
LFILE - # OF TIME STEPS TO RE SKIPPED WHILE WRITING ON FILE
IPLOT - PUT 1 TO PLOT PROFILE IN PRINT OUT
IREAD - PUT 1 TO READ DATA FROM FILE
        - PUT 2 TO READ ION IMPLANT DATA AND TO
        DO REDISTRIBUTION.
JSTEP - # OF DATA STEPS TO BE READ FROM FILE IF IREAD = 1
IMAX1, JMAX1 - # OF GRID POINTS IN X AND Y DIRECTIONS
        RESPECTIVELY. CHECK DIMENSION BEFORE CHANGING
        FORMAT FIELD - 8110

SECOND CARD:
JSTP - PUT 0 IF CONST. SOURCE DIFF. IS DESIRED.
        - PUT 1 IF REDISTRIBUTION IS DESIRED.
        - PUT > 1 IF TWO-STEP DIFF. IS DESIRED.
ORINT - PUT 1 FOR 100 CRYSTAL ORIENTATION
        - PUT 2 FOR 110 CRYSTAL ORIENTATION
        - PUT 3 FOR 111 CRYSTAL ORIENTATION
AMRNT - PUT 1 FOR DRY OXYGEN
        - PUT 2 FOR STEAM
        - PUT 3 FOR NITROGEN
        FIELD 3110

THIRD CARD:
CSUR - SUBSTRATE DOPING/1.E15
CS - SURFACE CONCENTRATION/1.E18
TEMP - TEMPERATURE IN DEG. CENT.
TMAX - NORMALIZATION TIME IN SECOND
THIS HAS NO EFFECT IF LAMDA IS SPECIFIED AS DATA
XDIST, YDIST - WIDTH AND THICKNESS(IN MICRON) OF THE TWO
DIMENSIONAL REGION IN QUESTION
OXTHIC - WIDTH(IN MICRON) OF THE OXIDE IN THE REGION
DFLT - NORMALIZED TIME STEP
FORMAT FIELD - BF10.3

FORTH CARD:
IMTYPE - SPECIFY TYPE OF IMPURITY BY PUTTING N OR P
NO SPEC. IS NECESSARY IF IT IS BORON
IMPUTY - PUT BORON, ARSFNIC, PHOSPHOROUS OR ANY
        OTHER NAME.
EA - ACTIVATION ENERGY OF THE DIFFUSION
        IF BLANK AND BORON DIFF., DATA IS SUPPLIED INTERNALLY
DI - DIFFUSIVITY CONST. OF THE IMPURITY
        IF BLANK AND BORON DIFF., DATA IS SUPPLIED INTERNALLY
        FIELD A4.4A4.2F10.3

FIFTH CARD:
ID - IDENTIFICATION COMMENT TO BE PRINTED ON TOP OF
        PROFILE PRINT OUT
ITEST - PUT 0 TO READ LAMDA FROM DATA DECK
CSTOP - CONCENTRATION/1.E15 AT WHICH SIMULATION STOPS
        WHEN THE LEFT END CORNER OF SILICON AND SAPPHIRE
        INTERFACE REACHES THIS VALUE(DURING PREDEP)
        FORMAT FIELD - 15A4,15,F15.9

SIXTH CARD(IF ISTP>0):
ROTEMP - REDISTRIBUTION TEMPERATURE
ROTMAX - REDISTRIBUTION NORM. TIME
        REDISTRIBUTION FINAL TIME IS 1.
RDLDT - REDISTRIBUTION NORM. TIME STEP.
XOA - REDISTRIBUTION INITIAL OXIDE THICKNESS IN CM

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80      CEE WHERE SURF. CONC. WAS CS
81      CEE XOR = REDISTRIBUTION INITIAL OXIDE THICKNESS IN CM
82      CEE WHERE SURF. HAS THE THICK OXIDE
83      CEE CM = SEGREGATION COEFFICIENT, GENERATED INTERNALLY IF
84      CEE IMPURITY IS BORON AND NO VALUE IS GIVEN
85      CEE FIELD 6F10.3
86      CEE
87      CEE SEVENTH CARD(USE WHEN ITEST=0):
88      CEE LAMDA = LAMDA**2/1.E-3
89      CEE      FORMAT FFLD = F10.3
90      CEE
91      CEE EIGHTH CARD(USE IF [READ=2]):
92      CEE TON, IMPLANTATION DATA
93      CEE CMAX = MAX. CONCENTRATION
94      CEE RP = RANGE OF DISTRIBUTION, MEAN VALUE (IN MICRON )
95      CEE DRP = STRAGGLE, STANDARD DEVIATION. (IN MICRON )
96      CEE VOLT - IMPLANTATION ENERGY LEVEL IN KEV
97      CEE      FIELD 3E15.6,F10.5
98      CEE
99      CEE *****cccccccccccccccccccccccccccccccccccccccccccccccc
100     C
101     C IMPLICIT DOUBLE PRECISION (A-H,O-Z)
102     C INTEGER ORINT,AMBT
103     C DOUBLE PRECISION KB,NI,LAMDA
104     C COMMON /TRI/ A(64),B(64),D(64),E(64),V(64)
105     C COMMON /CON/ CB1(64:64)
106     C DIMENSION X(64), Y(64), CB1(64,64), CB2(64,64), G(64,64), ID(15)
107     C DIMENSION IMTYPE(1), IMPUTY(4), IBRON(4),
108     C DIMENSION XOLAST(44), X0(64), DRXIO(64), VP(64)
109     C DIMENSION IMAT(2), IORTN(1), IDOX(2), INIT(2), ISTHM(1)
110     C
111     C DEFINE COMPUTING FUNCTIONS
112     C
113     C RHS(Q,G1,G3,C10,C20)=C00+Q*(G1*C20+G3*C10)
114     C RATIO(C,CSUB,NI)=(C-CSUB)/(2.0*NI)
115     C ROOT(RATIO)=DSQRT((RATIO**2)+1.0)
116     C FURATIO(RATIO)=((RATIO+ROOT)**2)/ROOT
117     C CALL ERTRAN (9,DATE,ITIME)
118     C
119     C READ SIMULATION INITIAL DATA
120     C
121     C READ 360, LIST,IFILE,LFILE,IPILOT,IREAD,JSTEP,IMAX1,JMAX1
122     C READ 360, JSTP,ORINT,AMBT
123     C IF(IREAD.EQ.2) JSTP=1
124     C READ 370, CSUB,CS,TEMP,TMAX,XDIST,YDIST,DXTHIC,DELT
125     C READ 320, IMTYPE,IMPUTY,EA,DI
126     C READ 380, ID,ITEST,CSTOP
127     C IF (JSTP.GT.0) READ (5,370,ERR=310) RDTMP,RDTMAX,RDDLT,XOA,XAB,CM
128     C IF (ITEST.EQ.0) READ (5,370,ERR=310) LAMDA
129     C
130     C DEFINE DATA:
131     C
132     C KB = BOLTZMANN'S CONSTANT
133     C JLIM = # OF ALLOWABLE ITERATIONS
134     C DVLIM = ALLOWABLE ERROR IN CONVERGENCE
135     C TIMAX = NORMALIZED TIME AT WHICH SIMULATION STOPS
136     C EA8 AND DI8 - BORON DIFFUSIVITY DATA
137     C
138     C DATA EA8,DIR /3.59D0,3.17D0/
139     C DATA IBRON /4HBORO,4HN ,4H ,4H   /
140     C DATA NYP,IPT /1HN,1HP/
141     C DATA KB /8.616D-5/
142     C DATA JLIM,DVLIM /60,1.D-8/,TIMAX /1.00/
143     C DATA IDOX/6HDRY,OX,6HYGEN /
144     C DATA INIT/6HNITROG,6HEN /
145     C DATA ISTHM/6HSTEAM /
146     C
147     C IF (IMPUTY.EQ.1.AND.IRFAD.EQ.0) IER=1
148     C IF (IMPUTY.NE.1.AND.IRFAD.EQ.0) IER=1
149     C IF (IMPUTY.NE.1.AND.IBRON.AND.EA.EQ.0.00) IER=1
150     C IF (IMPUTY.NE.1.AND.IBRON.AND.DI.EQ.0.00) IER=1
151     C IF (IER.EQ.1) PRINT 460
152     C IF (IER.EQ.1) GO TO 310
153     C IF (IMTYPE.EQ.1) ITYPE=0
154     C IF (IMTYPE.EQ.NYP) ITYPE=1
155     C IF (IMTYPE.EQ.IBRON.AND.EA.EQ.0.00) EA=EA8
156     C IF (IMTYPE.EQ.IBRON.AND.DI.EQ.0.00) DI=DI8
157     C PRINT 410, ID
158     C PRINT 330, IMPUTY,IMTYPE
159

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160      NAMELIST /PUT/ LIST, IFILE, LFILE, IPLOT, IREAD, JSTEP, IMAX1, JMAX1, JSTP
161      , ORINT, AMBNT, CSUB, CS, TEMP, TMAX, XOLST, YDIST, OXTHIC, DELT, EA, DI, ITFST
162      , CSTOP, LAHDA, RDTMP, RANTMAX, RDCLT, XOA, XOB, CM, JLIM, DVLIM, TMAX
163      WRITE (6,PUT)
164
165      C C REFORMATION OF COMPUTING, GEOMETRIC AND PHYSICAL PARAMETERS
166
167      IF (JSTP.EQ.0.OR.JSTP.GT.1) ICOND=1
168      IF (AMBNT.EQ.1) AMRNT=1
169      IF (AMBNT.NE.3) XDIST=IDIST=1.D-4
170      IF (AMBNT.NE.3) YDIST=YDIST=1.D-4
171      IF (AMRNT.NE.3) OXTHIC=OXTHIC=1.D-4
172      JMAX=JMAX1-1
173      KOTI=0
174      IMAX=IMAX1-1
175      IMAX2=IMAX1+1
176      IF ((IMAX1.GT.3) GO TO 5
177      DELX=6.D0
178      IF (AMRNT.NE.3) DELX=6.D-4
179      GO TO 6
180      S DELX=XDIST/FLOAT(JMAX2-3)
181      DELY=YDIST/FLOAT(JMAX1)
182      CSUB=CSUB=1.DIS
183      CSTOP=CSTOP=1.D15
184      LAHDA=LADMA=1.D-3
185      CS=CS=1.D18
186      T=TEMP+273.
187      WINDO=(XDIST-OXTHIC)+1.D-5
188      GM=CM
189      CM=1.0
190      TMX=TMAX
191      IF (AMBNT.EQ.1) IMAT(1)=IDOX(1)
192      IF (AMBNT.EQ.1) IMAT(2)=IDOX(2)
193      IF (AMBNT.EQ.2) IMAT=ISTM
194      IF (AMRNT.EQ.3) IMAT(1)=INIT(1)
195      IF (AMRNT.EQ.3) IMAT(2)=INIT(2)
196      IF (ORINT.EQ.1) ORNT=100
197      IF (ORINT.EQ.2) ORNT=110
198      IF (ORINT.EQ.3) ORNT=111
199
200      C C CALCULATE DISTANCE X AND Y
201
202      DO 10 I=2,IMAX1
203      X(I)=(I-2)*DELX
204      10 IF (X(I).LE.WINDO) K=1
205      DO 20 J=1,JMAX1
206      20 Y(J)=(J-1)*DELY
207      DO 30 I=2,IMAX1
208      30 XOLAST(I)=XOA
209      DO 31 J=JMAX1,1,-1
210      31 YP(J)=(JMAX1-J)*(1./FLOAT(JMAX1))
211
212      C C SPECIFY PREDEP CONDITIONS
213
214      DO 40 I=1,IMAX2
215      DO 40 J=1,JMAX1
216          CR(I,J)=0.C
217          CR(I,J)=0.0
218          40 CB2(I,J)=0.0
219          DO 50 I=2,K
220              CR(I,JMAX1)=CS
221              CB1(I,JMAX1)=CS
222              CB2(I,JMAX1)=CS
223              TIME=0.0
224              LM=0
225
226      C C SPECIFY INITIAL PROFILE
227
228      IF (IREAD.EQ.2) CALL SUBION(IMAX1,JMAX1,K,Y,YDIST,CSTOP)
229      IF (IREAD.EQ.1) CALL XYZ (IMFI,JMFI,X,Y,LMTIME,KA,DFA,TMP,TIMX,JS
230      ISTEP,XOLAST,YDIST,AMBNT)
231      IF (IREAD.EQ.1) TIMAX=TIME+1.0
232      STIME=TIME
233      IF (JSTP.EQ.1) ICAND=2
234
235      C C READ CONTOUR FRONT MOVEMENT FROM DATA FILE IF IREAD = 1
236
237      IF (IREAD.EQ.1) CALL FRONT (IMI,JMI,LA,KC,TMP,DFB,DLT,LN,I,KOTI,Y
238      IDIST)
239      IF (IREAD.EQ.1) PRINT 430, LM, TIME, TMP, DFA, TIMX, IMFI, JMFI, KA

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240      IF (IREAD.EQ.1) PRINT 440, TMF, DFB, LA, IM1, JM1
241      IF (IREAD.NE.1) GO TO 60
242      IF (IMF1.NE.1MAX1.OR..IMF1.NE.JMAX1.OR.KA.NE.K) IER=1
243      IF (IFR.EQ.1) PRINT 450
244      IF (IFR.EQ.1) GO TO 310
245
246      C   START SIMULATION STEP
247
248      C   60 IF (ICOND.EQ.1) GO TO 70
249      KOTI=0
250      TEMP=RDTTEMP
251      T=TEMP+273.
252      DELT=RDTDELT
253      THAX=RDTMAX
254      IF(AMANT.NE.3) DELT=DELT+THAX
255      IF(AMANT.NE.3) THAX=THAX
256      TIME=0.
257      70 CONTINUE
258
259      C   CALCULATE NI
260
261      C   262 TIMAX=TIMAX-DELT
263      CALL PARAH (NI,T)
264      DF0=DEXP(-EA/(K*T))
265      IF (ITEST.NE.0) DF1=DF*THAX/((YDIST+1.D-4)**2)
266      IF(AMANT.NE.3) DF1=DF
267      IF (ITEST.EQ.0) DF1=LAMDA
268      IF (ICOND.EQ.1) PRINT 340
269      IF (ICOND.EQ.2) PRINT 350
270      PRINT 390, NI, DF
271      PRINT 420, IMPUTY, TEMP,DF1,THAX
272
273      C   P=(DF1*DELT)/(DELX**2)
274      Q=(DF1*DELT)/(DELY**2)
275
276      C   PRINT INITIAL PROFILE
277
278      C   279 CALL OUTPUT (X,Y,1MAX1,JMAX1,K,LH,JJ,TIME,YDIST,DD,TIME,XOLAST,
280      * PTIMF,DTIME,AMBNT)
281      IF (IREAD.EQ.2.AND.IFILE.EQ.1) CALL ABC (1MAX1,JMAX1,X,Y,LH,TIME,K
282      1,DF1,TEMP,THAX,KOTI,XOLAST,YDIST,AMBNT)
283      AM=1.0
284      CC=1.0
285      RR=1.0
286      IF (ICOND.NE.1) CALL OXDATA (AMANT,ORINT,T,BR,
287      1,CC,AM,KB)
288      IF (ICOND.EQ.2.AND.GM.FQ.D.) CM = BM
289      IF (ICOND.EQ.2.AND.GM.NE.D.) CM = GM
290      IF (ICOND.EQ.2) PRINT 421, IMBT, ORNT, BR, CC, CM
291
292      C   START TIME STEP LOOP
293
294      C   80 LH=LH+1
295
296      C   STORE N TH. RESULT FOR R.H.S., WILL NOT BE CHANGED DURING ITER.
297
298      C   299 TIME=TIME+DELT
300      IF (ICOND.EQ.1) STIME=TIME
301      PTIME=TMX+STIME
302      DTIME=RDTMAX*(TIME-STIME)
303      IF (AMANT.NE.3) DTIME=TIME
304      DO 90 I=1,1MAX2
305      DO 90 J=1,JMAX1
306      CR2(I,J)=CR1(I,J)
307      IF (ICOND.EQ.1) GO TO 110
308
309      C   CALCULATE OXIDE THICKNESS
310
311      IF (AMANT.NE.3) GO TO 95
312      DO 94 I=2,1MAX1
313      94     X0(I)=XOLAST(I)
314      GO TO 110
315      95     PS=RR*DELT
316      QS=RR/CC
317      DO 100 I=2,1MAX1
318      X0(I)=XOLAST(I)+PS/2.*XOLAST(I)+QS)
319      100    DRRX0(I)=(X0(I)-XOLAST(I))/DELT
            X0(I)=X0(2)

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320      IF((YDIST-0.45*X0(1)),LT,0.1D-4) GO TO 310
321      CONTINUE
322      DELY=(1./FLOAT(JMAX))+(YDIST-0.45*X0LAST(2))
323      IF(AMBNT.NE.3) P=DF1*DELT)/(DELY*2)
324      JJ=0
325      JH=0
326
327      START ITERATION LOOP
328
329      120  JJ=JJ+1
330      IF (JJ.GT.JLIM) PRINT 400, CTER
331      IF (JJ.GT.JLIM) GO TO 290
332
333      TRANSFER SOLN. VECTOR FROM LAST ITERA. FOR CAL. OF G
334
335      DO 130 I=1,IMAX2
336      DO 130 J=1,JMAX1
337      130  CR(I,J)=CR1(I,J)
338
339      CAL.G
340
341      DO 140 I=1,IMAX2
342      DO 140 J=1,JMAX1
343      RA=RATIO(CR(I,J),rSUB,NII)
344      RO=ROOT(RA)
345      140  G(I,J)=FU(RA,RO)
346
347      SOLVE SYSTEM IN Y DIRECTION
348
349      DO 220 I=2,IMAX1
350
351      CALCULATE THE COEFF. IN Y DIRECTION
352
353      SR=0.
354      DO 150 J=2,JMAX
355      G1=(G(I,J)+G(I+1,J))/2.0
356      G2=(G(I,J)+G(I,J+1))/2.0
357      G3=(G(I,J)+G(I-1,J))/2.0
358      G4=(G(I,J)+G(I+1,J-1))/2.0
359      IF(AMBNT.EQ.3) GO TO 151
360      SR=0.45*DRRX0(I)*(YP(J)-1.0)*DELT/DELY
361      151  CONTINUE
362      A(J)=P*G4
363      A(J)=1.+Q*(G1+G3)+P*(G2+G4)+SR
364      D(J)=P*G2-SR
365      150  E(J)=RHS(Q,G1,G3,rB(I-1,J),rB(I,J),rB(I+1,J))
366
367      PUT BOUNDARY CONDITION ON Y AXIS
368
369      R(2)=A(2)+B(2)
370      A(2)=0.0
371      IF (ICOND.NE.1) GO TO 170
372      IF (I.GT.K) GO TO 140
373      E(JMAX)=E(JMAX)+D(JMAX)*CS
374      D(JMAX)=0.0
375      GO TO 180
376
377      160  CONTINUE
378      B(JMAX)=B(JMAX)+D(JMAX)
379      D(JMAX)=0.0
380      GO TO 180
381
382      170  IF (AMBNT.EQ.3) DRRX0(I)=0.
383      HA=-DELY*(1./CM-0.45)*DRRX0(I)
384      HR=2.*DF1
385      HK1=HA/(HR+G(I,IMAX1))
386      HK2=HA/(HB+G(I,JMAX1))
387      B(JMAX)=B(JMAX)+(1.+HK2)/(1.+HK1))*D(IMAX)
388      D(JMAX)=0.
389      180  CONTINUE
390
391      CALL TRIDAG (2,IMAX)
392
393      CONVERT MATRIX SOLUTION
394
395      DO 190 J=2,JMAX
396      CR1(I,J)=V(J)
397      190 CONTINUE
398
399      PUT BOUNDARY VALUES IN Y
            CR1(I,1)=CR1(I,2)

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400      IF ((ICOND.NE.1) GO TO 210
401      IF ((I.GT.K) GO TO 200
402      CRI(I,JMAX1)=CS
403      GO TO 220
404      200  CB1(I,JMAX1)=CRI(I,JMAX1)
405      GO TO 220
406      210  CONTINUE
407      CB1(I,JMAX1)=((I+HK2)/(I+HK1))*CB1(I,JMAX1)
408      IF(CRI(I,JMAX1).LT.1.0-300) CRI(I,JMAX1)=1.0-300
409      220  CONTINUE
410
411      C   PUT BOUNDARY VALUES IN AXIS X(PERIODIC BOUNDARY)
412
413      DO 230 J=1,JMAX1
414      CRI(1,J)=CB1(3,J)
415      230  CB1(IMAX2,J)=CRI(IMAX,J)
416
417      C   CHECK FOR CONVERGENCE
418
419      IF ((JJ.EQ.1) GO TO 120
420      ICK=0
421      DO 240 I=1,IMAX1
422          DO 240 J=1,JMAX1
423              IF ((CB1(I,J).LE.0.0) GO TO 240
424              CTEST=DABS((CRI(I,J)-CR(I,J))/CB1(I,J))
425              IF (CTEST.LE.OVLIM) GO TO 240
426              CTER=OMAX1*(CTEST,CTER)
427              ICK=1
428          CONTINUE
429          IF ((ICK.NE.0) GO TO 120
430          JM=JM+1
431          DO 241 I=1,IMAX1
432              DO 241 J=1,JMAX1
433              241 IF(CRI(I,J).LT.0.0)    CB1(I,J)=CB1(I,J)
434              IF(JM.EQ.1) GO TO 120
435
436      C   PRINT RESULTS
437
438      ISLM/LISTOLIST=LM
439      IF ((IS.EQ.0) GO TO 250
440      IF ((TIME.GE.TIMAX.AND.CS.NE.0.0) GO TO 250
441      IF(CRI(2,1).GE.CSTOP.AND.ICOND.EQ.1) GO TO 260
442      IF(CB1(2,1).GE.CSTOP.AND.CS.EQ.0.0.AND.JSTP.EQ.1) GO TO 250
443      GO TO 260
444      250  CALL OUTPUT (X,Y,IMAX1,JMAX1,K,LM,JJ,TIME,YDIST,IN,ITIME,XO,
445          * PTIME,DTIME,AMBN)
446      CALL SHREJN (CSUR,YDIST,JMAX1,Y,TIME,DELT,DELY,TEMP,THMX,IFILE,ITY
447      IPE,AMANT,XO(2))
448      IF ((IPLOT.NE.1) GO TO 260
449      CALL PLOT (CS,IMAX1,JMAX1,K)
450
451      C   STORE TRANSIENT DATA
452
453      260 IF ((FILE.EQ.0) GO TO 270
454      IT=LM/LFILE*FILE-LM
455      IF(IT.EQ.0) GO TO 265
456      IF(TIME.GE.TIMAX) GO TO 265
457      IF(CB1(2,1).GE.CSTOP.AND.ICOND.EQ.1) GO TO 265
458      GO TO 266
459      265 CALL ABC(IMAX1,JMAX1,XO,Y,LM,TIME,
460          * IK,DFI,TEMP,THMX,KATI,XO,YDIST,AMANTI)
461
462      C   LOCATE CONTOUR POSITION AND STORE DATA
463
464      266 CONTINUE
465      CALL FRONT (IMAX1,JMAX1,LM,K,TEMP,DFI,DELT,JSTEP,O,KOTI,XDIST)
466      270 CONTINUE
467
468      C   GO TO NEXT TIME STEP
469
470      IF ((CRI(2,1).GE.CSTOP.AND.ICOND.FQ.1) GO TO 290
471      IF ((TIME.GE.TIMAX) GO TO 290
472      X0(1)=X0(2)
473      280  DO 280 I=2,IMAX1
474          DO 280 I=2,IMAX1
475          X0(LAST(I))=X0(I)
476      280  GO TO 280
477      290  IF ((JSTP.GT.1.AND.ICOND.EQ.1) GO TO 300
478          GO TO 310
479      300  TIMAX=TIME+1.

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480      IF(AMRNT.NE.3) TMAX=TIME+RDTHM
481      ICOND=2
482      GO TO 60
483      310 IF(ILM.EQ.0) PRINT 450
484      STOP
485
486      C
487      320 FORMAT (1H0,4A4,2F10,3)
488      330 FORMAT (1H0,20X,1,IMPURITY = 1,4A4,2X,1,IMPURITY TYPE = 1,A4)
489      340 FORMAT (1H0,20X,1,000 PREDEPOSITION CYCLE 000)
490      350 FORMAT (1H0,20X,1,000 REDISTRIBUTION CYCLE 000)
491      360 FORMAT (B110)
492      370 FORMAT (8E10.5)
493      380 FORMAT (15A4,15,F15.9)
494      390 FORMAT (//,1H0,10X,1,NT = 1D10.3,5X,1,DFI = 1D10.3//)
495      400 FORMAT (//,1H0,10X,1,ITERATION DID NOT CONVERGE ERROR = 1D10.3)
496      410 FORMAT (1H,10X,1,000 SOLUTION OF DIFFUSION PROBLEM FOR SILICON
497      1 ON SAPPHIRE 000//1H0,31X,1,NORMALIZED SOLUTION//1H ,10X,15A4//1
498      2H0,10X,1,FOLLOWINGS ARE THE DATA VALUE)
499      420 FORMAT (1H,1H0,10X,1,NT - INTRINSIC CARRIER CONC.//1H ,10X,1,DFI =
500      1 ,1H0,10X,1,INTRINSIC DIFFUSIVITY OF ,1X,4A4,2X,1,AT ,2X,1,10.3,2X,1,DEG. CEMT.
501      2 //,1H ,10X,1,LAHDA**2 = DF1*THMAX/(YMAX*1.E-4**2)//,1H ,10X,
502      3 ,LAHDA = 1D10.3,6X,1,FOR NORMALIZATION TIME = 1E12.6,2X,1,SEC. 1
503      421 FORMAT (1H,1H0,10X,1,AMRNT = 1,2A6/1H0,5X,1,CRYSTAL ORIENTATION = 1
504      0A4//1H0,5X,1,OXIDATION PARAMETERS//,5X,2X,1,B = 1
505      *E10.3,2X,1,C = 1,1F10.3,
506      *1H0,5X,1,SEGREGATION COEFF. = 1,E10.3)
507      430 FORMAT (1H0,10X,1,000 INITIAL PROFILE AT TIME STEP = 1,15,2X,1,TIME
508      1 = 1D10.3,2X,1,HAS BEEN READ IN FROM DATA-FILE 11 000//1H0,15X,1,F01
509      2 FOLLOWING DATA ARE PROVIDED//1H ,15X,1,TEMP = 1,1D10.3,2X,1,LAHDA**2 =
510      3 1,1D10.3,2X/1H ,15X,1,NORM. TIME = 1,1D10.3,2X,1,IMAX1 = 1,110,2X,1,JH
511      4,AX1 = 1,110,2X,1,OXIDE GRID = 1,16)
512      440 FORMAT (1H0,10X,1,000 FOLLOWING DATA ARE OBTAINED FROM THE DATA
513      1 FILE 9 000//1H ,10X,1,TEMP = 1,1F10.3/1H ,10X,1,LAHDA**2 = 1,D10.
514      23/1H ,10X,1,TIME STEP = 1,110/1H ,10X,1,IMAX1 = 1,15/1H ,10X,1,JMAX1
515      3 = 1,15)
516      450 FORMAT (1H0,10X,1,000DATA INPUT ERROR 000//1H0,8X,1,RUNSTREAM TERMIN
517      1ATED)
518      C
519      END

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SPRT 5052.SHREJN1.MAIN-PLOT

```

MICRON=S052(1),SHRFJN
      SUBROUTINE SHRFJN(CSUR,YDIST,JMAXI,X,TIME,DELT,DELY,
1          * TEMP,TMAX,IFILE,ITYPE,IAMBNT,X0)
2      {***** SURROUNTS FOR CALCULATING SHEET RESISTANCE AND JUNCTION
3      * IMPLICIT DOUBLE PRECISION(A=H,D=2)
4      COMMON /CDN/C(64,A4)
5      DIMENSION CNET(64),CR1(64),X(1),Y(64)
6      DELBYDIST/FLOAT(JMAXI-1)
7      TF(IAMBNT,NE=3) DEL=DFL/YDIST
8
9      YWJ=0.0
10     YWJI=0.0
11     DO 6 I=1,JMAXI
12        IJ=JMAXI-I+1
13        Y(I)=YDIST-X(IJ)
14        IF(IAMBNT,NE=3) Y(I)=(I-1)*(1./FLOAT(JMAXI-1))
15        JN1=I
16        ICK=0
17        DO 5 J=JMAXI,1,-1
18          I=JMAXI+I-J
19          CR1(I)=C(2,J)
20          IF(CR1(I).LT.CSUR,AND,ICK.EQ.0) JN1=I
21          IF(CB1(I).GT.CSUB) ICK=1
22          IF(CB1(I).GT.CSUR) JN1=I
23          S CNET(I)=CB1(I)-CSUB
24          IF(JN1.EQ.1.OR.JN.EQ.(JMAXI-1).OR.JN.EQ.JMAXI) GO TO 7
25          YWJ=(YDIST/(JMAXI-1))+(CB1(JN)-CSUB)/(CB1(JN)-CB1(JN+1))
26          IF(IAMBNT,NE=3) YWJ=YWJ/YDIST
27          YWJI=DEL*(CSUB-CR1(JN))/((CB1(JN+1)-CB1(JN)))
28
29        K=0
30        SIGMA=0.000
31        0=0.00
32
33        C C START INTEGRATION
34
35        1 K=K+1
36        IF(K.GE.JMAXI) GO TO 2
37        Q=0*(CB1(K+1)+CB1(K))/DEL/2.0
38        IF(K.LE.JN1,OR,K.GE.JN) GO TO 1
39        SIG1=G(DABS(CNET(K)),ITYPE)
40        SIG2=G(DABS(CNET(K+1)),ITYPE)
41        SIGMA=SIGMA+(Y(K+1)-Y(K))*(SIG2+SIG1)/2.000
42        GO TO 1
43
44        2 CONTINUE
45        IF(JN.EQ.JMAXI) YWJ=0.0
46        IF(JN1.EQ.1,AND,CR1(JN1).GT.CSUR) YWJI=0.0
47        SIGA=G(DABS(CNET(.IN+1)),ITYPE)
48        SIGB=G(DABS(CNET(.IN+1)),ITYPE)
49        SIGC=G(DABS(CNET(.IN+1)),ITYPE)
50        YJUNC=Y(JN)+YWJ
51        SIGIN=G(DABS(CNET(JN)),ITYPE)
52        SIGWJ=0.5*(YWJ*(SIGIN+SIGA)+(DEL-YWJI)*(SIGB+SIGC))
53        YWJI=Y(JN)+YWJ
54        SIGMA=SIGMA+SIGWJ
55        RS=1.00/SIGMA
56        WRITE(6,203) YWJ,YJUNC,RS
57        203 FORMAT(1F5.1,'JUNCTION IS AT ',ZD15.9,' CM',5X,/,
58        * 5X,'SHEET RESISTANCE = ',D15.9,3X,
59        * /3X,'INTEGRATED IMPURITY= ',D15.9)
60        WRITE(6,201) JN1,JN
61        201 FORMAT(1O',5X,'JN= ',2I5/)
62        AFAC=1.0
63        IF(IAMBNT,NF=3) AFAC=(YDIST-0.45*X0)/1.0*4
64        YJUNC=YJUNC*AFAC
65        RS=RS/(AFAC*1.0*4)
66        Q=0*AFAC*1.0*4
67        IF(IFILE,FQ=1) CALL SWFILE(TIME,DELT,DELY,TEMP,
68        * TMAX,RS,YWJ,YJUNC,0,JMAXI,YDIST,X0,IAMBNT)
69        RETURN
70        END

```

```

MICRON-SNS2(1).MAIN= PLOT
1      C   * ISOCONCENTRATION PLOT PROGRAM *
2
3      C   READ IN FROM DATA DECK
4      C   FIRST CARD: LL = # OF TIME STEPS TO BE
5      C   READ IN FROM DATA FILE, FIELD 13;
6      C   SECOND CARD: IIT = TIME STEPS TO BE SKIPPED WHILE
7      C   PLOTTING PROFILE. DEFAULT PLOT AT
8      C   TIME STEPS 1 AND AT LL, FIELD 13.
9
10     DIMENSION CB(64,64),XC(64),YC(64),XO(64)
11     DATA XMAX,YMAX/8.0,4.0/0X/3.6/
12     DATA IDOL,IBLNK/IHS,IW /
13     DATA MGT/0.0875/
14     READ(5,3) LL
15     READ(5,3) IIT
16     3  FORMAT(1I3)
17     C* READ DATA FILE II
18     DO 100 LM=LL
19     READ(7,4) MARK
20     4  FORMAT(1H0,A6)
21     IF(MARK.NE.IDOL) GO TO 5
22     READ(7,1) DF1,TMAX,TEMP,YDIST
23     READ(7,2) K,IMAX1,JMAX1,IAMBNT
24     IK=TMAX1
25     JK=JMAX1
26     1  FORMAT(1H ,SE15.9)
27     2  FORMAT(1H ,B110)
28     READ(7,1) (XC(I),I=2,IK)
29     READ(7,1) (YC(I),I=1,JK)
30     READ(7,4) MARK
31     S  CONTINUE
32     READ(7,2) LM
33     READ(7,1) TIME
34     DO 99 J=JK,1,-1
35     READ(7,1) (CB(I,J),I=2,IK)
36     DO 60 I=2,IK
37     60  IF(ICR(I,J).LE.1.E-30) CB(I,J)=1.E-30
38     99  CONTINUE
39     READ(7,1) (XO(I),I=2,IK)
40     IS=L/1.E0+1 IT=L
41     IF((IS.EQ.0)) GO TO 11
42     IF((L.EQ.1.OR.L.EQ.LL)) GO TO 11
43     GO TO 100
44     11  CONTINUE
45     C* INITIALIZE PLOT.
46     CALL PLOTS(10.0,10.0)
47     C* RESET PEN TO ORIGIN
48     CALL PLOT(1.0,2.0,-3)
49     C* DRAW BORDER
50     CALL PLOT(0.0,YMAX+2,-1)
51     CALL PLOT(XMAX,YMAX+2,-1)
52     CALL PLOT(XMAX,0.0+2,-1)
53     CALL PLOT(0.0,0.0+2,-1)
54     C* DRAW OXIDE MASK
55     XP=(XC(IK)-2)
56     IF((IAMBNT.NE.3)) XP=(XC(IK)-2.E-4)/1.E-4
57     OX=(R./XP)*XC(IK)
58     CALL PLOT(OX,YMAX+3)
59     CALL PLOT(OX,YMAX+0.2,-1)
60     CALL PLOT(XMAX,YMAX+0.2,-1)
61     CALL PLOT(XMAX,YMAX+2,-1)
62     X=XMAX
63     PAT=8.-OX
64     INC=INT(PAT/0.2)
65     DO 10 I=1,INC
66     X=X-0.2
67     CALL PLOT(X,YMAX+0.2,-1)
68     CALL PLOT(X,YMAX,3)
69     10  CONTINUE
70     C* HORIZONTAL GRID LINES
71     DO 20 I=1,9
72     Y=C.4*FLOAT(I)
73     LNWT=+3
74     IF((I.EQ.5)) LNWT=+1
75     CALL PLOT(C.0,Y,3)
76     CALL PLOT(XMAX,Y,2,LNWT)
77     20  CONTINUE
78     C* VERTICAL GRID LINES
79

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80      DO 30 I=1,19
81      XBD,4*FLOAT(I)
82      LNWT=3
83      IF (MOD(I,6),E0.0) LNWT=1
84      CALL PLOT(X,0.0,3)
85      CALL PLOT(X,YMAX,2,LNWT)
86
87      C* 30 CONTINUE
88      * HORIZONTAL AXIS NUMBERS
89      DEX=XP/20.
90      IEX=21
91      IEP=1
92      IF(DEX<LT,0.1) IEP=11
93      IF(DEX>LT,0.1) IEP=2
94      IF(DEX>LT,0.01) DEX=XP/10.
95      IF((IAMBNT,E0.3) GO TO 31
96      IGP=1
97      DEX=XP/20.
98      IEX=21
99
100     31 CONTINUE
101     DO 40 I=1,18
102     VAL=DEX*FLOAT(I-1)
103     XBD,4*FLOAT(I-1)-(.5*HGT+0.04
104     YB=0.2
105     CALL NUMBERIX,Y,HGT,VAL,0.0,16)
106
107     C* 40 CONTINUE
108     * VERTICAL AXIS NUMBERS
109     IF((IAMBNT,NE,3) YAK=YC(JK)/1.E-4
110     DEY=YAK/10.
111     DO 50 I=1,11
112     VAL=DEY*FLOAT(I-1)
113     XB=-3.0*HGT+0.1
114     YMAX=0.4*FLOAT(I-1)-0.5*HGT
115     CALL NUMBERIX,Y,HGT,VAL,0.0,1)
116
117     50 CONTINUE
118     CALL SYMBOL(4,2,5,7,0,1,'- 1.0E2n',0.0,8)
119     CALL SYMBOL(4,2,5,5,0,1,'- 1.0E19',0.0,8)
120     CALL SYMBOL(4,2,5,3,0,1,'- 1.0E18',0.0,8)
121     CALL SYMBOL(4,2,5,1,0,1,'- 1.0E17',0.0,8)
122     CALL SYMBOL(4,2,4,9,0,1,'- 1.0E16',0.0,8)
123     CALL SYMBOL(4,2,4,7,0,1,'- 1.0E15',0.0,8)
124     CALL SYMBOL(4,0,5,7,0,1,'0.0',0,-1)
125     CALL SYMBOL(4,0,5,5,0,1,'1.0',0,-1)
126     CALL SYMBOL(4,0,5,3,0,1,'2.0',0,-1)
127     CALL SYMBOL(4,0,5,1,0,1,'3.0',0,-1)          * 1.0,0,14)
128     CALL SYMBOL(4,0,4,9,0,1,'4.0',0,-1)
129     CALL SYMBOL(4,0,4,7,0,1,'5.0',0,-1)
130     CALL SYMBOL(0,0,5,4,0,2,'2.41',0,-1)          * 1.0,0,14)
131     CALL SYMBOL(999,5,5,1,'2',0,-1)
132     CALL NUMBER(2,6,5,4,0,2,DP1,0,-4)
133     CALL SYMBOL(0,0,5,1,0,2,'TEMPERATURE = ',0.0,14)
134     CALL NUMBER(2,6,5,1,0,2,TEMP,0.0,0)
135     CALL SYMBOL(0,0,4,8,0,2,'TIME STEP = ',0.0,14)
136     TLM=LM
137     CALL NUMBER(2,6,4,8,0,2,TLM,0.0,-1)          * 1.0,0,14)
138     CALL SYMBOL(0,0,4,5,0,2,'TIME'           = 1.0,0,14)
139     CALL NUMBER(2,6,4,5,0,2,TIME,0.0,2)
140     DO 200 II=1,6
141     CONVAL=10.0*FLOAT(20+II+1)
142     CALL PLTCONICB,CONVAL,II,IK,JK)
143     CONTINUE
144     CALL PLOT(0.0,0.0,n,999)
145     CONTINUE
146     STOP
147     END

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